

DSP/BIOS Power Management for OMAP3430

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ABSTRACT

This document provides a summary of the configuration and application programming interfaces (APIs) for the C64x+ version of the DSP/BIOS Power Manager (PWRM module) included in the DSP/BIOS 5.31 product release. The OMAP3430 device is the only C64x+ device with PWRM support in this DSP/BIOS release.

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1 Overview

This document summarizes the configuration and application programming interfaces (APIs) for the C64x+ version of the DSP/BIOS Power Manager (PWRM module) included in the DSP/BIOS 5.31 product release. The OMAP3430 device is the only C64x+ device with PWRM support in this DSP/BIOS release.

The DSP/BIOS PWRM module provides ways to use the following power-related features within an OMAP3430 application:

- **CPU load monitoring.** Your application can gather information about the percentage of time the CPU has been idle recently, and can take action to conserve power based on the results.
- **Dynamic resource tracking.** You can make runtime PWRM API calls to inform the Power Manager of the specific resources (for example, clock domains, peripherals, and clock pins) that your application is dependent upon. With this knowledge of required resources, PWRM can idle resources that have no declared dependencies.
- **Retention state.** You can put the DSP a low-power state where all memory and logic contents are retained.
- **Hibernation state.** You can completely power off the DSP, with context saved before going off, and restored upon power on.
- **Voltage and frequency scaling.** On the OMAP3430, dynamic changes to the operating voltage and frequency of the CPU are possible using ARM-side code. This is called V/F scaling. Since power usage is linearly proportional to the frequency and quadratically proportional to the voltage, using V/F scaling can result in significant power savings.

On the OMAP3430 platform, setpoint changes occur only via ARM-side control code. These changes may occur either because DSP Bridge has requested a change to the setpoint or because an independent (ARM-side) decision has been made to change the setpoint. Whether the change request is made by DSP Bridge or by ARM-side code, the PWRM module does not control the actual V/F scaling. Instead, its role is to send out scaling event notifications to any DSP-side code that has registered with PWRM for scaling notifications.

More specifically, when a setpoint is about to change, DSP Bridge calls `PWRM_signalEvent` to signal the `PWRM_PENDINGSETPOINTCHANGE` event to any PWRM clients registered for this event. When notifications have completed, DSP Bridge acknowledges this to the ARM-side control code so that scaling can proceed. Following the setpoint change, DSP Bridge calls `PWRM_signalEvent` to signal the `PWRM_DONESETPOINTCHANGE` event to any registered clients. As part of these notifications, PWRM's internal setpoint variable is updated and `GBL_setFrequency` is called to update the CPU frequency known to DSP/BIOS.

2 Configuration

2.1 Configuration Properties

The following list shows the properties that can be configured in a Tconf script, along with their types and default values. For details, see the PWRM Manager Properties section.

Module Configuration Parameters

Name	Type	Default (Enum Options)
ENABLE	Bool	false
IDLECPU	Bool	false
IDLEFXN	Extern	prog.extern("_PWRM_F_idleStopClk")
LOADENABLE	Bool	false
NUMSLOTS	Numeric	1
USECLKPRD	Bool	false
CLKTICKSPERSLOT	Numeric	10
SLOTHOOKFXN	Extern	prog.extern("FXN_F_nop")
RESOURCETRACKING	Bool	false
USERRESOURCES	Numeric	0
SHAREDRESOURCEFXN	Extern	prog.extern("FXN_F_nop")
SCALING	Bool	false
WARMBOOTMEMSEG	Reference	prog.get("IRAM")
CTXBUFMEMSEG	Reference	prog.get("IRAM")
SCM_BASEADDR	Address	0x48002000
CM_BASEADDR	Address	0x48004000
PRM_BASEADDR	Address	0x48306000
IVAMMU_BASEADDR	Address	0x5D000000
USETIMER	Bool	false
TIMERID	Enumerated String	"Timer 6"
TIMERBASEADDR	Address	0
TIMERINPUTCLK	Unsigned	32
TIMERPERIOD	Numeric	10
TIMERINTR	Reference	HWI_UNUSED

Number of history slots to buffer. This property allows you to specify the number of “slots” or intervals of CPU load history to be buffered within PWRM. The “Enable CPU Load Monitoring” box must be checked for this property to be writeable.

Tconf Name: NUMSLOTS Type: Numeric

Example: `bios.PWRM.NUMSLOTS = 5;`

Use CLK and PRD for finalizing slots. Check this box if you want to use the DSP/BIOS CLK and PRD modules to determine when a history slot should be finalized (completed). Currently this the only supported method for finalizing slots, and you should always check this box if you want to use PWRM’s CPU load monitoring feature. The “Enable CPU Load Monitoring” box must be checked for this box to be writeable.

Tconf Name: USECLKPRD Type: Bool

Example: `bios.PWRM.USECLKPRD = true;`

Number of CLK ticks per slot. This property allows you to specify the duration of CPU load history slots, in terms of CLK clock ticks. For example, if the CLK module is configured for 1 tick per millisecond, then a value of 10 for this property means CPU history slot has a duration of 10 milliseconds. The “Use CLK and PRD for finalizing slots” box must be checked for this box to be writeable.

Tconf Name: CLKTICKSPERSLOT Type: Numeric

Example: `bios.PWRM.CLKTICKSPERSLOT = 10;`

Hook function to call upon slot finalization. This property allows you to configure a function to be called upon the finalization of each history slot. This function will be called as the last step of finalization, after the slot data has been written to PWRM’s internal history buffer. The “Use CLK and PRD for finalizing slots” box must be checked for this property to be writeable.

The callout function signature is:

```
Void slotHookFxn(Uns arg0)
```

When this function is called, `arg0` indicates the slot finalization timestamp.

Tconf Name: SLOTHOOKFXN Type: Extern

Example: `bios.PWRM.SLOTHOOKFXN = prog.extern("myHookFunction");`

Enable Resource Tracking. Check this box if you want to enable PWRM support for dynamic resource tracking.

Tconf Name: RESOURCETRACKING Type: Bool

Example: `bios.PWRM.RESOURCETRACKING = true;`

Number of user-defined resources to support. This property allows you to define additional resources (beyond those device-specific resources supported by default), that can be tracked and reference counted by PWRM. For example, for OMAP3430, the header file `pwrms3430.h` defines a `PWRM_Resource` enumeration listing the resources PWRM supports by default. The last element of this enumeration is “`PWRM_3430_USER_BASE`”, which can serve as a resource ID for the first user-defined resource. If, for example, you specify that there are two user-defined resources, PWRM allocates reference counting support for these resources at PWRM initialization time, and recognizes these resources as IDs `PWRM_3430_USER_BASE` and `PWRM_3430_USER_BASE+1`. The “Enable Resource Tracking” box must be checked for this property to be writeable.

Tconf Name: `USERRESOURCES` Type: Numeric
 Example: `bios.PWRM.USERRESOURCES = 4;`

Callout function for shared resources. This property allows you to specify the function PWRM should call upon $0 \rightarrow 1$ and $1 \rightarrow 0$ reference count transitions.

