TI Network Developer's Kit (NDK) v2.21 API

Reference Guide



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Read This First

About This Manual

This programmer's reference guide describes the various API functions provided by the NDK libraries, and is intended to aid the development of network applications. It is the central reference document used when programming the stack. See the *TI Network Developer's Kit (NDK) User's Guide* (SPRU523) to familiarize yourself with the stack libraries, NDK configuration, and using the stack with the SYS/BIOS and Code Composer Studio™ Development Tools.

The latest version number as of the publication of this guide is NDK v2.21.

The document covers NDK programming as it applies to the TMS320C6000, Cortex-A8, and ARM9 programming environment,.

How to Use This Manual

This document contains the following chapters:

- Chapter 1: Introduction summarizes the various API sets described in the NDK documentation.
- Chapter 2: Operating System Abstraction API describes the API used by the adaptation layer to
 access the operating system.
- Chapter 3: Sockets and Stream IO API describes the file and sockets API functions.
- Chapter 4: Initialization and Configuration describes the XGCONF configuration method, the NDK initialization sequence, and the Network Control module.
- Chapter 5: Network Tools Library Support Functions describes the network support functions contained in the NETTOOLS library.
- Chapter 6: Network Tools Library Services describes the network servers and services contained in the NETTOOLS library.
- Appendix A: Internal Stack Functions contains a partial list of internal stack functions provided to aid
 in the comprehension of kernel oriented calls.
- Appendix B: Network Address Translation describes the optional Network Address Translation component, how to set up virtual networks, and protocol proxies.
- Appendix C: Point-to-Point Protocol describes the operation of the PPP and PPPoE support API included in the NDK, and how to interface to a serial device.
- Appendix D: Hardware Adaptation Layer (HAL) describes the operation of the HAL, and the HAL
 API functions.
- Appendix E: Web Programming with the HTTP Server describes how to get information from an embedded network device through the webserver.
- Appendix F: IP Version 6 (IPv6) Stack API describes the APIs and data structures exposed by the IPv6 stack.
- Appendix G: Legacy Configuration Manager API describes the legacy Configuration Manager API.
- Appendix H: Revision History describes the changes to this document since the previous release.



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Notational Conventions

This document uses the following conventions:

- Program listings, program examples, and interactive displays are shown in a special typeface.
- In syntax descriptions, the function or macro appears in a bold typeface and the parameters appear in
 plain face within parentheses. Portions of a syntax that are in bold should be entered as shown;
 portions of a syntax that are within parentheses describe the type of information that should be
 entered.
- Macro names are written in uppercase text; function names are written in lowercase.

Related Documentation From Texas Instruments

Additional information about the NDK can be found in <u>SPRU523</u> (*TI Network Developer's Kit (NDK) User's Guide.*) and the <u>NDK category</u> of the TI Embedded Processors Wiki. If you have questions, you can ask them on the <u>BIOS forum</u> in TI's E2E community.

Information about SYS/BIOS, which is used in NDK applications, can be found in the SPRUEX3 (TI SYS/BIOS Real-time Operating System User's Guide) and the SYS/BIOS main page of the TI Embedded Processors Wiki.

The following documents describe Cortex[™]-A8 and ARM9 devices and related support tools. Many of these documents can be found on the Internet at http://www.ti.com.

SPNU151— ARM Optimizing C/C++ Compiler User's Guide

SPNU118— ARM Assembly Language Tools User's Guide

SPRUH73— AM335x ARM® Cortex™-A8 Microprocessors (MPUs) Technical Reference Manual

Cortex-A8 wiki page—on the TI Embedded Processors Wiki

ARM9 wiki page—on Ti's Embedded Processors Wiki

Sitara ARM Microprocessors forum—in TI's E2E Community

The following documents describe the TMS320C6x[™] devices and related support tools. To obtain a copy of any of these TI documents, call the Texas Instruments Literature Response Center at (800) 477–8924. When ordering, please identify the book by its title and literature number. Many of these documents can be found on the Internet at http://www.ti.com.

SPRU189 — TMS320C6000 DSP CPU and Instruction Set Reference Guide.

SPRU190 — TMS320C6000 DSP Peripherals Overview Reference Guide.

SPRU197 — TMS320C6000 Technical Brief.

SPRU198 — TMS320C6000 Programmer's Guide

SPRU509 — TMS320C6000 Code Composer Studio ™Development Tools v3.3 Getting Started Guide

SPRUFP2 — TMS320C6000 Network Developer's Kit (NDK) Support Package Ethernet Driver Design Guide.



Introduction

This chapter serves as an introduction to the programming API reference for the NDK software.

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1.1 What This Document Covers

This Reference Guide for the NDK is mainly a programming API reference guide. It is intended to aid in the development of network applications and describes the various API functions provided by the stack libraries.

Although this Programmer's Reference Guide will be the central reference document used when programming the stack, you should first see the *TI Network Developer's Kit (NDK) User's Guide* (SPRU523) to familiarize yourself with the stack libraries and with using the stack with the SYS/BIOS and Code Composer Studio™ (CCStudio) development tools.

1.1.1 Supplemental API Information

The following information appears as appendices to this document. These sections contain optional information that may be useful in understanding the low-level application interface, but is not required when developing traditional network applications.

• Appendix A Internal Stack Functions

The stack library internal function specification describes a subset of the low-level programming interface to the stack. These functions allow the application writer to make use of kernel level function APIs. As a general rule, it is not necessary to use this API for application development, although some of the sample applications included in the NDK make use of these function calls.

Appendix B Network Address Translation (NAT)

The stack library includes Network Address Translation module. This appendix describes the operational theory of NAT, and how to use the NAT functions included in the library.

Appendix C Point-to-Point Protocol (PPP)

The stack library has internal device sections for both traditional Ethernet, and PPP. The PPP module can act as PPP client, server, or both (assuming multiple interfaces). This appendix describes the operation of the PPP module, the PPP over Ethernet (PPPoE) module, and how to interface an HDLC based serial device.

Appendix D Hardware Adaptation Layer (HAL)

This appendix describes the hardware and operating system interfaces used by the stack. The information allows application programmers to call device drivers directly when needed. This appendix does not supply information about porting the HAL to a new platform.

Appendix E Web Programming with the HTTP Server

This appendix describes how to make use of the HTTP server included in the NDK. The main topics covered are adding Web content and writing CGI functions. There is also a description of the HTTP API used by CGI functions, and some CGI example applications.

Appendix F IPv6 Stack API

This appendix contains the data structure and API definitions exported by the IPv6 stack in the NDK. All IPv6 socket level APIs are also documented so that the application can use them for communication over IPv6 networks.

Appendix G Legacy Configuration Manager API

This appendix contains information about the legacy configuration API. This API was used by applications before the XGCONF configuration method was added.



Operating System Abstraction API

To keep the stack system portable, it was coded to a very compact operating system abstraction. The stack can execute in any operating environment by porting the functions described here. Most of these functions will map directly to their native OS counterpart.

If you program to this API, your applications will execute on any system to which this abstraction is ported, but more importantly, because all the NDK functions are written to this layer, the behavior of the NDK can be altered by altering the implementation of this layer. This allows the stack to be tuned in how it interfaces to the native operating system.

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2.1 Operating System Configuration

If you are using XGCONF to configure your application, you can configure several aspects of the OS behavior in the **Scheduling** tab of the Global NDK module property page. When you build the *.cfg configuration file, the data structure described in the following section is generated internally and linked into your application. See the SPRU523 (TI Network Developer's Kit (NDK) User's Guide.) and the context-sensitive help for details.

If you are not using XGCONF to configure your application, the configuration options that regulate OS behavior are stored in a data structure. The types of properties defined in the structure are those that would typically be macros, but using a data structure allows the values to be changed without rebuilding the libraries. The structure is described here for completeness, but applications should use the configuration system to make alterations to these values.

Configuration methods are described in Chapter 4.

2.1.1 Configuration Structure

This section describes a data structure that is generated automatically by the XGCONF configuration. If you are using XGCONF for configuration, you can ignore the structure described here.

The stack internal configuration structure is **_oscfg**. Any element in this structure may be modified before the system is booted. System initialization is covered later in this document.

The _oscfg structure is of type OSENVCFG, which is defined as follows:

```
// Configuration Structure
typedef struct _osenvcfg {
    uint DbgPrintLevel; // Debug message print threshold
    uint DbgAbortLevel; // Debug message sys abort threshold
    int TaskPriLow; // Lowest priority for stack task
    int TaskPriNorm; // Normal priority for stack task
    int TaskPriHigh; // High priority for stack task
    int TaskPriKern; // Kernel-level priority (highest)
    int TaskStkLow; // Minimum stack size
    int TaskStkNorm; // Normal stack size
    int TaskStkHigh; // Stack size for high volume tasks
} OSENVCFG;
```

The structure entries as defined as follows:

_oscfg.DbgPrintLevel Debug message print threshold

Default Value DBG INFO

Description This is the lowest severity level of a system debug message (call to *DbgPrintf()* function)

that will be recorded into the debug log. The threshold may be raised. The legal values for this veriable are: DRC_NEG_DRC_WARN_DRC_ERROR and DRC_Nega

for this variable are: DBG_INFO, DBG_WARN, DBG_ERROR, and DBG_None.

_oscfg.DbgAbortLevel Debug message abort threshold

Default Value DBG_ERROR

Description This is the lowest severity level of a system debug message (call to *DbgPrintf()* function)

that will result in a system shutdown (call to NC_NetStop()). The threshold may be raised. The legal values for this variable are: DBG_INFO, DBG_WARN, DBG_ERROR,

and DBG_None.



_oscfg.TaskPriLow Priority Level for Low Priority Stack Task

3 **Default Value**

Description This is the priority at which low priority stack task threads are set. Setting a thread to a

lower priority than this will not disrupt the system, but no system or service supplied in

this package will attempt it.

oscfg.TaskPriNorm Priority Level for Normal Priority for Stack Task

Default Value 5

This is the priority at which most stack task threads are set. Task threads that are Description

created by the system or services will usually run at this level.

oscfg.TaskPriHigh Priority Level for High Priority for Stack Task

7 **Default Value**

This is the priority at which high priority stack task threads are set. Setting a thread at a Description

higher priority than this may disrupt the system and cause unpredictable behavior if the thread calls any stack related functions. High priority tasks (like interrupts) can execute at higher priority levels, but should signal lower priority tasks to perform any required

stack functions.

_oscfg.TaskPriKern Priority Level of High Priority Kernel Tasks

9 **Default Value**

This is the priority that task threads execute at when they are inside the kernel. Setting **Description**

tasks to this priority level ensures that they will not be disrupted by another task calling stack functions. Note that this priority should be 2 higher than _oscfg.TaskPriHigh, to allow the scheduler thread to occupy a priority in between. The proper method of entering the kernel is to call IlEnter() and IlExit(). These functions are discussed in the

appendices, as they are not required for applications programming.

_oscfg.TaskStkLow Minimum Task Stack Size

3072 **Default Value**

Description This is the stack size used for network task that do very little network processing, or do

not use TCP.

oscfg.TaskStkNorm Normal Task Stack Size

4096 **Default Value**

Description This is the stack size used for a network task with an average network bandwidth using

TCP. It is used for the majority of network tasks in the network tools library that use

TCP.



_oscfg.TaskStkHigh High Volume Task Stack Size

Default Value 5120

Description This is the stack size used to network tasks that require a high network bandwidth using

TCP. It is also used for tasks calling HTTP CGI functions.

2.2 Task Support

The task object provides a method of manipulating task threads using a generic task handle. Task threads are executed on a priority based method, with a least-recently-run algorithm used on those with equal priority. Each task thread has its own private stack.

SYS/BIOS Users Note: Task handles created and used by this abstraction are compatible and interchangeable with SYS/BIOS Task handles.