For example, when a driver declares the first dependency upon a resource (via a call to `PWRM_setDependency`), this is a $0 \rightarrow 1$ reference count transition. When this occurs, PWRM makes a callout to the configured function to perform the necessary processing to enable the resource. Subsequent calls to set more dependencies on the same resource result in increments of the reference count, but no further calls to the callout function. Dependencies upon the resource can be released via calls to `PWRM_releaseDependency`, and when the last dependency upon the resource is released, this is $1 \rightarrow 0$ reference count transition, and PWRM will callout again to the configured function to do the necessary processing to disable the resource.

The callout function signature is:

```
Uns resourceCallout(Uns arg0, Uns arg1)
```

When this function is called: `arg0` indicates the resourceID of the corresponding call to `PWRM_setDependency` or `PWRM_releaseDependency`; and `arg1` is `PWRM_SET` if a $0 \rightarrow 1$ transition occurred, or `PWRM_RELEASE` if a $1 \rightarrow 0$ transition occurred. The callout function should return `TRUE` on success, and `FALSE` if a failure occurs.

The “Enable Resource Tracking” box must be checked for this property to be writeable.

Tconf Name: `SHAREDRESOURCEFXN` Type: Extern
 Example: `bios.PWRM.SHAREDRESOURCEFXN = prog.extern("rsrcCallout");`

Enable V/F Scaling Support. Check this box to enable PWRM's support for V/F scaling.

Tconf Name: `SCALING` Type: Bool
 Example: `bios.PWRM.SCALING = true;`

MEM section for hibernate resume code. This property allows you to specify the MEM section where PWRM's code for resuming from the PWRM_HIBERNATE sleep mode should be located. Since the C64x+ processor is powered off during hibernation, you must specify an external MEM section that remains powered during hibernation.

Tconf Name: WARMBOOTMEMSEG Type: Reference

Example: `bios.PWRM.WARMBOOTMEMSEG = prog.get("DDR");`

MEM section for hibernate context. This property allows you to specify the MEM section where the DSP context should be saved to prior to powering off the DSP for the PWRM_HIBERNATE sleep mode. You must specify an external MEM section that remains powered during hibernation.

Tconf Name: CTXBUFMEMSEG Type: Reference

Example: `bios.PWRM.CTXBUFMEMSEG = prog.get("DDR");`

Base address of System Control Module (SCM). When enabling the IVA MMU, use this configuration property to specify the virtual address mapped to the physical address of the System Control Module. The IVA MMU must map one page (4 KB) of virtual memory starting at the given address.

Tconf Name: SCM_BASEADDR Type: Address

Example: `bios.PWRM.SCM_BASEADDR = 0x12007000;`

Base address of Clock Manager (CM). When enabling the IVA MMU, use this configuration property to specify the virtual address mapped to the physical address of the Clock Manager. The IVA MMU must map one page (4 KB) of virtual memory starting at the given address.

Tconf Name: CM_BASEADDR Type: Address

Example: `bios.PWRM.CM_BASEADDR = 0x12004000;`

Base address of Power & Reset Manager (PRM). When enabling the IVA MMU, use this configuration property to specify the virtual address mapped to the physical address of the Power & Reset Manager. The IVA MMU must map one page (4 KB) of virtual memory starting at the given address.

Tconf Name: PRM_BASEADDR Type: Address

Example: `bios.PWRM.PRM_BASEADDR = 0x12006000;`

Base address of IVA MMU. When enabling the IVA MMU, use this configuration property to specify the virtual address mapped to the physical address of the IVA MMU. The IVA MMU must map one page (4 KB) of virtual memory starting at the given address.

Tconf Name: IVAMMU_BASEADDR Type: Address

Example: `bios.PWRM.IVAMMU_BASEADDR = 0x12005000;`

Use timer based CPU load monitoring. To use timer-based CPU load monitoring, set the USETIMER property to 1. Note, you must first set USECLKPRD to 0 in order to select the timer configuration (`bios.PWRM.USECLKPRD = 0`).

Tconf Name: USETIMER Type: Bool

Example: `bios.PWRM.USETIMER = 1;`

Select timer. Select which timer to use as the time base for CPU load monitoring. You may choose Timer 5, 6, 7, or 8. Note that you cannot use the same timer that is being used for the DSP/BIOS clock.

Tconf Name: `TIMERID` Type: Enumerated String

Example: `bios.PWRM.TIMERID = "Timer 7";`

Base address of timer. When enabling the IVA MMU, use this configuration property to specify the virtual address mapped to the physical address of the timer. The IVA MMU must map one page (4 KB) of virtual memory starting at the given address. If the IVA MMU is disabled, the timer physical address must be specified.

Tconf Name: `TIMERBASEADDR` Type: Address

Example: `bios.PWRM.TIMERBASEADDR = 0x4903C000;`

Timer input clock speed. The timer input clock speed must be specified. It is specified in KHz.

Tconf Name: `TIMERINPUTCLK` Type: Unsigned

Example: `bios.PWRM.TIMERINPUTCLK = 19200;`

Timer period. Specify the period at which the timer should finalize the CPU load monitoring slots. The period is specified in milliseconds.

Tconf Name: `TIMERPERIOD` Type: Unsigned

Example: `bios.PWRM.TIMERPERIOD = 10;`

Timer interrupt. Specify which CPU interrupt the timer should be routed to.

Tconf Name: `TIMERINTR` Type: Reference

Example: `bios.PWRM.TIMERINTR = prog.get("HWI_INT15");`

2.3 Graphical View

The following dialog allows you to set PWRM properties in GConf:

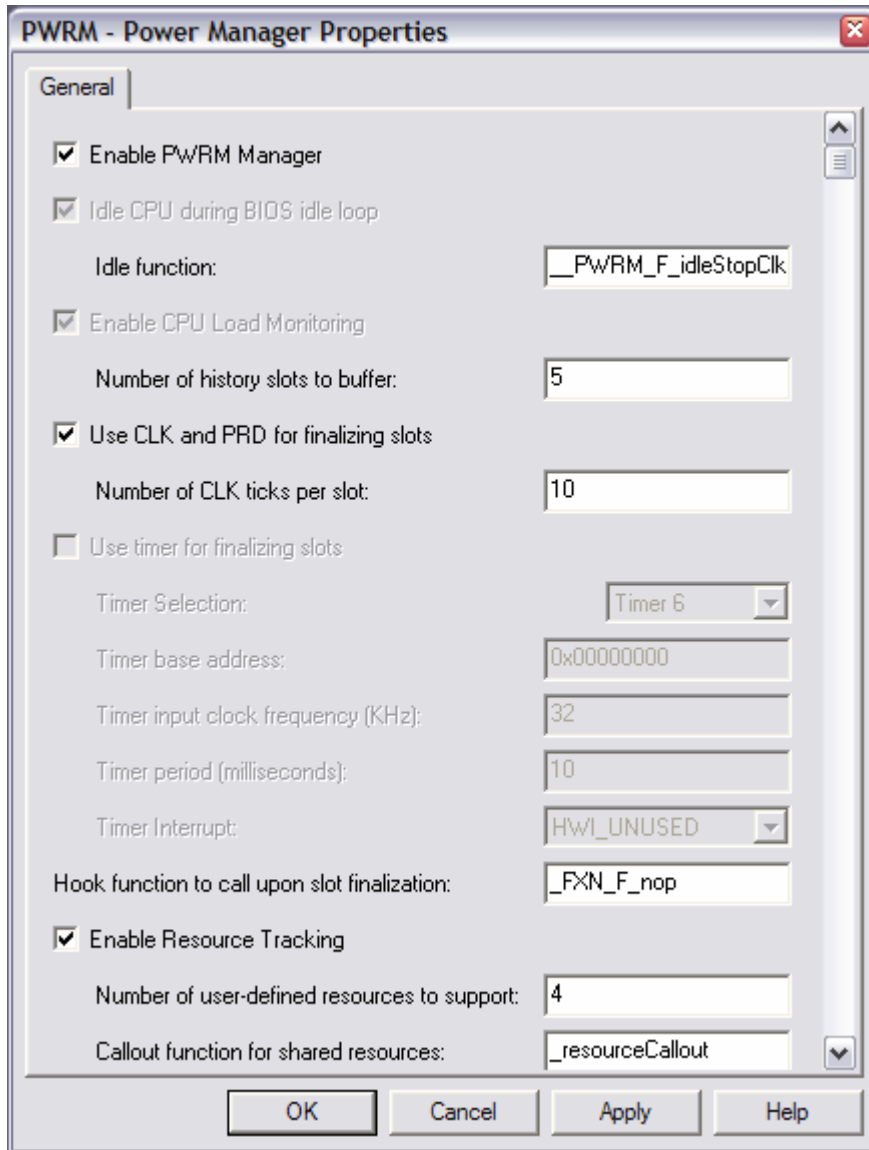


Figure 1. PWRM Properties Dialog (top portion)

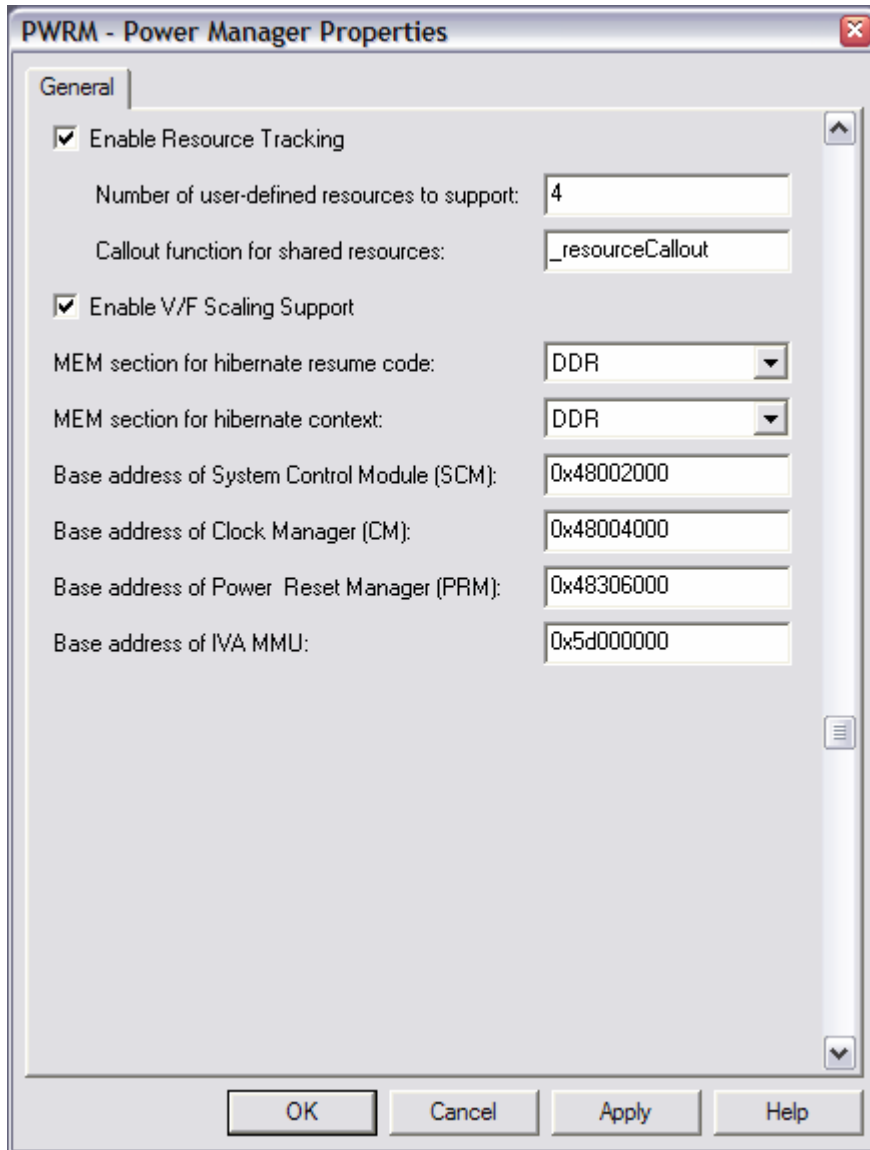


Figure 2. PWRM Properties Dialog (lower portion)

3 DSP/BIOS Power Manager API Reference

The PWRM APIs for C64x+ are summarized in the following table, and listed on the following pages in reference format.

Function	Purpose
PWRM_getCapabilities	Get information on PWRM's capabilities on the current platform
PWRM_getCPULoad	Get CPU load information as measured by PWRM.
PWRM_getCurrentSetpoint	Get the current setpoint in effect
PWRM_getDependencyCount	Get count of dependencies currently declared on a resource.
PWRM_getLoadMonitorInfo	Get PWRM load monitor configuration info.
PWRM_getNumSetpoints	Get the number of setpoints supported for the current platform
PWRM_getSetpointInfo	Get the corresponding frequency and voltage for a setpoint
PWRM_initSetpointInfo	Initialize PWRM's setpoint info.
PWRM_registerNotify	Register a function to be called on a specific power event
PWRM_releaseDependency	Release a dependency that has been previously declared.
PWRM_resetCPULoadHistory	Reset PWRM's CPU load history buffer.
PWRM_setDependency	Declare a dependency upon a resource.
PWRM_signalEvent	Signal a PWRM event to clients who've registered for the event.
PWRM_sleepDSP	Transition the DSP to a new sleep state
PWRM_startCPULoadMonitoring	Start CPU load monitoring.
PWRM_stopCPULoadMonitoring	Stop CPU load monitoring.
PWRM_unregisterNotify	Unregister for an event notification from PWRM.
PWRM_validateSetpoint	Check whether a setpoint conflicts with constraints of registered notification clients.

PWRM_getCapabilities

Get information on PWRM capabilities on the current platform

Syntax `status = PWRM_getCapabilities(capsMask);`

Parameters `Uns * capsMask` `/* ptr to location of capabilities mask */`

Return Value `PWRM_Status status;` `/* returned status */`

Reentrant `Yes`

Description PWRM_getCapabilities returns information about the PWRM module's capabilities on the current platform.

The capsMask parameter should point to the location where PWRM_getCapabilities should write a bitmask that defines the capabilities. You can use the following constants to check for capabilities in the bitmask:

Name	Usage
PWRM_CLOADMONITORING	The PWRM module supports CPU load monitoring.
PWRM_CRESOURCETRACKING	The PWRM module supports dynamic resource tracking.
PWRM_CVFSCALING	The PWRM module supports voltage and frequency scaling.

PWRM_getCapabilities returns one of the following constants as a status value of type PWRM_Status:

Name	Usage
PWRM_SOK	The operation succeeded.
PWRM_EINVALIDPOINTER	The operation failed because the capsMask parameter was NULL.