2.2.1 Function Overview

The Task Object access functions (in functional order) are as follows:

TaskCreate() Create new task thread TaskDestroy() Destroy a task thread

TaskSelf() Get handle to current task thread
TaskExit() Exit (terminate) current task thread

TaskYield() Yield to another task thread at the same priority

TaskSleep() Block a task thread for a period of time

TaskBlock() Block a task thread

TaskSetPri() Set task thread priority level TaskGetPri() Get task thread priority level

TaskSetEnv() Assign one of three private environment handles to task thread

TaskGetEnv() Retrieve one of three private environment handles

2.2.2 Task API Functions

TaskBlock Block Task From Execution

Syntax void TaskBlock(HANDLE hTask);

Parameters

hTask Handle to target task

Return Value None.

Description Permanently blocks the specified task from execution.

Calling this function may cause a task switch.



TaskCreate Create a Task Thread

Syntax HANDLE TaskCreate(void(*pFun)(), char *Name, int Priority, uint StackSize, UINT32

Arg1, UINT32 Arg2, UINT32 Arg3);

Parameters

pFun Pointer to task entry-point function

Name NULL terminated task name (truncated after 11 characters)

Priority Task priority level (0-15)

StackSize Task stack size

Arg1 Optional task function argument 1
Arg2 Optional task function argument 2
Arg3 Optional task function argument 3

Return Value

Returns a Task Handle on success or NULL on memory failure.

Description

Creates a new task object. If successful, *TaskCreate()* returns a handle to the newly created task.

The task name supplied in *Name* is used for informational purposes only, and does not need to be unique.

The task priority specified in *Priority* determines the task thread's priority relative to other tasks in the system. The priority should not be higher than the configured value for the NDK's Global.highTaskPriLevel property (the priority for high priority NDK tasks), which is 7 by default. 0 is the lowest priority and should be reserved for an idle task. If the specified priority is negative, the task is blocked.

The task stack size specified by *StackSize* is not examined or adjusted by the create function. The size should be made compatible with the native environment (a multiple of 4 bytes should be sufficient).

Arg1 through Arg3 are optional arguments that can be passed to the calling function (they are always pushed onto the stack, but the task function need not reference them).

There is no limit to the number of tasks that can be installed in the system. The only possible failure on *TaskCreate()* is a memory allocation error.

If the priority level of the new task is higher than the priority level of the current task, the entry-point function pFun is executed immediately (before *TaskCreate()* returns to the caller).

Calling this function may cause a task switch.



TaskDestroy Destroy a Task Thread

Syntax void TaskDestroy(HANDLE hTask);

Parameters

hTask Handle to target task

Return Value None.

Description Terminates execution of the task object specified by the supplied handle *hTask*, and

frees task object from system memory. Note that memory allocated by the task thread is

not associated with the task thread and must be freed manually.

TaskExit Exit a Task Thread

Syntax void TaskExit();

Parameters None.

Return Value Does not return.

Description This function exits a task thread. It should always be called immediately before the task

entry-point function is about to return, but it may be called from anywhere.

TaskGetEnv Get Task Environment Handle

Syntax HANDLE TaskGetEnv(HANDLE hTask, int Slot);

Parameters

hTask Handle to target task

Slot Environment slot to use (1-3)

Return Value Private environment handle or NULL.

DescriptionReturns a private environment handle for the supplied task handle hTask that was previously stored with the *TaskSetEnv()* function. The slot specified in *Slot* specifies the address (1-3) of the environment handle. There are actually four slots, but slot 0 is

reserved.

NOTE: This function returns without setting or getting an environment variable if

the "slot" parameter is non-zero. All internal stack functions use slot zero.

SYS/BIOS Users Note: The OS adaptation layer (OS.LIB) implements this function for slot 0 only. The reserved slot 0 is the only slot required by the NDK. Slots 1 to 3 are not implemented. You should use the standard SYS/BIOS functions *Task_setEnv()* and

Task_getEnv() for private environment pointer storage and retrieval.



TaskGetPri Get Task Priority

Syntax int TaskGetPri(HANDLE hTask);

Parameters

hTask Handle to target task

Return Value Task priority level.

Returns the priority of the target task. See TaskSetPri() for more information on priority. Description

TaskSelf Get the Handle to the Currently Executing Task Thread

HANDLE TaskSelf(); **Syntax**

Parameters None.

Return Value Handle to currently executing thread, or NULL on error.

Returns the task handle of the currently executing task thread. This function is used Description

mainly in other task object calls where the caller wishes to operate on the current thread,

but does not know the current thread's handle.

If called on an illegal (system) thread, this function returns NULL. Only certain

implementations of the OS even have a system thread, and no user code should ever be executed on it. A NULL may also result if Task functions are called before the operating

system is initialized.

TaskSetEnv Set Task Environment Handle

void TaskSetEnv(HANDLE hTask, int Slot, HANDLE hEnv); **Syntax**

Parameters

hTask Handle to target task

Slot Environment slot to use (1-3) Private environment handle hEnv

None. **Return Value**

Description Sets and stores a private environment handle for the supplied task handle hTask. This handle can be later retrieved by TaskGetEnv(). The slot specified in Slot assigns an

address (1-3) to the environment handle. There are actually four slots, but slot 0 is

reserved.

NOTE: This function returns without setting or getting an environment variable if

the "slot" parameter is non-zero. All internal stack functions use slot zero. SYS/BIOS Users Note: The OS adaptation layer (OS.LIB) implements this function for

slot 0 only. The reserved slot 0 is the only slot required by the NDK. Slots 1 to 3 are not implemented. Application programmers should use the standard SYS/BIOS functions Task setEnv() and Task getEnv() for private environment pointer storage and retrieval.



TaskSetPri Set Task Priority

Syntax int TaskSetPri(HANDLE hTask, int Priority);

Parameters

hTask Handle to target task Priority Task priority level

Return Value Previous task priority level.

Description Sets the priority of the target task to the specified value. The priority should not be higher

than the configured value for the NDK's Global.highTaskPriLevel property (the priority for high priority NDK tasks), which is 7 by default. 0 is the lowest priority and should be reserved for an idle task. If the specified priority is negative, the task is blocked.

Calling this function may cause a task switch.

TaskSleep Sleep Task for Period of Time

Syntax void TaskSleep(UINT32 Delay);

Parameters

Delay Time (in milliseconds) of sleep

Return Value None.

Description Sleeps the calling task for a period of time as supplied in *Delay*. The sleep time cannot

be zero.

Calling this function may cause a task switch.

TaskYield Yield Execution to Another Task Thread

Syntax void TaskYield();

Parameters None.

Return Value None.

Description This function yields execution to another thread by causing a round-robin task switch

among ready task threads executing at the same priority level.

This function always causes a task switch; however, the original calling task may be the

next to execute.



www.ti.com Semaphore Support

2.3 Semaphore Support

The semaphore object provides a method of manipulating counting semaphores using a generic handle. Semaphores can be used for both task synchronization and mutual exclusion.

SYS/BIOS Users Note: Semaphore handles created and used by this abstraction are compatible and interchangeable with SYS/BIOS Semaphore handles.

2.3.1 Function Overview

The Semaphore Object access functions (in functional order) are as follows:

SemCreate() Create new semaphore SemDelete() Delete semaphore

SemPend() Wait on semaphore, optionally for a period of time

SemCount() Get the current semaphore count
SemPost() Release semaphore - increment count
SemReset() Reset semaphore and set new count

2.3.2 Semaphore API Functions

SemCreate Create New Semaphore

Syntax HANDLE SemCreate(int Count);

Parameters

Count Initial semaphore count

Return Value Handle to semaphore or NULL on error.

Description Creates a new semaphore object with an initial count.

SemCount Get Current Semaphore Count

Syntax int SemCount(HANDLE hSem);

Parameters

hSem Handle to Semaphore

Return Value Current semaphore count

Description Returns the current count of the semaphore object.



SemDelete Delete Semaphore

Syntax void SemDelete(HANDLE hSem);

Parameters

hSem Handle to Semaphore

Return Value None.

Description Deletes the semaphore object and frees related memory.

Any task currently waiting on this semaphore is blocked forever - even if it originally specified a timeout to SemPend(). With a little care in programming, this will not occur.

SemPend Wait for a Semaphore

Syntax int SemPend(HANDLE hSem, UINT32 Timeout);

Parameters

hSem Handle to Semaphore

Timeout Maximum time to wait (in milliseconds)

Return Value The function returns 1 if the semaphore was obtained, and 0 if not.

Description This function waits on a semaphore.

If the semaphore count is greater than 0, the semaphore count is decrement and this function immediately returns.

If the semaphore count is zero, the task is placed on a waiting list for the semaphore and blocked. If the semaphore becomes available in the time period specified in *Timeout*, the function returns. However, the function returns regardless once the timeout has expired. A timeout value of 0 always returns without blocking or yielding. A timeout value of BIOS_WAIT_FOREVER causes the caller to wait on the semaphore without time out.

The waiting list is first in, first out, without regard to priority. Thus, semaphores can be used to round-robin task threads at different priority levels.

Calling this function may cause a task switch (unless called with *Timeout* set to 0).



SemPost Signal a Semaphore

Syntax void SemPost(HANDLE hSem);

Parameters

hSem Handle to Semaphore

Return Value None.

Description If the semaphore count is greater than 0 (or is equal to 0, but without any pending task

threads), the semaphore count is incremented and this function immediately returns.

If the semaphore count is zero and there are tasks threads pending on it, the count

remains at zero, and the first thread in the pending list is unblocked.

Calling this function may cause a task switch.

SemReset Reset Semaphore

Syntax void SemReset(HANDLE hSem, int Count);

Parameters

hSem Handle to Semaphore
Count Initial semaphore count

Return Value None.

Description This function resets the semaphore, first setting an initial semaphore count, and then

unblocking all tasks that are pending on the semaphore.

This function should be used with care. Tasks that are pending on the semaphore may exhibit unexpected behavior because all tasks pending on the semaphore will return from their respective SemPend() calls regardless of requested timeout. The return value for the respective SemPend() calls will always be correct because one or more tasks may get the semaphore (depending on the value of Count), but tasks that called SemPend() without a timeout may assume they have obtained the semaphore without checking the SemPend() return value.

Calling this function may cause a task switch.



2.4 Memory Allocation Support

As part of normal stack operation, memory will be allocated and freed on a regular basis. It is therefore recommended that a memory support system have the ability to allocate and free small memory blocks in a variety of sizes, without memory fragmentation. The functions described here work on a memory bucket system of predefined fixed sizes. Although it allocates more memory than requested, when the memory is released, it can be reused without fragmentation.

2.4.1 Function Overview

The Memory Allocation access functions (in functional order) are as follows:

mmAlloc() Allocate Small Memory Block
mmFree() Free mmAlloc() Memory Block
mmBulkAlloc() Allocate Unrestricted Memory Block
mmBulkFree() Free mmBulkAlloc() Memory Block

mmCopy() Copy a Memory Block

mmZeroInit() Initialize a Memory Block to Zero

2.4.2 Memory Allocation API Functions

Syntax void *mmAlloc(uint size);

Return Value Pointer to allocated memory or NULL on error.

Description Allocates a memory block of at least *size* bytes in length. The function should return a

pointer to the new memory block, or NULL if memory is not available. The size of the

allocation cannot be more than 3068 bytes.

mmFree Free Memory Block

Syntax int mmFree(void *pv);

Return Value If a memory tracking error occurs, this function returns 0; otherwise, it returns 1.

Description Frees a previously allocated memory block by supplying the pointer that *mmAlloc()*

originally returned.

mmBulkAlloc Allocate Bulk Memory Block

Syntax void *mmBulkAlloc(INT32 Size);

Return Value Pointer to allocated memory or NULL on error.

Description Allocates a memory block of at least *size* bytes in length. The function returns a pointer

to the new memory block, or NULL if memory is not available. The size of the allocation

is not restricted.



mmBulkFree Free Bulk Memory Block

Syntax void mmBulkFree(void *pv);

Return Value None.

Description Frees a previously allocated memory block by supplying the pointer that *mmBulkAlloc()*

originally returned.

mmCopy Copy Memory

Syntax void mmCopy(void *pDst, void *pSrc, uint size);

Return Value None.