Example

```
PWRM_Status status;
Uns capsMask;

/* Query PWRM capabilities on this platform */
status = PWRM_getCapabilities(&capsMask);
if (status == PWRM_SOK) {
    LOG_printf(TRACE, "Caps mask=0x%X", capsMask);
    if ((capsMask & PWRM_CVFSCALING) == 0) {
        LOG_printf(TRACE, "V/F scaling not supported!");
    }
}
else {
    LOG_printf(TRACE, "ERROR: status = %x", status);
}
```

PWRM_getCPULoad

Get CPU load information

Syntax `status = PWRM_getCPULoad(numSlots, loadInfo);`

Parameters `Uns numSlots; /* # of history slots of load info to retrieve */
PWRM_CPULoadInfo *loadInfo;
 /* array of load info structures to be filled by PWRM */`

Return Value `PWRM_Status status; /* returned status */`

Reentrant `Yes`

Description PWRM_getCPULoad reports CPU load information accumulated by the PWRM module. Load history is accumulated in “slots” of a configured duration. (See PWRM Manager Properties on page 4 for details on configuring the number of slots to be buffered by PWRM and the duration of those slots.)

The PWRM_CPULoadInfo structure reports the total number of CPU cycles for the slot, the number of those cycles where the CPU was busy, and a timestamp indicating when the slot was finalized (completed).

```
typedef struct PWRM_CPULoadInfo {
    Uns busyCycles;           /* number of cycles CPU was busy */
    Uns totalCycles;        /* total number of CPU cycles in slot */
    Uns timeStamp;          /* time when slot finalized */
} PWRM_CPULoadInfo;
```

The numSlots parameter specifies how many history slots of the loadInfo array should be written by PWRM. History slots are reported in last-in, first-out (LIFO) order. In other words, the most recently finalized history slot is reported in the first element of the loadInfo array, the slot previous to that is reported in the second element, and so on.

PWRM maintains a ring buffer of history slots. Once all history slots have been filled, finalizing the next slot causes the oldest history slot to be overwritten. The number of slots buffered in PWRM is configured statically. If numSlots is greater than the number of slots maintained by PWRM, then a PWRM_EOUTOFRANGE error is reported, and no history data is copied to loadInfo.

If a history slot is “empty” then the slot data elements have a default (reset) value:

```
PWRM_CPULoadInfo _PWRM_resetLoad = {
    0, /* busyCycles */
    0, /* totalCycles */
    0 /* timestamp */
};
```

Slots are empty if not enough time has passed for PWRM’s internal slot buffer to fill, either since startup, or since a call to PWRM_resetCPULoadHistory.

PWRM only reports load information for finalized slots. In other words, PWRM does not report information on the currently filling but not yet completed slot. It is only when the current slot is finalized that the accumulated busy and total cycles will be stored in PWRM's ring buffer.

PWRM_getCPULoad returns one of the following constants as a status value of type PWRM_Status:

Name	Usage
PWRM_SOK	The operation succeeded.
PWRM_EINITFAILURE	The operation failed because there was a failure during load monitor initialization.
PWRM_EINVALIDPOINTER	The operation failed because the loadInfo parameter was NULL.
PWRM_ENOTSUPPORTED	The operation failed because load monitoring is not enabled.
PWRM_EOUTOFRANGE	The operation failed because numSlots is greater than the number of history slots PWRM has been configured to maintain.

Example

```
#define NUMSLOTS          5

PWRM_CPULoadInfo history[NUMSLOTS];

status = PWRM_getCPULoad(NUMSLOTS, history);
if (status == PWRM_SOK) {
    displayCPULoad(history);
}
else {
    LOG_printf	TRACE, "Error: status = %x", status;
}
```

PWRM_getCurrentSetpoint	Get the current setpoint
--------------------------------	--------------------------

Syntax `status = PWRM_getCurrentSetpoint(setpoint);`

Parameters `Uns *setpoint; /* current V/F setpoint */`

Return Value `PWRM_Status status; /* returned status */`

Reentrant `No`

Description `PWRM_getCurrentSetpoint` returns the V/F scaling setpoint currently in use. The setpoint parameter should point to the location where `PWRM_getCurrentSetpoint` should write the current setpoint.

`PWRM_getCurrentSetpoint` returns one of the following constants as a status value of type `PWRM_Status`:

Name	Usage
<code>PWRM_SOK</code>	The operation succeeded.
<code>PWRM_EINVALIDPOINTER</code>	The operation failed because the setpoint parameter was NULL.
<code>PWRM_EINITFAILURE</code>	A failure occurred while initializing V/F scaling support; V/F scaling is unavailable.
<code>PWRM_ENOTSUPPORTED</code>	The operation failed because V/F scaling is not enabled.

Constraints and Calling Context

- Attempts to call `PWRM_getCurrentSetpoint` before `PWRM_initSetpointInfo` is called result in a return code of `PWRM_EINITFAILURE`. Once `PWRM_initSetpointInfo` is successfully called, `PWRM_getCurrentSetpoint` should become functional.
- If a call to `PWRM_getCurrentSetpoint` is made during a change to the current setpoint, the value `PWRM_getCurrentSetpoint` returns may be the old setpoint and not the new setpoint.

Example

```

PWRM_Status status;
Uns currSetpoint;
status = PWRM_getCurrentSetpoint(&currSetpoint);
if (status == PWRM_SOK) {
    LOG_printf	TRACE, "Setpoint: %d", currSetpoint;
}
else {
    LOG_printf	TRACE, "ERROR: status = %x", status;
}
    
```

PWRM_getDependencyCount

Get count of dependencies declared on resource

Syntax `status = PWRM_getDependencyCount(resourceID, count);`
Parameters `Uns resourceID; /* resource ID */`
 `Uns *count; /* pointer to where count is written */`
Return Value `PWRM_Status status; /* returned status */`
Reentrant `Yes`

Description `PWRM_getDependencyCount` returns the number of dependencies that are currently declared on a resource. Normally this corresponds to the number of times `PWRM_setDependency` has been called for the resource, minus the number of times `PWRM_releaseDependency` has been called for the same resource.

Resource IDs are device-specific, and are defined in a `PWRM_Resource` enumeration in a device-specific header file. For example, see `pwr3430.h` for OMAP3430. Additionally, users may declare "user-defined" resources, and reference these as an offset to the last enumerated pre-defined resource. For more information, see the "Number of user-defined resources to support" description in the PWRM Manager Properties section on page 4.

`PWRM_getDependencyCount` returns one of the following constants as a status value of type `PWRM_Status`:

Name	Usage
<code>PWRM_SOK</code>	The operation succeeded, and the reference count was written to the location pointed to by <code>count</code> .
<code>PWRM_EINITFAILURE</code>	An error occurred during initialization for user-defined resources.
<code>PWRM_EINVALIDPOINTER</code>	The operation failed because the <code>count</code> parameter was <code>NULL</code> .
<code>PWRM_ENOTSUPPORTED</code>	The operation failed because resource tracking is not enabled.
<code>PWRM_EOUTOFRANGE</code>	The specified <code>resourceID</code> is outside the range of valid pre-defined or user-defined resource IDs.