Description Called to copy *size* bytes of data memory from the data buffer *pSrc* to the data buffer

pDst.

mmZerolnit Zero Memory

Syntax void mmZeroInit(void *pDst, uint size);

Return Value None.

Description Called to initialize *size* bytes of data memory in the data buffer *pDst* to NULL.

2.5 Print and Debug Support

The OS abstraction includes a family of compact *printf()* functions that print using a fixed buffer. The size of the buffer (max *printf()* length) is defined in the OS abstraction layer. The code to print to the standard output device is also provided, and this function can be modified to print or log as required.

The stack also provides another form of the printf function called *DbgPrintf()*. This function prints debug messages to a global debug log. The severity threshold at which the debug message is recorded can be adjusted, as well as at what point the error causes a system shutdown.

SYS/BIOS Users Note: Under SYS/BIOS, there is a minor incompatibility between the compact *printf()* function provided here and the one supplied in the RTS library. Other than not supporting floating point, this version of *printf()* treats long values (e.g., %ld) as 32 bit quantities, not 40 bits. Thus, when using SYS/BIOS, it is best to avoid the use of %ld.

2.5.1 Standard API Functions

The standard set of printf functions is supported:

```
int printf(const char *format, ...);
int sprintf(char *s, const char *format, ...);
int vprintf(const char *format, va_list arg);
int vsprintf(char *s, const char *format, va_list arg);
```



2.5.2 Debug API Functions

DbgPrintf Print a Debug Message to the Debug Log

void DbgPrintf(int ErrLevel, char *Format, ?); **Syntax**

Parameters

ErrLevel Severity level of the error Standard printf format string Format

Return Value

None.

Description

This function prints a debug message to the global debug log buffer. The log buffer is defined as follows:

```
#define LL_DEBUG_LOG_MAX
extern char DebugLog[LL_DEBUG_LOG_MAX]; // DebugLog Buffer
extern int DebugLogSize;
                                       // Bytes of data currently in DebugLog
```

The buffer behaves like one large NULL terminated string. The contents are cleared by setting DebugLogSize to 0.

The value of ErrLevel determines if the message is printed and additionally, if the message results in a system shutdown. Both of these thresholds (printing and shutdown) are set through the OS configuration. The definition of the severity levels are as follows:

```
#define DBG INFO 1
#define DBG_WARN
#define DBG_ERROR 3
#define DBG_None 4
```

2.6 File I/O Support for Embedded Systems

The next section of this document discusses the support for stream IO that is built into the stack library. The support documented in that section is intended to augment the basic functions provided by the native operating system (in the case where the stack is ported to a new environment).

This section details functionality required by the Network Tools services interfacing with File IO. The functionality described here is more likely to have a local counterpart. The API described in this section must be ported to allow the network services that use it to operate.

The API described here was taken from the Unix standard. The names of the functions have been prefixed with the designation efs , which stands for embedded file system. This was done so that the functions would not conflict with any existing file system. The EFS API is a very simple RAM based file system. A couple of new functions are included that allow the creation of RAM files by supplying pointers to static data buffers. For systems with existing file structures, most of the functions in this API become secondary to their standard IO counterparts.

NOTE: This API is unrelated to the stream API provided for Sockets. If the services that need this API are not required, then this module can be discarded from the OS abstraction. Currently, only the HTTP Server service uses this API.



2.6.1 Function Overview

The following functions are custom to this implementation, but can be ported:

efs_createfile() Create (declare) RAM based file

efs_createfilecb() Create (declare) RAM based file (with callback function)

efs_destroyfile() Destroy RAM based file efs_getfilesize() Get the length of file data

efs_filecheck() Check the file type and authorization efs_filesend() Send file contents directly to a socket

efs_loadfunction() Load executable file and return entry-point function

As previously mentioned, most of the API closely matches its standard C counterpart:

efs fclose() Close file

efs_feof() Check for end of file

efs_fopen()

efs_fread()

efs_fread()

efs_fseek()

efs_ftell()

efs_fwrite()

Open file

Read from file

Set file position

Get file position

Write to file

efs_rewind() Reset file position to start of file

2.6.2 EFS Custom API Functions

efs createfile Create (declare) a RAM Based File

Syntax void efs_createfile(char *name, INT32 length, UINT8 *pData);

Parameters

name Filename (maximum length of EFS FILENAME MAX)

length Length of file data pData Pointer to file data

Return Value None.

Description This function creates an internal record of the RAM based file with the indicated

filename, file length, and data pointer. The file data is not copied, so the buffer must be

statically allocated. The filename is copied, so it does not need to be static.

A static buffer based system is more efficient for embedded systems because the data must already be present in RAM or ROM. However, the <code>efs_createfile()</code> function could easily be altered to use allocated buffers that are later freed when <code>efs_destroyfile()</code> is called. These create and destroy functions are only called by the sample application code, and thus the system programmer is free to alter the operation of these functions so long as they create files that are compatible with the rest of this API.



efs_createfilecb Create (declare) a RAM Based File with Callback

Syntax void efs_createfilecb(char *name, INT32 length, UINT8 *pData, EFSFUN pcbFreeFun,

UINT32 FreeArg);

Parameters

name Filename (maximum length of EFS_FILENAME_MAX)

length Length of file data
pData Pointer to file data
pcbFreeFun Pointer to file data
FreeArg Pointer to file data

Return Value

None.

Description

This is identical to *efs_createfile()*, except that is takes two additional arguments, a pointer to a file free function, and a 32 bit argument. It is designed to be used in system where the memory used for the file is allocated, and not static.

The EFS file system tracks the numbers of references to a particular file. When the <code>efs_destroyfile()</code> function is called to destroy a file, the file is marked so that it can no longer be opened, but open handles to the file remain valid until closed by their respective application. The free function callback calls back to the file creator when the last file handle to the file has been closed, allowing the creator to safely reclaim any memory associated with the file. The argument FreeArg is used as a calling parameter to the callback.

efs_destroyfile

Destroy (remove declaration from) a RAM Based File

Syntax

void efs_destroyfile(char *name);

Parameters

name

Filename (maximum length of EFS FILENAME MAX)

Return Value

None.

Description

This function deletes the internal file record associating the filename with the static data pointer as originally passed to *efs_createfile()*.

A static buffer based system is more efficient for embedded systems because the data must already be present in RAM or ROM. However, the <code>efs_createfile()</code> function could easily be altered to use allocated buffers that are later freed when <code>efs_destroyfile()</code> is called. These create and destroy functions are only called by the sample application code, and thus the system programmer is free to alter the operation of these functions so long as they create files that are compatible with the rest of this API.



efs_getfilesize Get the Length of a File

Syntax INT32 efs_getfilesize(EFS_FILE *stream);

Parameters

stream Pointer to open stream (file)

Return Value File size in bytes.

Description This function returns the length in bytes of the indicated file. The file must already have

been opened via a call to efs_fopen().

efs_filecheck Check the file type and authorization

Syntax int efs_filecheck(char *name, char *user, char *password, int *prealm);

Parameters

name Filename (NULL terminated string)
user Username (NULL terminated string)
password Password (NULL terminated string)

prealm Pointer to receive realm Index (if authentication fails)

Return Value An integer consisting of one or more of the following flags:

EFS_FC_NOTFOUND File not found

EFS_FC_NOTALLOWED File cannot be accessed

EFS_FC_EXECUTE Filename represents a function call (CGI)

EFS_FC_AUTHFAILED File authentication failed (failing realm Index supplied)

Description

This function is called by a file server (e.g., HTTP) on a particular filename (provided in *name*), to retrieve the file type, and authenticate user access. The user credentials are supplied in the user and password calling parameters.

The user and password arguments must always be valid pointers, but can be NULL strings.

When user authentication fails, the Index of the failing authentication realm (1 to 4) is written to the address supplied in *prealm*.



efs_filesend Send file contents directly to a socket

Syntax size_t efs_filesend(EFS_FILE *stream, size_t size, SOCKET s);

Parameters

stream Pointer to open stream (file)

size Number of bytes to transfer from the file s Socket onto which to send the file data

Return Value Returns the number of bytes transferred, **NULL** on an error.

DescriptionThis function is called by a file server (e.g., HTTP) on a particular file stream (provided in *stream*), to read data from the file and send it to socket s. Because EFS file systems are

typically RAM based, this custom function can send the file to socket s more efficiently

than an application that has to call efs_read() and then send().

The number of bytes to transfer is given by size. Transfer begins and the current file

pointer location, and the file pointer is advanced by this call.

efs_loadfunction Load Executable File and Return Entry-point

Syntax EFSFUN efs_loadfunction(char *name);

Parameters

name Filename (maximum length of EFS_FILENAME_MAX)

Return Value Pointer to executable function.

Description This function loads an executable file and returns a pointer to the entry-point function.

The type EFSFUN is declared as:

typedef void (*EFSFUN)();

The application is really free to treat this function in whatever manner is required. This executable file is created with a call to *efs_createfile()* where the *pData* parameter points to a function that is already loaded in memory. This allows the HTTP server to call

services contained in CGI files.

A static buffer based system is more efficient for embedded systems because the data must already be present in RAM or ROM. However, the HTTP can be made to work with

physical CGI files by porting this function to load CGI.





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2.6.3 EFS Standard API Functions

efs fclose Close File

Syntax int efs fclose(EFS FILE *stream);

Parameters

stream Pointer to open stream (file)

Return Value Returns EOF if any errors occurred, and zero otherwise.

Description This function performs a logical close on an open file. It is functionally equivalent to

fclose().

efs_feof Test for End of File

Syntax int efs_feof(EFS_FILE *stream);

Parameters

stream Pointer to open stream (file)

Return Value Returns non-zero if EOF has been reached, and zero otherwise.

Description This function tests to see is the file position has reached the end of the file. It is

functionally equivalent to feof().

efs_fopen Open File

Syntax EFS_FILE *efs_fopen(char *name, char *mode);

Parameters

name Name of file to open mode Desired mode of open file

Return Value Returns a stream pointer or NULL on error.

Description This function performs a logical open on the named file and returns a stream or NULL if

the attempt fails. It is functionally equivalent to fopen().

The mode parameter determines the mode for which the file is opened. In the embedded

file system version of this function, the list of supported modes is quite simple:

rb - open binary file for reading

The flags are still passed through to ensure compatibility with a full file system.



eis ireau — Reau from a File	efs	fread	Read from a File
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Syntax size_t efs_fread(void *ptr, size_t size, size_t nobj, EFS_FILE *stream);

Parameters

ptr Pointer to data buffer to receive data

size Size in bytes of a read object nobj Number of objects to read stream Pointer to open stream (file)

Return Value Returns the number of objects read.

Description This function reads from the indicated *stream* in the array *ptr* at most *nobj* objects of a

length specified by size. It returns the number of objects read; this may be less than the

number of objects requested. It is functionally equivalent to *f read()*.

efs_feof() can be used to detect end of file.

efs_fseek Set File Position

Syntax INT32 efs_fseek(EFS_FILE *stream, INT32 offset, int origin);

Parameters

stream Pointer to open stream (file)
offset Offset of desired new position
origin Base reference point for offset

Return Value Returns non-zero on error.

Description This function sets the file position of the indicated *stream* to that specified by *offset* from

a base reference point specified by *origin*. It is functionally equivalent to *fseek()*.

The *origin* parameter can be set to one of the following:

EFS_SEEK_SET - Position by offset from the beginning of the file

EFS_SEEK_CUR - Position by offset from the current position

EFS_SEEK_END - Position by offset from the end of the file

efs ftell Get File Position

Syntax INT32 efs_ftell(EFS_FILE *stream);

Parameters

stream Pointer to open stream (file)

Return Value Returns file position or -1 on error.

DescriptionThis function returns the current file position of the indicated stream. It is functionally

equivalent to ftell().



efs_fwrite	Write to a File
Syntax	size_t efs_fwrite(void *ptr, size_t size, size_t nobj, EFS_FILE *stream);
Parameters	
ptr	Pointer to data buffer to receive data
size	Size in bytes of a read object
nobj	Number of objects to read
stream	Pointer to open stream (file)
Return Value	Returns the number of objects written (0).
Description	This function writes to the indicated stream from the array <i>ptr</i> , up to <i>nobj</i> objects of a length specified by <i>size</i> . It returns the number of objects written; this may be less than the number of objects requested on an error. It is functionally equivalent to <i>fwrite()</i> .
	Nothing in the stack package requires write capability, thus this function always returns zero.
efs_rewind	Reset File Position to Start of File
Syntax	void efs_rewind(EFS_FILE *stream);
Parameters	
stream	Pointer to open stream (file)
Return Value	None.
Description	This sets the position of the indicated <i>stream</i> to zero, and clears any current error.

2.7 **Interrupt Management Support**

The Interrupt Manager defines the APIs and data structures required to configure and manage interrupts in a generic way. This wrapper hides the OS specific implementation details of interrupt management by providing a unified API to do the same.

(Errors are not tracked in this implementation.)

The NDK interrupt manager implementation provided in NDK uses SYS/BIOS as its underlying OS. It uses SYS/BIOS Hwi and EventCombiner module APIs in turn to configure the interrupts.

Depending on the system, there could be multiple or just a single system event defined for the peripheral events. Based on the same, one could register a single interrupt and interrupt service routine (ISR) for their module's events or register separate ones for each of the events. If two or more system events are mapped to the same interrupt number, then they are termed as combined interrupts and are handled separately by the interrupt manager.



2.7.1 Configuration Structure

The NDK driver or application that wishes to configure interrupts would need to use the following "IntSetup" structure to pass the interrupt configuration information to the Interrupt manager module. All the APIs exported by this module reference this structure to retrieve interrupt configuration info.

```
/**
* @brief
* The structure describes the interrupt setup object defined by
* the interrupt management wrapper in OS Abstraction Layer.
* @details * This structure can be used by a driver/such in setting up
 * interrupts using the underlying OS (BIOS) constructs without
* having to know the details of the OS specific calls. All calls
* to the interrupt management wrapper require a handle to
* the structure described below.
typedef struct _IntSetup
     * @brief HWI Object number to use for setting up this
               system event. The valid values for this range
               between 4 - 15 (both inclusive).
     Uint8
               intVectId;
    /**
     * @brief System Event number(s) for which the
               interrupts need to be setup. The valid values
               for this range between 4 - 127 (both inclusive).
     * /
     Uint8
               sysEvtId[MAX_NUM_SYSEVENTS];
     * @brief Number of system events that need to be mapped
               to a given interrupt number and be serviced by
               a specified Interrupt Service Routine (ISR).
               Valid values for this range between 1 - 128.
     * /
     Uint8
               sysEvtCount;
     * @brief The callback function to be triggered when the
               interrupt occurs, i.e. the ISR. This should not be
               set to NULL for a successful interrupt setup.
     * /
     void
               (*pCallbackFxn)(void* pCallbackArg);
     \mbox{\scriptsize *} @brief \, The arguments that need to be passed to the ISR.
               Can be NULL.
     * /
     void*
               pCallbackArg;
     * @brief Flag to indicate whether to enable/disable the
               interrupt by default. This flag is valid only
               when setting up combined interrupts, i.e.,
               multiple system events mapped to a single
               interrupt number.
     * /
               bEnable;
     Uint8
} IntSetup;
```



The structure entries are defined as follows:

intVectId The interrupt number to use for this interrupt.

Description The interrupt number to use for this system event. The range of valid values is

hardware-dependent. For example, for C6000 targets, the intVectId can range from 4-14.

sysEvtId Array of system event numbers that map to the given interrupt vector.

Description One or more of the 128 system events can be mapped to a single interrupt line in the

system. This array holds all the system events that are mapped to the specified interrupt vector number. The valid values for the system event numbers that can be specified in this array are 4 - 127 (both inclusive). The system events 0 - 3 are used by the

EventCombiner module in setting up combined interrupts and hence cannot be used by

an application for individual masked interrupts.

sysEvtCount Number of system events configured in the sysEvtId array.

Description Number of system events that are configured in the sysEvtId array and are to be

mapped to the interrupt vector number specified in this structure.

pCallbackFxn Handle to the ISR that needs to be invoked when this interrupt occurs.

Description This holds a pointer to the user specified callback function or ISR that needs to be

invoked when the specified interrupts occurs in the system. This should be set to a non

NULL value for a successful interrupt setup.

pCallbackArg Arguments that need to be passed back to the ISR.

Description Any arguments that need to be passed back to the ISR as a part of its context can be

specified here. This can be omitted or set to NULL if no context information needs to be

passed back to ISR when the interrupt occurs.

bEnable Flag to enable or disable the interrupt by default.

Description This flag is valid only while setting up combined interrupts, i.e., one or more system

events mapped to a single SYS/BIOS interrupt number. This indicates whether the configured interrupt is to be enabled or disabled by default when added to the system.

2.7.2 Function Overview

The interrupt configuration functions exported by the manager are as follows:

Interrupt_add Configure a new interrupt in the system using the underlying OS constructs

(SYS/BIOS).

Interrupt_delete Remove a previously configured interrupt Interrupt_enable Enable the interrupt and make it active Disable the interrupt in the system



2.7.3 Interrupt Manager API Overview

Interrupt_add Configure a new interrupt in the system.

Syntax Uint32 Interrupt_add(IntSetup* myIntSetup);

Parameters

myIntSetup Handle to the interrupt setup structure configured by the driver or application.

Return Value Returns 0 on success and 1 on error.

Description This function validates the interrupt configuration parameters passed by the

application/driver and sets up the interrupt using the underlying OS interrupt management constructs (SYS/BIOS's Hwi and EventCombiner module constructs here).

It enables/disables the interrupt too based on the input for combined interrupts.

Interrupt_delete Removes a previously configured interrupt.

Syntax Uint32 Interrupt_delete(IntSetup* myIntSetup);

Parameters

myIntSetup Handle to the interrupt setup structure configured by the driver or application.

Return Value Always returns 0.

Description This function can be used to implement the logic required to remove any previously

configured interrupts in the system. SYS/BIOS does not define any constructs to remove interrupts. Hence, this function is currently a placeholder and does nothing. It always

returns success.

Syntax int32 Interrupt_enable(IntSetup* myIntSetup);

Parameters

myIntSetup Handle to the interrupt setup structure configured by the driver or application.

Return Value Returns 1 on error and 0 on success.

Description This function validates the input parameters and enables the interrupts using SYS/BIOS

APIs. This function is only applicable for combined interrupts, i.e., interrupts where

multiple system events are mapped to a single interrupt.



Syntax Uint32 Interrupt_disable(IntSetup* myIntSetup);

Parameters

myIntSetup Handle to the interrupt setup structure configured by the driver or application.

Return Value Returns 1 on error and 0 on success.

Description This function validates the input parameters and disables the interrupts using SYS/BIOS

APIs. it is only applicable for combined interrupts, i.e., interrupts where multiple system

events are mapped to a single interrupt.

For an illustration of the interrupt configuration using Interrupt Manager APIs for any C64x+ devices, see the sample Ethernet driver code packaged in the NDK Support Package (NSP) for your target. The Embedded Software Download Page provides links to download the NSP. The Embedded Software Download Page provides a link to download the NSP for the OMAP-L138. Other NSPs are provided as part of the SDK for that development platform.



Sockets and Stream IO API

This chapter describes the socket and file API functions.

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3.1 File Descriptor Environment

In most embedded operating system environments, support for file descriptors varies greatly. In most cases, only the bare minimum functionality is provided, and trimmed down support functions are provided using the common reserved names (read(), write(), close(), etc.).

As this stack supports the standard sockets interface functions, and these functions require file descriptor support, the stack provides its own small file system. This section describes the basic mechanics of the file system.

3.1.1 Organization

The basic building block of the stack code internally is an object handle. Internally to the stack, both sockets and pipes are addressed by object handles. However, at the application level, sockets and pipes are treated as file descriptors. The file descriptor contains additional state information allowing tasks to be blocked and unblocked based on socket activity.

The stack API supports the use of file descriptors by adding a file descriptor layer of abstraction to the native operating environment. This layer implements the standard sockets and file IO functions. The stack works by associating a file descriptor session with each caller's thread (or in this terminology, task). In this system, each task has its own file descriptor session. The file descriptor session is used when the task needs to block pending network activity.

Note that although file descriptors can be used in classic functions like *select()*, in this implementation, they are still handles, not integers. For compatibility, network applications must use the NDK header files, and use INVALID_SOCKET for an error condition (not -1), and refrain from comparing sockets as <0 when checking for validity.

3.1.2 Initializing the File System Environment

To use the file system and socket functions provided by the stack, a task must first allocate a file descriptor table (called a file descriptor session). This is accomplished at the application layer by calling the file descriptor function fdOpenSession().

When the task is finished using the file descriptor API, or when it is about to terminate, the function *fdCloseSession()* is called.

3.1.2.1 When to Initialize the File Descriptor Environment

For correct stack operation, a task thread must open a file descriptor session before calling any file descriptor related functions, and then close it when it is done.

The simplest way to handle the session is for the task to open a file session when it starts, and close the session when it completes. For example:

Socket Task:

```
void socket_task(int IPAddr, int TcpPort)
{
    SOCKET s;

    // Open the file session
    fdOpenSession(TaskSelf());

    < socket application code >

    // Close the file session
    fdCloseSession(TaskSelf());
}
```

A second option is for the task that creates the socket task thread to open the file descriptor session for the child thread. Note that the parent task must guarantee that the child task's file session is open before the child task executes. This is done via task priority or semaphore, but can complicate task creation. Therefore, it is not the ideal approach.



A third, more common, option is to allow a child task to open its own file session, but allow the parent task to monitor its children and eventually destroy them. Here, the parent task must close the file session of the child task threads it destroys. The child task then blocks when finished instead of terminating its own thread. The following example illustrates this concept:

Child Socket Task:

```
void child_socket_task(int IPAddr, int TcpPort)
{
    SOCKET s;

    // Open the file session
    fdOpenSession(TaskSelf());

    < socket application code >

    // We are done, but our parent thread will close
    // our file session and destroy this task, so here
    // we just block.
    TaskBlock(TaskSelf());
}
```

The parent task functions would look as follows:

Parent Task Functions:

```
void create_child_task()
{
    // Create System Tasks

    // Create a child task
    hChildTask = TaskCreate(&child_socket_task, ?);
}

void destroy_child_task()
{
    // First close the child's file session
    // (This will close all open files)
    fdSessionClose(hChildTask);

    // Then destroy the task
    TaskDestroy(hChildTask);
}
```

3.2 File Descriptor Programming Interface

The purpose of supporting a file system is to support the sockets API. Unfortunately, the sockets API is not a complete IO API, as it was originally designed to integrate into the Unix file system. Thus, several file descriptor functions that are important for application programming are not really socket calls at all. The stack library supports a handful of what are normally considered file functions, so that sockets applications can be programmed in a more traditional sense. So that these functions will not conflict with any other file functions in the system, their names have been altered slightly from the standard definitions.

3.2.1 Function Overview

The stream IO object can take two forms. In the vast majority of cases, it will be in the form of a local file descriptor. The following functions can operate on file descriptors:

fdOpenSession()	Open file descriptor support session
fdCloseSession()	Close file descriptor support session
fdClose()	Flush stream and close file descriptor (same as standard close())
fdError()	Return last error value (same as standard error)
fdPoll()	Wait on a list of file descriptor events (same as standard poll())
fdSelect()	Wait on one or more file events (same as standard select())





Aborts calls to fdSelect() and fdPoll() with forced timeout condition fdSelectAbort() fdStatus() Get the current status of a file descriptor (similar to ioctl/FIONREAD)

fdShare() Add a reference count to a file descriptor

The fdSelect() function uses file descriptor sets to specify which file descriptors are being checked for activity and which have activity detected. There is a small set of MACRO functions for manipulating file descriptor sets. These include the following:

FD_SET() Add a file descriptor to a file descriptor set FD_CLR() Remove a file descriptor from a file descriptor set

FD_ISSET() Test to see if a file descriptor is included in a file descriptor set

FD COPY() Copy a file descriptor set

FD_ZERO() Clear (initialize) a file descriptor set

3.2.2 File Descriptor API Functions

fdOpenSession Open File Descriptor Session

Syntax int fdOpenSession(HANDLE hTask);

Parameters

hTask Task Thread Handle

Return Value 1 on success or 0 on error. An error return indicates that a session is already open for

the specified task, or that a memory allocation error has occurred.