Example

```

/* Display some dependency counts */
LOG_printf(TRACE, "Initial dependencies:");

PWRM_getDependencyCount(PWRM_3430_GPTIMER_5, &count);
LOG_printf(TRACE, "GPT5 count = %d", count);

PWRM_getDependencyCount(PWRM_3430_BIOS_CLK, &count);
LOG_printf(TRACE, "BIOS CLK count = %d", count);

PWRM_getDependencyCount(PWRM_3430_MCBSP_1, &count);
LOG_printf(TRACE, "MCBSP_1 count = %d", count);

```


PWRM_getNumSetpoints

Get the number of setpoints supported by platform

Syntax `status = PWRM_getNumSetpoints(numberSetpoints);`

Parameters `Uns *numberSetpoints; /* number of supported setpoints */`

Return Value `PWRM_Status status; /* returned status */`

Reentrant Yes

Description `PWRM_getNumSetpoints` returns the number of setpoints supported by the platform. The `numberSetpoints` parameter should point to the location where `PWRM_getNumSetpoints` should write the number of setpoints.

`PWRM_getNumSetpoints` returns one of the following constants as a status value of type `PWRM_Status`:

Name	Usage
<code>PWRM_SOK</code>	The operation succeeded.
<code>PWRM_EINVALIDPOINTER</code>	The operation failed because the <code>numberSetpoints</code> parameter was NULL.
<code>PWRM_EINITFAILURE</code>	V/F scaling support has not been initialized; V/F scaling is unavailable.
<code>PWRM_ENOTSUPPORTED</code>	The operation failed because V/F scaling is not enabled.

Constraints and Calling Context

- Attempts to call `PWRM_getNumSetpoints` before `PWRM_initSetpointInfo` is called result in a return code of `PWRM_EINITFAILURE`. Once `PWRM_initSetpointInfo` is successfully called, `PWRM_getNumSetpoints` should become functional.

Example

```
PWRM_Status status;
Uns numSetpoints;

status = PWRM_getNumSetpoints(&numSetpoints);
if (status == PWRM_SOK) {
    LOG_printf	TRACE, "NumSetpoints: %d", numSetpoints);
}
else {
    LOG_printf	TRACE, "Error: status = %x", status);
}
```

PWRM_getSetpointInfo

Get frequency and voltage for a setpoint

Syntax `status = PWRM_getSetpointInfo(setpoint, frequency, voltage);`

Parameters `Uns setpoint; /* the setpoint to query */`
 `Uns *frequency; /* CPU frequency (in kHz) */`
 `Uns *voltage; /* CPU core voltage (in millivolts) */`

Return Value `PWRM_Status status; /* returned status */`

Reentrant Yes

Description This function returns the DSP CPU frequency and voltage for a given setpoint.

The setpoint parameter should specify the setpoint value for which you want to know the frequency and voltage on this platform. The frequency parameter should point to the location where PWRM_getSetpointInfo should write the CPU frequency for the specified setpoint. The voltage parameter should point to the location where PWRM_getSetpointInfo should write the CPU core voltage for the specified setpoint.

PWRM_getSetpointInfo returns one of the following constants as a status value of type PWRM_Status:

Name	Usage
PWRM_SOK	The operation succeeded.
PWRM_EINVALIDPOINTER	The operation failed because the frequency or voltage parameter was NULL.
PWRM_EINITFAILURE	V/F scaling support has not been initialized; V/F scaling is unavailable.
PWRM_ENOTSUPPORTED	The operation failed because V/F scaling is not enabled.
PWRM_EOUTOFRANGE	The operation failed because the setpoint parameter is out of range of valid setpoints for the platform.

Constraints and Calling Context

- Attempts to call PWRM_getSetpointInfo before PWRM_initSetpointInfo is called result in a return code of PWRM_EINITFAILURE. Once PWRM_initSetpointInfo is successfully called, PWRM_getSetpointInfo should become functional.

Example

```
#define MAX_SETPOINTS    4
PWRM_Status status;

/* arrays for saving setpoint info */
Uns freq[MAX_SETPOINTS];
Uns volts[MAX_SETPOINTS];

status = PWRM_getSetpointInfo(i, &freq[i], &volts[i]);
if (status != PWRM_SOK) {
    LOG_printf	TRACE, "Error: status=%x", status;
}
```

PWRM_initSetpointInfo

Initialize V/F setpoint information for this platform

Syntax `status = PWRM_initSetpointInfo(numSetpoints, currentSetpoint, setpointInfo);`

Parameters `Uns numSetpoints ; /* number of setpoints */`
 `Uns currentSetpoint ; /* the current setpoint */`
 `PWRM_SetpointInfo * setpointInfo; /* setpoint info array */`

Return Value `PWRM_Status status; /* returned status */`

Reentrant `No`

Description `PWRM_initSetpointInfo` is called during program initialization to inform PWRM of the number of V/F setpoints available on the platform, the current setpoint, and the voltage and frequency information for each setpoint. Setpoint voltage and frequency details are specified via the `setpointInfo` array of `PWRM_SetpointInfo` structures.

```
typedef struct PWRM_SetpointInfo {
    Uns frequency;                            /* frequency in kHz */
    Uns voltage;                              /* voltage in millivolts */
} PWRM_SetpointInfo;
```

The first element of the array corresponds to setpoint “0”, the second element for setpoint “1”, etc.

`PWRM_initSetpointInfo` should be called only once during initialization. Attempts to call other setpoint related APIs (for example, `PWRM_getNumSetpoints`) before `PWRM_initSetpointInfo` is called will result in `PWRM_EINITFAILURE` return codes from those APIs. Once `PWRM_initSetpointInfo` is successfully called, the related setpoint APIs should become functional.

If `PWRM_initSetpointInfo` is called more than once, a `PWRM_ETOOMANYCALLS` error is returned.

`PWRM_initSetpointInfo` returns one of the following constants as a status value of type `PWRM_Status`:

Name	Usage
<code>PWRM_SOK</code>	The operation succeeded.
<code>PWRM_EFAIL</code>	The operation failed due to a memory allocation failure.
<code>PWRM_EINVALIDPOINTER</code>	The operation failed because the <code>setpointInfo</code> parameter was <code>NULL</code> .
<code>PWRM_ENOTSUPPORTED</code>	The operation failed because V/F scaling is not enabled.
<code>PWRM_ETOOMANYCALLS</code>	The operation failed because setpoint info had already been initialized in a previous call.

Constraints and Calling Context

- `PWRM_initSetpointInfo` should only be called once, during program initialization.

Example

```

#define NUM_SETPOINTS 4

PWRM_SetpointInfo platformSPInfo[NUM_SETPOINTS];
/* initialize setpoint info array */

. . .

/* now populate PWRM's setpoint info */
status = PWRM_initSetpointInfo(NUM_SETPOINTS,2,platformSPInfo);
if (status != PWRM_SOK) {
    LOG_printf	TRACE, "Error: status = %x", status);
}

```


The `clientArg` parameter is an arbitrary argument to be passed to the client upon notification. This argument may allow one notify function to be used by multiple instances of a driver (that is, the `clientArg` can be used to identify the instance of the driver that is being notified).

The `notifyHandle` parameter should point to the location where `PWRM_registerNotify` should write a notification handle. If the application later needs to unregister the notification function, the application should pass this handle to `PWRM_unregisterNotify`.