This function opens a file descriptor session on a task thread so that the task can begin Description

using file descriptor and other stream IO functions.

A task thread normally calls fdOpenSession() when it is first created, and

fdCloseSession() before it exits. Use of these functions was described in more detail in

the previous section.

fdCloseSession Close File Descriptor Session

Syntax void fdCloseSession(HANDLE hTask);

Parameters

hTask Task Thread Handle

Return Value None.

This function closes a file descriptor session that was previously opened with Description

fdOpenSession(). When called, any remaining open file descriptors are closed.

A task thread normally calls fdOpenSession() when it is first created, and

fdCloseSession() before it exits. Use of these functions was described in more detail in

the previous section.



fdClose Close File Descriptor

Syntax int fdClose(HANDLE fd);

Parameters

fd File Descriptor to close (compatible with type SOCKET)

Return Value 0 on success or -1 on error. When an error occurs, the error type can be obtained by

calling fdError() (error is also equal to this function).

Description This function closes the indicated file descriptor.

fdError Get the Last File Error

Syntax int fdError();

Description This function returns the last file error that occurred on the current task. In the

SERRNO.H header file, error is equal to this function.

NOTE: The error code returned via *fdError()* is stored in the file descriptor session associated with a task. If a task calls a file or socket function before it opens a file descriptor session, an error condition results.

However, no error code can be stored for retrieval by fdError() because

the file descriptor session does not exist to hold it.



fdPoll

Wait on a List of File Descriptor Events

Syntax

int fdPoll(FDPOLLITEM items, uint itemcnt, INT32 timeout);

Parameters

items Pointer to a list of descriptor events of type FDPOLLITEM itemcnt Number of entries in *items* list Function timeout in milliseconds

Return Value

Returns the number of file descriptors in the items list for which the *eventsDetected* field is non-zero.

Returns SOCKET_ERROR if the caller has not opened a file descriptor session (with fdOpenSession()).

Returns zero (0) under any of the following conditions:

- · No detected flags and time out has occurred
- No detected flags and a fdSelectAbort() was issued
- · No detected flags and an internal resource allocation failed

Description

The fdPoll() function is a more efficient alternative to the fdSelect() function. It polls the supplied list of sockets, with a timeout specified in milliseconds (or POLLINFTIM for infinite timeout). It has the advantage over fdSelect() because the original list of file descriptors (or sockets) to be examined is not overwritten by the results, and thus can be used multiple times without reconstruction.

The list of file descriptors to check is provided in the *items* array. The array is of type FDPOLLITEM, which is defined as follows:

```
typedef struct _fdpollitem {
          HANDLE     fd;
          UINT16     eventsRequested;
          UINT16     eventsDetected;
} FDPOLLITEM;
```

The FDPOLLITEM entry contains a file descriptor (or socket) to check, a set of flags for requested events that is initialized by the application, and a set of resulting flags for a detected event that is initialized by the *fdPoll()* function.

The entry *fd* is the file descriptor to check. If fd is set to INVALID_SOCKET, or the *eventsRequested* field is NULL, the item entry is ignored. However, the *eventsDetected* field is still reset to zero.

The same file descriptor should not appear twice in the list, instead the event flags should be combined on a single entry. (Duplicate descriptors will not cause an error, but will increase system load.)

Valid flags for eventsRequested are one or more of the following:

- POLLIN Socket readable (or read error pending)
- POLLOUT Socket writable (or send error pending)
- POLLPRI Socket OOB readable (or error pending)
- POLLNVAL Socket or request type invalid

Valid flags for *eventsDetected* are the same as above, where all detected conditions are indicated. (Note that POLLNVAL can be set whether or not it was requested in *eventsRequested*.)



fdSelect Wait on one or multiple File Events

Syntax int fdSelect(int maxfd, fd_set *readset, fd_set *writeset, fd_set *exceptset, struct timeval

*timeout);

Parameters

maxfd Ignored

readset Set of file descriptors to check for reading writeset Set of file descriptors to check for writing

exceptset Set of file descriptors to check for exceptional conditions (OOB data)

Pointer to timeval structure of time to wait (or NULL) timeout

Return Value

Returns a positive count of ready descriptors (combined from all three possible sets), 0 on timeout, or -1 on error. When an error occurs, the error type can be obtained by calling fdError().

Description

This function allows the task to instruct the stack to wait for any one of multiple events to occur and to wake up the process only when one of more of these events occurs or when a specified amount of time has passed.

The definition of the timeval structure is:

```
struct timeval {
    INT32
           tv_sec;
    INT32
            tv_usec;
```

Passing in a NULL pointer for timeout specifies an infinite wait period. Passing a valid pointer to a timeval structure with both tv sec and tv usec set to zero specifies that the function should not block.

NOTE: This function is less efficient than *fpPoll()*. In fact, the *fdSelect()* function calls fdPoll() after rearranging the descriptor sets into a fdPoll() descriptor list.



fdSelectAbort

Terminate a Previous Call to fdSelect() or fdPoll()

Syntax

void fdSelectAbort(HANDLE hTask);

Parameters

hTask

Handle to the task thread that is blocked in fdSelect() or fdPoll()

Return Value

None.

Description

This function aborts a call to <code>fdSelect()</code> or <code>fdPoll()</code> on the specified target thread by simulating a timeout condition (even when no timeout was originally specified). It can be used to wake a thread using a different method than socket or pipe activity. It is useful in callback functions where the handle to the target task thread is known, but where socket calls cannot be easily used.

The return value from the fdSelect() or fdPoll() function called on the target thread is still valid. In other words, if there is pending file descriptor activity, it will still be returned to the caller. However, if the target task thread is blocked in fdSelect() or fdPoll() at the time of the call, the most likely return value is zero for no activity.

If the target thread is not currently pending on a call to <code>fdSelect()</code> or <code>fdPoll()</code>, any subsequent call will be affected. Thus, the target thread is guaranteed to see the abort (although it may be accompanied by actual socket activity). So there is no race condition on calling <code>fdSelectAbort()</code> immediately prior to the target task thread calling <code>fdSelect()</code> or <code>fdPoll()</code>.



fdStatus Get the Current Status of a File Descriptor

Syntax int fdStatus(HANDLE fd, int request, int *results);

Parameters

fd File descriptor (socket or pipe) to check

request Status request type.

hTask Pointer to where status results are written

Return Value

0 on success or -1 on error. When an error occurs, the error type can be obtained by calling *fdError()* (*errno* is also equal to this function).

Description

This function reads current status information about the file descriptor. The descriptor can be either a socket or a pipe object. The following describes the value written to results for the various request types and descriptor types:

request = FDSTATUS_TYPE;

The *results* pointer is written with the file descriptor type. It will be one of the following values:

- FDSTATUS_TYPE_SOCKET The file descriptor is a socket.
- FDSTATUS_TYPE_PIPE The file descriptor is a pipe.
- request = FDSTATUS_RECV;

On listening sockets, the *results* pointer is written with:

- -1 There is an error pending on the socket.
- 0 There are no connections ready to be accepted.
- 1 There is at least one connection ready to be accepted.

On data sockets, the *results* pointer is written with:

-1 - There is an error pending, or a call to recv() will result in an error.

NOTE: On a TCP socket, this return value can also indicate that the peer connection has been closed and all available data has been read. In

this case, a subsequent call to recv() will return NULL, not error.

<0 to n> - The number of bytes that can be read using recv() without blocking.

- request = FDSTATUS SEND;
 - On listening sockets, the *results* pointer is written with:
 - -1 A listening socket can never be written.

On TCP (non-ATOMIC) data sockets, the results pointer is written with:

- -1 There is an error pending, or a call to send() will result in an error.
- <0 to n> The number of bytes that can be written using send() without blocking.

On UDP/RAW (ATOMIC) data sockets, the *results* pointer is written with:

- -1 There is an error pending, or a call to send() will result in an error.
- <0 to n> The maximum number of bytes that can be written using a single send() call.



fdShare Add a Reference Count to a File Descriptor

Syntax int fdShare(HANDLE fd);

Parameters

fd File descriptor to share (compatible with type SOCKET)

Return Value Returns zero on success or -1 on error.

Description This is an optional function for applications that use descriptor sharing. It increments a

reference count on the target descriptor, which is then decremented when the application calls *fdClose()*. It allows the descriptor to be shared among multiple tasks, each calling *fdClose()* when they are done, and the file descriptor is only closed by the final call. (Note that file descriptors are created with a reference call of 1, meaning that

the first call to fdClose() will close the descriptor.)

For example, fdShare() is useful in a case where Task A opens a session and calls recv() in a loop on a socket. Task B has a loop that calls send() on the same socket. The call to send() from Task B will fail and then fdError() will return -1 if you do not call fdOpenSession() and then fdShare() from the second Task after the first Task has

opened the socket.

For an example that calls fdShare(), see the contest.c file in the <NDK_INSTALL_DIR>\packages\ti\ndk\tools\console directory.

3.2.3 File Descriptor Set (fd_set) Macros

FD_SET Add a File Descriptor to a File Descriptor Set

Syntax void FD_SET(HANDLE fd, fd_set *pFdSet);

Parameters

fd File descriptor to add (compatible with type SOCKET)

pFdSet Pointer to fd_set data type

Return Value Should be treated as a void function. The true return value is dependent on the

implementation of the macro.

Description This function adds a file descriptor to a file descriptor set, typically before using the set in

a call to fdSelect(). Note that after declaring a fd set data type, it should be initialized

using FD_ZERO() before attempting to set individual file descriptors.



FD_CLR Remove a File Descriptor From a File Descriptor Set

Syntax void FD_CLR(HANDLE fd, fd_set *pFdSet);

Parameters

fd File descriptor to remove pFdSet Pointer to fd_set data type

Return Value Should be treated as a void function. The true return value is dependent on the

implementation of the macro.

Description This function removes a file descriptor from a file descriptor set, typically after the file

descriptor has been processed in a loop that continuously checks a file descriptor set.

FD_ISSET Test to See if a File Descriptor is Included in a File Descriptor Set

Syntax void FD_ISSET(HANDLE fd, fd_set *pFdSet);

Parameters

fd File descriptor to check (compatible with type SOCKET)

pFdSet Pointer to fd_set data type

Return Value Returns an int value that should be treated as a TRUE/FALSE condition.

Description This function returns TRUE if the supplied file descriptor is contained in the indicated file

descriptor set. This function is typically called after a call to fdSelect() to determine on

what file descriptors select has detected activity.

FD COPY Copy a File Descriptor Set

Syntax void FD_COPY(fd_set *pFdSetSRC, fd_set *pFdSetDST);

Parameters

pFdSetSRC Pointer to fd_set to copy

pFdSetDST Pointer to fd_set to write copied data

Return Value None.

Description This function is called to make a copy of a file descriptor set. This is typically done if a

set needs to be modified, but this original information needs to be maintained.



FD_ZERO Clear (Initialize) a File Descriptor Set

Syntax void FD_ZERO(fd_set *pFdSet);

Parameters

pFdSet Pointer to fd_set to initialize

Return Value None.

Description This function is called to clear all bits in a file descriptor set. This should be the first call

made on a newly declared fd set variable.

3.3 Sockets Programming Interface

The socket function API supported by the stack library is consistent with the standard Berkeley sockets API. No parameter adjustments are required. This section only covers the IPv4 (AF_INET) family Sockets. For details on IPv6 sockets, see Appendix F of this document. Similarly, for details on Raw Ethernet Sockets, see Section A.17 of this document.

Two new types are defined for the socket function declarations:

typedef struct sockaddr SA;
typedef struct sockaddr *PSA;

3.3.1 Enhanced No-Copy Socket Operation

Any performance of any data stream operation suffers when data copies are performed. Although the stack software is designed to use a minimum number of data copies, memory efficiency and API compatibility sometimes require the use of data copy operations.

By default, neither UDP nor RAW sockets use send or receive buffers. However, the sockets API functions recv() and recvfrom() require a data buffer copy because of how the calling parameters to the functions are defined. In the stack library, two alternative functions (recvnc()) and recvncfrom()) are provided to allow an application to get received data buffers directly without a copy operation. When the application is finished with these buffers, it returns them to the system via a call to recvncfree().

By default, TCP uses both a send and receive buffer. The send buffer is used because the TCP protocol can require reshaping or retransmission of data due to window sizes, lost packets, etc. On receive, the standard TCP socket also has a receive buffer. This coalesces TCP data received from packet buffers. Coalescing data is important for protocols that transmit data in very small bursts (like a telnet session).

For TCP applications that get data in large bursts (and tend not to use flags like MSG_WAITALL on receive), the receive buffer can be eliminated by specifying an alternate TCP stream type of SOCK_STREAMNC (see <code>socket()</code>). Without the receive buffer, there is at least one less data copy because TCP will queue up the actual network packets containing receive data instead of copying it into a receive buffer.

Care needs to be taken when eliminating the TCP receive buffer. Here large amounts of packet buffers can be tied up for a small amount of data. Also, because packet buffers come from the HAL, there may be a limited supply available. If the MSG_WAITALL flag is used on a recv() or recvfrom() call, it is possible for all packet buffers to be consumed before the specified amount of payload data is received. This would cause a deadlock situation if no socket timeout is specified.

Although TCP sockets that use the SOCK_STREAMNC stream type are 100% compatible with the standard TCP socket type, they can also be used with the <code>recvnc()</code> and <code>recvncfrom()</code> functions that UDP and RAW sockets use to eliminate the final data copy from the stack to the sockets application. Using the no copy functions with SOCK_STREAMNC eliminates two data copies from the standard TCP socket. Note that when <code>recvnc()</code> and <code>recvncfrom()</code> are used with TCP, out of band data is not supported. If the SO_OOBINLINE socket option is set, the out of band data is retained, but the out of band data mark is discarded. If not using the inline socket option, the out of band data is discarded.



3.3.2 Function Overview

The standard socket access functions are as follows:

accept() Accept a connection on a socket

bind() Bind a name to a socket

connect() Initiate a connection on a socket

getpeername() Return name (address) of connected peer getsockname() Return the local name (address) of the socket

getsockopt() Get the value of a socket option

listen() Listen for connection requests on a socket

recv() Receive data from a socket

recvfrom() Receive data from a socket with the senders name (address)

send() Send data to a connected socket

sendto() Send data to a specified destination on an unconnected socket

setsockopt() Set the value of a socket option shutdown() Close one half of a socket connection

socket() Create a socket

socketpair() Create socket pair (redundant; see Section 3.5, Full Duplex Pipes

Programming Interface

The enhanced socket functions are as follows:

recvnc() Receive no-copy data from a socket

recvncfree() Free buffer obtained from recvnc() or recvncfrom()

recvncfrom() Receive no-copy data from a socket with the senders name (address)



3.3.3 Sockets API Functions

accept Accept a Connection on a Socket

Syntax SOCKET accept(SOCKET s, PSA pName, int *plen);

Parameters

s Socket

pName Name (address) of connected peer

plen Pointer to size of pName

Return Value If it succeeds, the function returns a non-negative integer that is a descriptor for the

accepted socket. Otherwise, a value of INVALID SOCKET is returned and the function

fdError() can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

ECONNABORTED Listening socket has been shut down for read operations.

EMFILE The file descriptor table is full. ENOMEM Memory allocation error.

ENOTSOCK The descriptor does not reference a socket.

EINVAL listen() has not been called on the socket or name arguments are invalid.

EWOULDBLOCK Socket is marked non-blocking and no connections are ready

Description

The argument s is a socket that has been created with the <code>socket()</code> function, bound to an address with <code>bind()</code>, and is listening for connections after a <code>listen()</code>. The <code>accept()</code> function extracts the first connection request on the queue of pending connections, creates a new socket with the same properties of socket s and allocates a new file descriptor for the socket. If no pending connections are present on the queue, and the socket is not marked as non-blocking, accept blocks the caller until a connection is present. If the socket is marked non-blocking and no pending connections are present on the queue, accept returns an error as described above.

The accepted socket may not be used to accept more connections. The original socket s remains open.

The argument *pName* is a result parameter that is filled in with the address of the connecting entity as known to the communications layer. The domain in which the communication is occurring determines the exact format of the *pName* parameter. The *plen* is a value-result parameter; it should initially contain at least sizeof(struct sockaddr), the amount of space pointed to by *pName*; on return it will contain the actual length (in bytes) of the address returned.

This call is used with connection-based socket types, currently with SOCK_STREAM.

It is possible to select (fdSelect()) a socket for the purposes of doing an accept by selecting it for read.



bind Bind a Name (Address) to a Socket

Syntax int bind(SOCKET s, PSA pName, int len);

Parameters

s Socket

pName Name (address) of desired local address

len Size of pName

Return Value If it succeeds, the function returns 0. Otherwise, a value of -1 is returned and the

function *fdError()* can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

ENOTSOCK The descriptor does not reference a socket.

EINVAL Name arguments are invalid.

EADDRNOTAVAIL The specified address is not available from the local machine.

EADDRINUSE The specified address is already in use.

Description The *bind()* function assigns a name to an unnamed socket. When a socket is created

with socket() it exists in a name space (address family) but has no name assigned. The

bind() function requests that name be assigned to the socket.

The argument s is a socket that has been created with the socket() function. The argument pName is a structure of type sockaddr that contains the desired local address.

The *len* parameter contains the size of *pName*, which is sizeof(struct sockaddr).

connect Initiate a Connection on a Socket

Syntax int connect(SOCKET s, PSA pName, int len);

Parameters

s Socket

pName Name (address) of desired peer

len Size of pName

Return Value If it succeeds, the function returns 0. Otherwise, a value of -1 is returned and the

function fdError() can be called to determine the error:

EADDRINUSE The specified address is already in use.

EADDRNOTAVAIL The specified address is not available from the local machine.

EALREADY A connection request is already pending on this socket.

EBADF The file descriptor (socket) is invalid.

ECONNREFUSED The attempt to connect was forcefully rejected.

EHOSTUNREACH The host is not reachable.

EINPROGRESS The request was accepted and is pending (non-blocking sockets).

EINVAL Name arguments are invalid.

EISCONN The socket is already connected.

ENOTSOCK The file descriptor does not reference a socket.

ENOTSUPP Socket is in the listening state and cannot be connected.

ETIMEDOUT Connection establishment timed out without establishing a connection.



Description

The *connect()* function establishes a logical (and potentially physical) connection from the socket specified by *s* to the foreign name (address) specified by *pName*.

If sock is of type SOCK_DGRAM, this call specifies the peer address with which the socket is to be associated; this address is that to which datagrams are to be sent, and the only address from which datagrams are to be received. If the socket is of type SOCK_STREAM, the function attempts to make a connection to another socket.

The argument s is a socket that has been created with the socket() function. The argument pName is a structure of type sockaddr that contains the desired foreign address. The len parameter contains the size of pName, which is sizeof(struct sockaddr).

Stream sockets may connect only once; while datagram sockets may re-connect multiple times to change their association. The connection may be dissolved by attempting to connect to an illegal address (for example, NULL IP address and Port). Datagram sockets that require multiple connections may consider using the *recvfrom()* and *sendto()* functions instead of *connect()*.

It is possible to select (fdSelect()) a socket for the purposes of doing a connect by selecting it for writing.

getpeername

Get Name (Address) of Connected Peer

Syntax int getpeername(SOCKET s, PSA pName, int *plen);

Parameters

s Socket

pName Name (address) of connected peer

plen Pointer to size of pName

Return Value

If it succeeds, the function returns 0. Otherwise, a value of -1 is returned and the function *fdError()* can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

ENOTSOCK The file descriptor does not reference a socket.

EINVAL Name arguments are invalid. ENOTCONN The socket is not connected.

Description

The *getpeername()* function returns the name (address) of the connected peer.

The argument *pName* is a result parameter that is filled in with the address of the connecting entity as known to the communications layer. The domain in which the communication is occurring determines the exact format of the *pName* parameter. The *plen* is a value-result parameter; it should initially contain at least sizeof(struct sockaddr), the amount of space pointed to by *pName*; on return it will contain the actual length (in bytes) of the address returned.



getsockname Get the Local Name (Address) of the Socket

Syntax int getsockname(SOCKET s, PSA pName, int *plen);

Parameters

s Socket

pName Name (address) of connected peer

plen Pointer to size of pName

Return Value If it succeeds, the function returns 0. Otherwise, a value of -1 is returned and the

function fdError() can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

ENOTSOCK The file descriptor does not reference a socket.

EINVAL Name arguments are invalid.

Description The *getsockname()* function returns the local name (address) of the socket.

The argument *pName* is a result parameter that is filled in with the address of the connecting entity as known to the communications layer. The domain in which the communication is occurring determines the exact format of the *pName* parameter. The *plen* is a value-result parameter; it should initially contain at least sizeof(struct sockaddr), the amount of space pointed to by *pName*; on return it will contain the actual length (in

bytes) of the address returned.



getsockopt Get the Value of a Socket Option Parameter

Syntax int getsockopt(SOCKET s, int level, int op, void *pbuf, int *pbufsize);

Parameters

s Socket

level Option level (SOL SOCKET, IPPROTO IP, IPPROTO TCP)

op Socket option to get pbuf Pointer to memory buffer

pbufsize Pointer to size of memory buffer

Return Value If it succeeds, the function returns 0. Otherwise, a value of -1 is returned and the

function fdError() can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

ENOTSOCK The file descriptor does not reference a socket.

EINVAL Buffer arguments are invalid.

Description

The *getsockopt()* function returns the options associated with a socket. Options may exist at multiple protocol levels; they are always present at the uppermost socket level.

When manipulating socket options, the level at which the option resides and the name of the option must be specified. To manipulate options at the socket level, level is specified as SOL_SOCKET. To manipulate options at any other level, the protocol number of the appropriate protocol controlling the option is supplied. In this implementation, only SOL_SOCKET, IPPROTO_IP, and IPPROTO_TCP are supported.

The parameters *pbuf* and *pbufsize* identify a buffer in which the value for the requested option(s) are to be returned. *pbufsize* is a value-result parameter, initially containing the size of the buffer pointed to by *pbuf*, and modified on return to indicate the actual size of the value returned.

Most socket-level options utilize an int parameter for *pbuf*. SO_LINGER uses a struct linger parameter, defined in INC\SOCKET.H, which specifies the desired state of the option and the linger interval (see below). SO_SNDTIMEO and SO_RCVTIMEO use a struct timeval parameter.

The following options are recognized at the socket level:

SO_REUSEADDR Specifies that the rules used in validating addresses supplied in a bind

call should allow reuse of local addresses.

SO_REUSEPORT Allows completely duplicate bindings by multiple processes if they all set

SO_REUSEPORT before binding the port. This option permits multiple instances of a program to each receive UDP/IP multicast or broadcast

datagrams destined for the bound port.

SO_KEEPALIVE Enables the periodic transmission of messages on a connected socket.

Should the connected party fail to respond to these messages, the connection is considered broken and processes using the socket are

notified when attempting to send data.

SO_DONTROUTE Indicates that outgoing messages should bypass the standard routing

facilities. Instead, messages are directed to the appropriate network interface according to the network portion of the destination address.