The `delayedCompletionFxn` is a pointer to a function provided by the PWRM module to the client at registration time. If a client cannot act immediately upon notification, its notify function should return `PWRM_NOTIFYNOTDONE`. Later, when the action is complete, the client should call the `delayedCompletionFxn` to signal PWRM that it has finished. The `delayedCompletionFxn` is a void function, taking no arguments, and having no return value. If a client can and does act immediately on the notification, it should return `PWRM_NOTIFYDONE` in response to notification, and should not call the `delayedCompletionFxn`.

For example, for a DMA driver to prepare for a setpoint change, it may need to wait for the current DMA transfer to complete. When the driver's DMA completes (for example, on the next hardware interrupt), it calls the `delayedCompletionFxn` function provided when it registered for notification. This completion function tells the PWRM module that the driver is finished. Meanwhile, the PWRM module was able to continue notifying other clients, and was waiting for all clients to signal completion.

This function returns one of the following constants as a status value of type `PWRM_Status`:

Name	Usage
PWRM_SOK	The operation succeeded.
PWRM_EFAIL	The operation failed due to a memory allocation failure.
PWRM_EINVALIDPOINTER	The operation failed because the <code>notifyFxn</code> , <code>notifyHandle</code> or <code>delayedCompletionFxn</code> parameter was NULL.
PWRM_EINVALIDEVENT	Operation failed because <code>eventType</code> is invalid.

Constraints and Calling Context

- `PWRM_registerNotify` cannot be called from a SWI or HWI. This is because `PWRM_registerNotify` internally calls `MEM_alloc`, which may cause a context switch.

Example

```
/* client #1 allows all setpoints */
#define ALLSETPOINTSALLOWED 0xFFFFFFFF

/* client #2 doesn't allow lowest 4 setpoints */
#define SOMESETPOINTSALLOWED 0xFFFFFFFF0

/* notification handles */
PWRM_NotifyHandle notifyHandle1;
PWRM_NotifyHandle notifyHandle2;

/* pointers to returned delayed completion fxns */
Fxn delayFxn1;
Fxn delayFxn2;

/* client #1 registers pre-setpoint notification */
PWRM_registerNotify(PWRM_PENDINGSETPOINTCHANGE,
    ALLSETPOINTSALLOWED, (Fxn)myNotifyFxn1,
    (Arg)0x1111, &notifyHandle1, (Fxn *) &delayFxn1);

/* client #2 registers post-setpoint notification */
PWRM_registerNotify(PWRM_DONESETPOINTCHANGE,
    SOMESETPOINTSALLOWED, (Fxn)myNotifyFxn2,
    (Arg)0x2222, &notifyHandle2, &delayFxn2);
```


pwrMNotifyFxn

Function to be called for power event notification

Syntax `status = notifyFxn(eventType, eventArg1, eventArg2, clientArg);`

Parameters `PWRM_Event eventType; /* type of power event */`
 `Arg eventArg1; /* event-specific argument */`
 `Arg eventArg2; /* event-specific argument */`
 `Arg clientArg; /* arbitrary argument */`

Return Value `PWRM_NotifyResponse status; /* returned status */`

Description PWRM_registerNotify registers a function to be called when a specific power event occurs. Clients, which are typically drivers, register notification functions they need to run when a particular power event occurs.

This topic describes the required prototype and behavior of such notification functions. Your application must provide and register these functions. Registered functions are called internally by the PWRM module.

The eventType parameter identifies the type of power event for which the notify function is being called. This parameter has an enumerated type of PWRM_Event. The values for this parameter are listed in the PWRM_registerNotify topic.

The eventArg1 and eventArg2 parameters are event-specific arguments. Currently, eventArg1 and eventArg2 are used only for V/F scaling events:

- **PWRM_PENDINGSETPOINTCHANGE.** The eventArg1 holds the current setpoint, and eventArg2 holds the pending setpoint.
- **PWRM_DONESETPOINTCHANGE.** The eventArg1 holds the previous setpoint, and eventArg2 holds the new setpoint.

The clientArg parameter holds the arbitrary argument passed to PWRM_registerNotify when this function was registered. This argument may allow one notify function to be used by multiple instances of a driver (that is, the clientArg can be used to identify the instance of the driver that is being notified).

The notification function must return one of the following constants as a status value of type PWRM_NotifyResponse:

Name	Usage
PWRM_NOTIFYDONE	The client processed the notification function successfully.
PWRM_NOTIFYNOTDONE	The client must wait for interrupt processing to occur before it can proceed. The client must later call the delayedCompletionFxn specified when this function was registered with PWRM_registerNotify.
PWRM_NOTIFYERROR	Notification cannot be processed. Either an internal client error occurred or the client was notified of an event it could not process. (For V/F setpoint changes, the client registers setpoints it can accommodate to avoid this error.) When a client returns this error, the caller of the PWRM function that triggered the notification receives a PWRM_EFAIL return status.

Constraints and Calling Context

- The notification function should not call PWRM APIs that trigger a notification event (for example, PWRM_sleepDSP). If such an API is called, the PWRM_EBUSY status code is returned.

Example

```
/* notification function prototypes */
PWRM_NotifyResponse myNotifyFxn1(
    PWRM_Event eventType, Arg eventArg1, Arg eventArg2, Arg clientArg);
PWRM_NotifyResponse myNotifyFxn2(
    PWRM_Event eventType, Arg eventArg1, Arg eventArg2, Arg clientArg);

/* ===== myNotifyFxn1 ===== */
PWRM_NotifyResponse myNotifyFxn1(
    PWRM_Event eventType, Arg eventArg, Arg eventArg2, Arg clientArg)
{
    #if VERBOSE
        LOG_printf	TRACE, "\nclient #1 notify, PENDINGSETPOINTCHANGE");
        LOG_printf	TRACE, "eventArg=%p, eventArg2=%p", eventArg, eventArg2);
        LOG_printf	TRACE, "clientArg=%p", clientArg);
        LOG_printf	TRACE, "signal notify complete");
    #endif
    return(PWRM_NOTIFYPDONE); /* notify complete */
}
```


PWRM_setDependency

Declare a dependency upon a resource

Syntax `status = PWRM_setDependency(resourceID);`

Parameters `Uns resourceID; /* resource ID */`

Return Value `PWRM_Status status; /* returned status */`

Reentrant `Yes`

Description This function sets a dependency on a resource. It is the companion to PWRM_releaseDependency.

Resource IDs are device-specific, and are defined in a PWRM_Resource enumeration in a device-specific header file. For example, see pwrms3430.h for OMAP3430. Additionally, users may declare "user-defined" resources, and reference these as an offset to the last enumerated pre-defined resource. For more information, see the "Number of user-defined resources to support" description in the PWRM Manager Properties section on page 4.

PWRM_setDependency returns one of the following constants as a status value of type PWRM_Status:

Name	Usage
PWRM_SOK	The operation succeeded, and dependency has been set.
PWRM_EINITFAILURE	An error occurred during initialization for user-defined resources.
PWRM_EFAIL	The operation failed while attempting to enable the resource.
PWRM_ENOTSUPPORTED	The operation failed because resource tracking is not enabled.
PWRM_EOUTOFRANGE	The specified resourceID is outside the range of valid pre-defined or user-defined resource IDs.