SO LINGER

Controls the action taken when unsent messages are queued on socket and a close is performed. If the socket promises reliable delivery of data and SO_LINGER is set, the system will block the process on the close attempt until it is able to transmit the data or until it decides it is unable to deliver the information (a timeout period, termed the linger interval, is specified in seconds in the setsockopt call when SO_LINGER is requested). If SO_LINGER is disabled and a close is issued, the system will process the close in a manner that allows the process to continue as quickly as possible.

SO BROADCAST

Requests permission to send broadcast datagrams on the socket. Broadcast was a privileged operation in earlier versions of the system.

SO_OOBINLINE

With protocols that support out-of-band data, this option requests that out-of-band data be placed in the normal data input queue as received; it will then be accessible with recv or read calls without the MSG_OOB flag. Some protocols always behave as if this option is set.

SO_SNDBUF SO_RCVBUF Buffer size for output. Buffer size for input.

SO_SNDLOWAT

Is an option to set the minimum count for output operations. Most output operations process all of the data supplied by the call, delivering data to the protocol for transmission and blocking as necessary for flow control. Non-blocking output operations will process as much data as permitted subject to flow control without blocking, but will process no data if flow control does not allow the smaller of the low water mark value or the entire request to be processed. A select operation testing the ability to write to a socket will return true only if the low water mark amount could be processed. The default value for SO_SNDLOWAT is set to a

convenient size for network efficiency, often 1024.

SO RCVLOWAT

Is an option to set the minimum count for input operations. In general, receive calls will block until any (non-zero) amount of data is received, then return with the smaller of the amount specified by SO_RCVLOWAT or the amount requested. The default value for SO_RCVLOWAT is 1. Receive calls may still return less than the amount specified by SO_RCVLOWAT or the amount requested if an error occurs, or the type

of data next in the receive queue is different from that which was

returned.

SO_SNDTIMEO

Is an option to set a timeout value for output operations. It accepts a struct timeval parameter with the number of seconds and microseconds used to limit waits for output operations to complete. If a send operation has blocked for this much time, it returns with a partial count or with the error EWOULDBLOCK if no data were sent. In the current

implementation, this timer is restarted each time additional data are delivered to the protocol, implying that the limit applies to output portions ranging in size from the low water mark to the high water mark for

output.

SO_RCVTIMEO

Is an option to set a timeout value for input operations. It accepts a struct timeval parameter with the number of seconds and microseconds used to limit waits for input operations to complete. This timer is restarted each time additional data are received by the protocol, and thus, the limit is in effect an inactivity timer. If a receive operation has been blocked for this much time without receiving additional data, it returns with a short count or with the error EWOULDBLOCK if no data were received.

SO_TYPE SO ERROR SO_TYPE returns the type of the socket, such as SOCK_STREAM.

Returns any pending error on the socket and clears the error status. It may be used to check for asynchronous errors on connected datagram sockets or for other asynchronous errors.

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SO PRIORITY

Is an option to set the VLAN user priority bit mapping for a given socket. It accepts only unsigned integer values. The valid values that can be configured for this option are 0-7. When a value of 0xFFFF is set to this option, it resets the priority back to its default value.

Options that are not Berkeley standard:

SO_IFDEVICE Specifies a uint index (1 to n) of the designated interface for sending and

receiving IP broadcast packets. When set, this interface is selected on a IP broadcast send operation if the socket's local (bound) IP address is NULL (INADDR_ANY). Also, when set, the socket will only accept incoming broadcast packets if they have been received on this interface.

SO_BLOCKING Specifies a int flag (1 or 0) indicating if the socket is in blocking or non-

blocking mode. Sockets default to blocking mode when created, but can be set to non-blocking by using setsockopt(). This option provides the

same functionality as calling the Unix function Fcntl() with the

O_NONBLOCK flag.

SO_TXTIMESTAMP Specifies a call-out function to allow timestamping of transmitted UDP

datagrams per socket basis. The NDK calls this function before adding the datagram into the driver's transmit queue. The function prototype of the call-out is "typedef void (*TimestampFxn)(UINT8 *plpHdr)", and is defined in "socket.h". This call-out function is responsible for updating

the UDP checksum accordingly.

The following options are recognized at the IPPROTO IP level:

IP_OPTIONS Specifies the IP options to be included in any outgoing IP packet sent via

this socket (maximum length is 20 bytes).

IP HDRINCL Indicates to IP that the socket application is supplying the IP header as

well as the rest of the packet payload. This is for use with RAW sockets

only.

IP_TOS Specifies the TOS value to place in the IP header. IP_TTL Specifies the TTLvalue to place in the IP header.

IP_ADD_MEMBERSHIP Specifies the multicast group to join. It accepts a struct ip_mreq

parameter (as defined in RFC 3678) which specifies multicast group address that the application wants to join and the interface IP address to

use for joining the multicast group.

IP_DROP_MEMBERSHIP Is an option used to leave a multicast group for a specified interface. It

accepts a struct ip_mreq parameter (as defined in RFC 3678) which specifies the IP address of the multicast group to leave and the interface

IP address on our device to use to leave the group.

The following options are recognized at the IPPROTO_TCP level:

TCP MAXSEG Set the maximum TCP segment size.

TCP_NODELAY Disables TCP send delay/coalesce algorithm.

TCP_NOPUSH Do not send data just to finish a data block (attempt to coalesce).

TCP_NOOPT Do not use TCP options.

TCP_SACKPERMITTED Permit RFC-2018 Selective Acknowledgment(SACK) conformant

connection. The SACK permitted option is exchanged at socket

connection time. Hence; on server side, the setting must be done before

calling "accept()", and on clint side before calling "connect()".



TCP MAXRTT

The maximum TCP Round Trip Time value allowed in the determination of the estimated TCP RTT. TCP packets containing RTT values greater than the value specified will not be used in the TCP RTT calculation (however, the packets are still processed by the stack). Units are in milliseconds. Values are rounded up to the next internal clock tick (100 millisecond). The minimum value is 100 milliseconds. The default value is 1 hour.

Listen for Connection Requests on Socket listen

Syntax int listen(SOCKET s, int maxcon);

Parameters

Socket S

Maximum number of connects to queue maxcon

Return Value If it succeeds, the function returns 0. Otherwise, a value of -1 is returned and the

function fdError() can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

ENOTSOCK The file descriptor does not reference a socket.

EOPNOTSUPP The socket is not of a type that supports the operation listen.

EISCONN The socket is already connected

Description The *listen()* function listens for connection requests on a socket.

> To accept connections, a socket is first created with socket(). The listen() function is called to specify a willingness to accept incoming connections and a queue limit for incoming connections. New connections are accepted by calling the accept() function.

The listen() function applies only to sockets of type SOCK STREAM.

The maxcon parameter defines the maximum length to which the gueue of pending connections may grow. If a connection request arrives with the gueue full, the client receives an error with an indication of ECONNREFUSED.



recv Receive Data from a Socket

Syntax int recv(SOCKET s, void *pbuf, int size, int flags);

Parameters

s Socket

pbuf Data buffer to place received data

size Size of desired data

flags Option flags

Return Value

If it succeeds, the function returns the number of bytes received. Returns 0 on connection oriented sockets where the connection has been closed by the peer (or socket shutdown for read). Otherwise, a value of -1 is returned and the function *fdError()* can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

EINVAL Attempt to read (or calling arguments) invalid for this socket.

ENOTCONN The socket is connection oriented and not connected ENOTSOCK The file descriptor does not reference a socket.

ETIMEDOUT The socket connection was dropped due to protocol layer timeout.

EWOULDBLOCK The socket is specified as non-blocking, or the timeout has expired.

Description

The *recv()* function attempts to receive data from a socket. It is normally used on a connected socket (see *connect()*). The data is placed into the buffer specified by *pbuf*, up to a maximum length specified by size. The options in flags can be used to change the default behavior of the operation.

The functions returns the length of the message on successful completion.

For a datagram type socket, the receive operation always copies one packet's worth of data. If the buffer is too short to hold the entire packet, the data is truncated and lost.

If no messages are available at the socket, it waits for a message to arrive, unless the socket is non-blocking. The function normally returns any data available, up to the requested amount, rather than waiting for receipt of the full amount requested; this behavior is affected by the options specified in flags as well as the socket-level options SO RCVLOWAT and SO RCVTIMEO described in *getsockopt()*.

The select call (fdSelect()) may be used to determine when more data arrives.

The *flags* argument to a *recv()* call is formed by combining one or more of the following flags:

MSG_DONTWAIT Requests that the operation not block when no data is available.

MSG OOB Requests receipt of out-of-band data that would not be received in the normal

data stream. Some protocols place expedited data at the head of the normal

data queue, and thus, this flag cannot be used with such protocols.

MSG_PEEK Causes the receive operation to return data from the beginning of the receive

queue without removing that data from the queue. Thus, a subsequent receive

call will return the same data.

MSG_WAITALL Requests that the operation block until the full request is satisfied. However,

the call may still return less data than requested if an error or disconnect occurs, or the next data to be received is of a different type than that returned.



recvfrom Receive Data from a Socket with the Sender's Name (Address)

Syntax int recvfrom(SOCKET s, void *pbuf, int size, int flags, PSA pName, int *plen);

Parameters

s Socket

pbuf Data buffer to place received data

size Size of desired data

flags Option flags

pName Pointer to place name (address) of sender

plen Pointer to size of pName

Return Value

If it succeeds, the function returns the number of bytes received. Returns 0 on connection oriented sockets where the connection has been closed by the peer (or socket shutdown for read). Otherwise, a value of -1 is returned and the function fdError() can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

EINVAL Attempt to read (or calling arguments) invalid for this socket.

ENOTCONN The socket is connection oriented and not connected.

ENOTSOCK The file descriptor does not reference a socket.

ETIMEDOUT The socket connection was dropped due to protocol layer timeout.

EWOULDBLOCK The socket is specified as non-blocking, or the timeout has expired.

Description

The *recvfrom()* function attempts to receive data from a socket. It is normally called with unconnected, non-connection oriented sockets. The data is placed into the buffer specified by *pbuf*, up to a maximum length specified by size. The options in flags can be used to change the default behavior of the operation. The name (address) of the sender is written to *pName*.

The argument *pName* is a result parameter that is filled in with the address of the sending entity as known to the communications layer. The domain in which the communication is occurring determines the exact format of the *pName* parameter. The *plen* is a value-result parameter; it should initially contain at least sizeof(struct sockaddr), the amount of space pointed to by pName; on return it will contain the actual length (in bytes) of the address returned.

The functions returns the length of the message on successful completion.

For a datagram type socket, the receive operation always copies one packet's worth of data. If the buffer is too short to hold the entire packet, the data is truncated and lost.

If no messages are available at the socket, it waits for a message to arrive, unless the socket is non-blocking. The function normally returns any data available, up to the requested amount, rather than waiting for receipt of the full amount requested; this behavior is affected by the options specified in flags as well as the socket-level options SO_RCVLOWAT and SO_RCVTIMEO described in <code>getsockopt()</code>.

The select call (fdSelect()) may be used to determine when more data arrives.

The flags argument to a *recv()* call is formed by combining one or more of the following flags:



MSG_DONTWAIT Requests that the operation not block when no data is available.

MSG_OOB Requests receipt of out-of-band data that would not be received in the normal

data stream. Some protocols place expedited data at the head of the normal

data queue, and thus, this flag cannot be used with such protocols.

MSG_PEEK Causes the receive operation to return data from the beginning of the receive

queue without removing that data from the queue. Thus, a subsequent receive

call will return the same data.

MSG WAITALL Requests that the operation block until the full request is satisfied. However,

the call may still return less data than requested if an error or disconnect occurs, or the next data to be received is of a different type than that returned.

recvnc Receive Data from a Socket without Buffer Copy

Syntax int recvnc(SOCKET s, void **ppbuf, int flags, HANDLE *phBuffer);

Parameters

s Socket

ppbuf Pointer to receive data buffer pointer

flags Option flags

phBuffer Pointer to receive buffer handle

Return Value

If it succeeds, the function returns the number of bytes received. Returns 0 on connection oriented sockets where the connection has been closed by the peer (or socket shutdown for read). Otherwise, a value of -1 is returned and the function *fdError()* can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

EINVAL Attempt to read (or calling arguments) invalid for this socket.