Example

```
/* Declare a driver dependency upon McBSP #1 */
PWRM_setDependency(PWRM_3430_MCBSP_1);
```


Constraints and Calling Context

- PWRM_signalEvent can be called from a HWI or SWI only if notifyTimeout is 0.

Example

```

status = PWRM_signalEvent(PWRM_DONESETPOINTCHANGE, previousSetpoint, newSetpoint, 0);
if (status != PWRM_SOK) {
    LOG_printf	TRACE, "Error: status = %x", status);
}
  
```

PWRM_sleepDSP

Transition the DSP to a new sleep state

Syntax `status = PWRM_sleepDSP(sleepCode, sleepArg, notifyTimeout);`

Parameters `Uns sleepCode; /* new sleep state */`
 `LgUns sleepArg; /* a sleepCode-specific argument */`
 `Uns notifyTimeout; /* max time to wait for notification */`

Return Value `PWRM_Status status; /* returned status */`

Reentrant `Yes`

Description `PWRM_sleepDSP` transitions the DSP to a new sleep state.

The `sleepCode` parameter indicates the new sleep state for the DSP. The following constants may be used on OMAP3430:

Name	Usage
PWRM_RETENTION	The DSP is put into a low-power state in which all memory and logic contents are retained.
PWRM_RETENTIONALT	The DSP is put into a low-power state in which all memory and logic contents are retained. This <code>sleepCode</code> allows the application to define two retention states. For example, one with clocks running and one with clocks stopped.
PWRM_HIBERNATE	The DSP is completely powered off, with context saved before going off, and restored upon power on.
PWRM_STANDBY	The GEM is put into a power-saving mode. Its clock is turned off. This mode has a minimal latency for wakeup.

A successful call to `PWRM_sleepDSP` returns when the DSP has awoken from the specified sleep state.

The `sleepArg` parameter may be zero or the address of an array that begins with a control word and is optionally followed by four words that indicate the wakeup conditions for returning from the sleep state to the CPU active state. The control word and wakeup conditions are specified via five masks with the following ordering:

```

Uns control;                   /* control bits as defined below */
Uns WUGEN_MEVT0;            /* bits to be set in WUGEN_MEVT0 register */
Uns WUGEN_MEVT1;            /* bits to be set in WUGEN_MEVT1 register */
Uns WUGEN_MEVT2;            /* bits to be set in WUGEN_MEVT2 register */
Uns WUGEN_MEVT3;            /* bits to be set in WUGEN_MEVT3 register */

```


The control word should be initialized to zero. The bits in the control word may be set with the following constants:

- **PWRM_ARGSWUGENMASK.** When set, this bit indicates that the sleepArg array contains four additional words that define the wakeup conditions. If this bit is not set, only the first element of the array (the control word itself) is referenced.
- **PWRM_ARGSNOPLLCONFIG.** When set, this bit indicates that the IVA2 DPLL configuration will not be modified by PWRM_sleepDSP. It is assumed to be configured as needed to support the given sleep code. If this bit is not set, PWRM_sleepDSP will configure the IVA2 DPLL as needed to support the given sleep code.

Prior to activating the sleep state, PWRM_sleepDSP uses the specified masks to set the corresponding bits in the WUGEN_MEVTx registers. Bits that are cleared correspond to events that can wake the DSP from the sleep state. Bits that are set correspond to events that will be blocked as wakeup events by the WUGEN. After CPU wakeup from a sleep state, the WUGEN event mask registers are restored to their original state. Any pending interrupt that was not configured as a wakeup event but had been allowed to propagate prior to calling PWRM_sleepDSP is allowed to pass through once the original event masks are restored.

The notifyTimeout parameter is the maximum amount of time (in system clock ticks) to wait for registered notification functions (set by PWRM_registerNotify) to respond to a delayed completion, before declaring failure and returning PWRM_ETIMEOUT. If the notifyTimeout parameter is zero, then all notification functions must return PWRM_NOTIFYDONE—they cannot request a delayed completion. If a notification function does not return, the system will hang. The notifyTimeout is not used to abandon a notification function; rather it indicates the amount of time PWRM_sleepDSP waits for all delayed completion requests to complete. The wait-loop is entered after all notification functions have been invoked.

PWRM_sleepDSP returns one of the following constants as a status value of type PWRM_Status:

Name	Usage
PWRM_SOK	A successful sleep and wake occurred.
PWRM_EFAIL	A general failure occurred. Could not sleep the DSP.
PWRM_ENOTIMPLEMENTED	The requested sleep mode is not implemented on this platform.
PWRM_ETIMEOUT	A registered notification function did not respond within the specified notifyTimeout.
PWRM_EBUSY	The requested operation cannot be performed at this time; PWRM is busy processing a previous request.

Due to the critical system nature of sleep commands, clients that register for sleep notification should make every effort to respond immediately to the sleep event.

The application should treat return values of PWRM_ETIMEOUT or PWRM_EFAIL as critical system failures. These values indicate the notification client is unresponsive, and the system is in an unknown state.

Constraints and Calling Context

- PWRM_sleepDSP cannot be called from an HWI.
- This API cannot be called from a program's main() function.
- PWRM_sleepDSP can only be called from a SWI if notifyTimeout is 0.

Example

```
#define TIMEOUT 10 /* notification timeout after 10 ticks */
Uns sleepArgs[5];

/* set wakeup conditions */
sleepArgs[0] = PWRM_ARGSWUGENMASK | PWRM_ARGSNOPLLCONFIG;
sleepArgs[1] = 0xFFFFFFFFBF; /* enable GP timer 5 as wakeup */
sleepArgs[2] = 0x0000FFFF; /* no wakeups via WUGEN_MEVT1 */
sleepArgs[3] = 0x0000FFFF; /* no wakeups via WUGEN_MEVT2 */
sleepArgs[4] = 0x00000001; /* no wakeups via WUGEN_MEVT3 */

LOG_printf(TRACE, "Putting DSP to retention...");
status = PWRM_sleepDSP(PWRM_RETENTION, (LgUns)&sleepArgs, TIMEOUT);
LOG_printf(TRACE, "DSP is awake from retention");
LOG_printf(TRACE, "Returned 0x%x", status);
```

PWRM_startCPULoadMonitoring	Start CPU load monitoring
------------------------------------	---------------------------

Syntax `status = PWRM_startCPULoadMonitoring();`

Parameters `none`

Return Value `PWRM_Status status;` `/* returned status */`

Reentrant `Yes`

Description This function starts the collection of CPU load information for the purpose of monitoring the CPU load.

When CPU load monitoring is started, an internal call to `PWRM_resetCPULoadHistory()` is made. `PWRM_setDependency()` is also called to declare a dependency on the timer. If timer-based CPU load monitoring is being used, the timer is reloaded and started.

`PWRM_startCPULoadMonitoring` returns one of the following constants as a status value of type `PWRM_Status`:

Name	Usage
<code>PWRM_SOK</code>	The operation succeeded, and the dependency has been released.
<code>PWRM_EINITFAILURE</code>	An error occurred during initialization for user-defined resources.
<code>PWRM_EFAIL</code>	The operation failed while attempting to release the resource.
<code>PWRM_ENOTSUPPORTED</code>	The operation failed because resource tracking is not enabled.
<code>PWRM_EOUTOFRANGE</code>	The specified resourceID is outside the range of valid pre-defined or user-defined resource IDs.

Example

<code>PWRM_startCPULoadMonitoring();</code>

PWRM_stopCPULoadMonitoring

Stop CPU load monitoring

Syntax `status = PWRM_stopCPULoadMonitoring();`

Parameters `none`

Return Value `PWRM_Status status; /* returned status */`

Reentrant `Yes`

Description This function stops the collection of CPU load information for the purpose of monitoring the CPU load. While stopped, no calls are made to the configured slot hook function.

If timer-based load monitoring is being used, the timer is stopped. In all cases, an internal call to `PWRM_releaseDependency()` is made to release the dependency on the timer.

`PWRM_stopCPULoadMonitoring` returns one of the following constants as a status value of type `PWRM_Status`:

Name	Usage
<code>PWRM_SOK</code>	The operation succeeded, and the dependency has been released.
<code>PWRM_EINITFAILURE</code>	An error occurred during initialization for user-defined resources.
<code>PWRM_EFAIL</code>	The operation failed while attempting to release the resource.
<code>PWRM_ENOTSUPPORTED</code>	The operation failed because resource tracking is not enabled.
<code>PWRM_EOUTOFRANGE</code>	The specified resourceID is outside the range of valid pre-defined or user-defined resource IDs.
<code>PWRM_ETOOMANYCALLS</code>	A dependency was not previously set and was therefore not released.

Example

```
PWRM_stopCPULoadMonitoring();
```

PWRM_unregisterNotify

Unregister for an event notification from PWRM

Syntax `status = PWRM_unregisterNotify(notifyHandle);`

Parameters `PWRM_NotifyHandle notifyHandle; /* handle to function */`

Return Value `PWRM_Status status; /* returned status */`

Reentrant `Yes`

Description PWRM_unregisterNotify unregisters an event notification that was registered by PWRM_registerNotify. For example, when an audio codec device is closed, it no longer needs to be notified, and must unregister for event notification.

The notifyHandle parameter is the parameter that was provided by PWRM_registerNotify when the function was registered.

PWRM_unregisterNotify returns one of the following constants as a status value of type PWRM_Status:

Name	Usage
PWRM_SOK	The function was successfully unregistered.
PWRM_EFAIL	The operation failed due to a memory free failure.
PWRM_EINVALIDHANDLE	The operation failed because notifyHandle is invalid.

Constraints and Calling Context

- This API cannot be called from a program's main() function.

Example

```
PWRM_NotifyHandle notifyHandle1;
PWRM_registerNotify(PWRM_PENDINGSETPOINTCHANGE, ALLSETPOINTSALLOWED,
    (Fxn)myNotifyFxn1, (Arg)0x1111, &notifyHandle1, (Fxn *) &delayFxn1);
PWRM_unregisterNotify(notifyHandle1);
```

PWRM_validateSetpoint

Validate a setpoint versus constraints of registered clients

Syntax `status = PWRM_validateSetpoint(setpoint);`

Parameters `Uns setpoint; /* setpoint to validate */`

Return Value `PWRM_Status status; /* returned status */`

Reentrant `Yes`

Description `PWRM_validateSetpoint` can be used to check whether a given setpoint has been declared as not supported during registrations for V/F scaling notifications. If the setpoint does not conflict with any registered constraints then `PWRM_SOK` is returned.

For example, a serial port driver may only be able to operate at a subset of available setpoints, and it indicates this via the `eventMask` parameter when it calls `PWRM_registerNotify`. Application code can quickly check to see if there is any such constraint on a setpoint by calling `PWRM_validateSetpoint`.

`PWRM_validateSetpoint` returns one of the following constants as a status value of type `PWRM_Status`:

Name	Usage
<code>PWRM_SOK</code>	The operation succeeded, no registered V/F scaling notification clients have indicated they cannot support the specified setpoint.
<code>PWRM_EINITFAILURE</code>	V/F scaling support has not been initialized; V/F scaling is unavailable.
<code>PWRM_ENOTSUPPORTED</code>	The operation failed because either: V/F scaling is not enabled, or a registered V/F scaling notification client has indicated it cannot support the specified setpoint.
<code>PWRM_EOUTOFRANGE</code>	The operation failed because the setpoint parameter is out of range of valid setpoints for the platform.

Constraints and Calling Context

- Attempts to call `PWRM_validateSetpoint` before `PWRM_initSetpointInfo` is called result in a return code of `PWRM_EINITFAILURE`. Once `PWRM_initSetpointInfo` is successfully called, `PWRM_validateSetpoint` should become functional.

Example

```
#define NUM_SETPOINTS 32
for (i = 0; i < NUM_SETPOINTS; i++) {
    status = PWRM_validateSetpoint(i);
    if (status == PWRM_SOK) {
        LOG_printf	TRACE, "SETPOINT %d is OK", i;
    }
}
```

4 Special Considerations

C64x+ developers must observe the following special considerations and cautions when using the DSP/BIOS Power Manager.

4.1 Sleep Mode Disruption of DSP/BIOS CLK Services

Invoking power-saving sleep modes on some platforms can have a significant impact upon the CLK module's accuracy and correctness. Two examples for OMAP3430 are:

- Putting the DSP into the PWRM_RETENTION state causes the C64x+ timestamp counter to freeze after some hardware transition delays. When the DSP wakes from retention, calls to CLK_gettime do not account for the cycles that the timestamp counter was frozen. Also, if the CLK module's corresponding timer interrupt is not a wakeup condition, then clock ticks can be missed while the DSP is in retention, so the number of CLK ticks reported by CLK_gettime when the DSP eventually wakes can be in error.
- Putting the DSP into PWRM_HIBERNATE causes the C64x+ timestamp counter to be reset to zero when power to the DSP is turned back on. This means that even for a short hibernate time, the value reported by CLK_gettime upon wakeup will be less than a value read immediately before going to hibernate. And similar to the retention case, if the CLK module's corresponding timer interrupt is not a wakeup condition for hibernate, then CLK ticks can be missed and not reported by subsequent calls to CLK_gettime.

4.2 Effect of Load Monitoring on IDL Loop Processing

To implement CPU load monitoring, PWRM measures and accumulates the number of CPU cycles spent in the CPU's "IDLE" instruction. This method allows for both energy savings while the CPU is idle waiting for an interrupt, and for a high accuracy measure of true CPU idle time.

The tradeoff for using this technique is that when PWRM idles the CPU, the DSP/BIOS idle (IDL) loop execution is "frozen" until the next CPU interrupt. This means that any other processing placed in the IDL loop does not run continuously, but runs only once per wakeup from the IDLE instruction, before IDLE is invoked again.

For debug environments, when the idle loop is configured to run the RTA data pump to pass data to the debug host, this means that HST channel data will not flow freely, dynamic updating of the real-time analysis data in CCStudio plugins will stall, and updates can appear "choppy" in CCStudio. If this presents a problem during debug, PWRM's CPU load monitoring feature should be disabled until the necessary debugging has been completed or until it is time to deploy the application. Idling by PWRM in the idle loop is ultimately intended for deployed systems, where there is no CCStudio debugger attached.

5 References

The following documents provide information about power management on the C55x platform. While the details of PWRM configuration and APIs are different for the OMAP3430, some of the background information provided in these documents is useful for OMAP3430 applications.

- *TMS320 DSP/BIOS User's Guide* (SPRU423)
- *TMS320C5000 DSP/BIOS API Reference* (SPRU404)

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