ENOTSOCK The file descriptor does not reference a socket.

ENOTCONN The socket is connection oriented and not connected.

ETIMEDOUT The socket connection was dropped due to protocol layer timeout.

EWOULDBLOCK The socket is specified as non-blocking, or the timeout has expired.

Description

The *recvnc()* function attempts to receive a data buffer from a socket. It is normally used on a connected socket (see *connect()*). A pointer to the data buffer is returned in *ppbuf*. A system handle used to free the buffer is returned in *phBuffer*. Both of these pointers must be valid. The options in flags can be used to change the default behavior of the operation.

The functions returns the length of the message on successful completion.

The receive operation always returns one packet buffer. The caller has no control over the size of the data returned in this buffer.

If no messages are available at the socket, this call waits for a message to arrive, unless the socket is non-blocking. The function returns the data buffer available.

When the caller no longer needs the data buffer, it is returned to the system by calling *recvncfree()*. Repeated failure to free buffers will eventually cause the stack to stop receiving data.

This function cannot be used with sockets of type SOCK_STREAM. When used with sockets of type SOCK_STREAMNC, out of band data marks are cleared.

The select call (fdSelect()) may be used to determine when more data arrives.



The flags argument to a *recv()* call can be one of the following flags:

MSG_DONTWAIT Requests that the operation not block when no data is available.

MSG_WAITALL Requests that the operation block until data is available. Because blocking is

the default behavior of a standard socket, this flag only alters the behavior of a

non blocking socket for this call.

recvncfree Return a Data Buffer Obtained from a No-Copy Receive Operation

Syntax void recvncfree(HANDLE hBuffer);

Parameters

hBuffer Handle to receive buffer to free

Return Value None.

Description The *recvncfree()* function frees a data buffer obtained from calling either *recvnc()* or

recvncfrom(). The calling parameter hBuffer is the handle of the buffer to free (not the

pointer to the buffer).

recvncfrom Receive Data and the Sender's Name From a Socket Without Buffer Copy

Syntax int recvncfrom(SOCKET s, void **ppbuf, int flags, PSA pName, int *plen, HANDLE

*phBuffer);

Parameters

Socket Socket

ppbuf Pointer to receive data buffer pointer

flags Option flags

pName Pointer to place name (address) of sender

plen Pointer to size of pName

phBuffer Pointer to receive buffer handle

Return Value If it succeeds, the function returns the number of bytes received. Returns 0 on

connection oriented sockets where the connection has been closed by the peer (or socket shutdown for read). Otherwise, a value of -1 is returned and the function fdError()

can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

EINVAL Attempt to read (or calling arguments) invalid for this socket.

ENOTSOCK The file descriptor does not reference a socket.

ENOTCONN The socket is connection oriented and not connected.

ETIMEDOUT The socket connection was dropped due to protocol layer timeout. EWOULDBLOCK The socket is specified as non-blocking, or the timeout has expired.

Description The recvncfrom() function attempts to receive a data buffer from a socket. It is normally

called with unconnected, non-connection oriented sockets. A pointer to the data buffer is returned in *ppbuf*. A system handle used to free the buffer is returned in *phBuffer*. Both of these pointers must be valid. The options in flags can be used to change the default behavior of the operation. The name (address) of the sender is written to *pName*.

The argument pName is a result parameter that is filled in with the address of the



sending entity as known to the communications layer. The domain in which the communication is occurring determines the exact format of the *pName* parameter. The *plen* is a value-result parameter; it should initially contain at least sizeof(struct sockaddr), the amount of space pointed to by *pName*; on return it will contain the actual length (in bytes) of the address returned.

The functions returns the length of the message on successful completion.

The receive operation always returns one packet buffer. The caller has no control over the size of the data returned in this buffer.

If no messages are available at the socket, this call waits for a message to arrive, unless the socket is non-blocking. The function returns the data buffer available.

When the caller no longer needs the data buffer, it is returned to the system by calling *recvncfree()*. Repeated failure to free buffers will eventually cause the stack to stop receiving data.

This function cannot be used with sockets of type SOCK_STREAM. When used with sockets of type SOCK_STREAMNC, out of band data marks are cleared.

The select call (fdSelect()) may be used to determine when more data arrives.

The *flags* argument to a *recv()* call can be one of the following flags:

MSG_DONTWAIT
MSG_WAITALL

Requests that the operation not block when no data is available.

Requests that the operation block until data is available. Because blocking is the default behavior of a standard socket, this flag only alters the behavior of a non blocking socket for this call.

send Transmit Data to a Socket

Syntax int send(SOCKET s, void *pbuf, int size, int flags);

Parameters

s Socket

pbuf Data buffer holding data to transmit

size Size of data flags Option flags

Return Value

If it succeeds, the function returns the number of bytes sent. Otherwise, a value of -1 is returned and the function fdError() can be called to determine the error:

EBADF The file descriptor (socket) is invalid. EHOSTUNREACH The remote host was unreachable.

EMSGSIZE The specified size exceeds the limit of the underlying protocol.

ENOBUFS Memory allocation failure while attempting to send data.

ENOTSOCK The file descriptor does not reference a socket.

ENOTCONN The socket is connection oriented and not connected.

ESHUTDOWN The socket has been shut down for writes.

ETIMEDOUT The socket connection was dropped due to protocol layer timeout. EWOULDBLOCK The socket is specified as non-blocking, or the timeout has expired.



Description

The send() function attempts to send data on a socket. It is used on connected sockets only (see connect()). The data to send is contained in the buffer specified by pbuf, with a length specified by size. The options in flags can be used to change the default behavior of the operation.

The function returns the length of the data transmitted on successful completion.

If a thread does not contain calls to fdOpenSession() and fdCloseSession(), the send() function returns a value of -1.

For a datagram type socket, the send operation always copies one packet's worth of data. If the buffer size is too large to be transmitted in a single packet, an error code of EMSGSIZE is returned.

If there is not transmit buffer space available on a stream type socket, the function waits for space to become available, unless the socket is non-blocking. The function normally transmits all the specified data.

The select call (fdSelect()) may be used to determine when the socket is able to write.

The flags argument to a *send()* call is formed by combining one or more of the following flags:

MSG_OOB sends out-of-band data on sockets that support this notion (e.g.

SOCK_STREAM); the underlying protocol must also support out-of-band data.

MSG_EOR indicates a record mark for protocols that support the concept.

MSG_EOF Requests that the sender side of a socket be shut down, and that an

appropriate indication be sent at the end of the specified data; this flag is only implemented for SOCK_STREAM sockets in the AF_INET protocol family, and

implements Transaction TCP.

MSG_DONTROUTE Specifies that the packet should not be routed, but sent only using the ARP

table entries.

sendto Transmit Data on a Socket to Designated Destination

Syntax int sendto(SOCKET s, void *pbuf, int size, int flags, PSA pName, int len);

Parameters

s Socket

pbuf Data buffer holding data to transmit

size Size of data flags Option flags

pName Pointer to name (address) of destination

len Size of data pointed to by pName

Return Value If it succeeds, the function returns the number of bytes sent. Otherwise, a value of -1 is

returned and the function fdError() can be called to determine the error:

EBADF The file descriptor (socket) is invalid. EHOSTUNREACH The remote host was unreachable.

EMSGSIZE The specified size exceeds the limit of the underlying protocol.

ENOBUFS Memory allocation failure while attempting to send data.

ENOTSOCK The file descriptor does not reference a socket.

ENOTCONN The socket is connection oriented and not connected.

ESHUTDOWN The socket has been shut down for writes.



ETIMEDOUT EWOULDBLOCK The socket connection was dropped due to protocol layer timeout. The socket is specified as non-blocking, or the timeout has expired.

Description

The sendto() function attempts to send data on a socket to a specified destination. It is used on unconnected, non-connection oriented sockets only (see connect()). The data to send is contained in the buffer specified by pbuf, with a length specified by size. The options in flags can be used to change the default behavior of the operation.

The argument pName is a pointer to the address of the destination entity as known to the communications layer. The domain in which the communication is occurring determines the exact format of the pName parameter. The len parameter should contain the size of name, which is sizeof(struct sockaddr).

The functions returns the length of the data transmitted on successful completion.

For a datagram type socket, the send operation always copies one packet's worth of data. If the buffer size is too large to be transmitted in a single packet, an error code of EMSGSIZE is returned.

The select call (fdSelect()) may be used to determine when the socket is able to write.

The flags argument to a send() call is formed by combining one or more of the following flags:

MSG OOB sends out-of-band data on sockets that support this notion (e.g.,

SOCK STREAM); the underlying protocol must also support out-of-band data.

MSG EOR indicates a record mark for protocols that support the concept.

MSG_EOF Requests that the sender side of a socket be shut down, and that an

> appropriate indication be sent at the end of the specified data; this flag is only implemented for SOCK_STREAM sockets in the AF_INET protocol family, and

implements Transaction TCP.

MSG DONTROUTE Specifies that the packet should not be routed, but sent only using the ARP

table entries.

NOTE: The native operation of the socket *sendto* operation is to connect ® sendto ® disconnect. Sockets that are not bound to a local IP or local port would have an ephemeral port selected every time in order to override this behavior and to ensure that the ephemeral port is not selected every time it is recommended that customers do a bind to port 0.

This selects the first free port not in use and all subsequent

communication uses the same port.

setsockopt Set the Value of a Socket Option Parameter

Syntax int setsockopt(SOCKET s, int level, int op, void *pbuf, int bufsize);

Parameters

Socket s

Option level (SOL SOCKET, IPPROTO IP, IPPROTO TCP) level

op Socket option to set pbuf Pointer to memory buffer

bufsize Size of memory buffer pointed to by pbuf



Return Value

If it succeeds, the function returns 0. Otherwise, a value of -1 is returned and the function *fdError()* can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

ENOTSOCK The file descriptor does not reference a socket.

EINVAL Buffer arguments are invalid.

Description

The setsockopt() function sets option values associated with a socket. Options may exist at multiple protocol levels; they are always present at the uppermost socket level.

When manipulating socket options, the level at which the option resides and the name of the option must be specified. To manipulate options at the socket level, level is specified as SOL SOCKET. To manipulate options at any other level, the protocol number of the appropriate protocol controlling the option is supplied. In this implementation, only SOL_SOCKET, IPPROTO_IP, and IPPROTO_TCP are supported.

The parameters pbuf and bufsize identify a buffer that holds the value for the specified option.

Most socket-level options utilize an int parameter for pbuf. SO_LINGER uses a struct linger parameter, defined in INC\SOCKET.H, which specifies the desired state of the option and the linger interval. SO_SNDTIMEO and SO_RCVTIMEO use a struct timeval parameter. The IP-level options IP_ADD_MEMBERSHIP and IP_DROP_MEMBERSHIP accept a struct ip mreg parameter.

The socket options supported for setsockopt() are the same as defined for getsockopt(), with the exception of SO TYPE and SO ERROR, which cannot be set.

Please see the description of *getsockopt()* for a list of socket options.

NOTE: The SO_SNDBUFand SO_RCVBUFoptions can only be set if there is no transmit or receive data pending at the socket. In general, the buffer sizes should only be configured before the socket is bound or connected. Buffer sizes set on listen sockets will propagate to spawned accept sockets.



shutdown Close One Half of a Connected Socket

Syntax int shutdown(SOCKET s, int how);

Parameters

s Socket

how Manner of shut down

Return Value If it succeeds, the function returns 0. Otherwise, a value of -1 is returned and the

function fdError() can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

ENOTSOCK The file descriptor does not reference a socket.

ENOTCONN The specified socket is not connected.

Description The shutdown() function causes all or part of a full-duplex connection on the socket

associated with a socket to be shut down. If how is SHUT_RD (0), further receives will be disallowed. If how is SHUT_WR (1), further sends will be disallowed. If how is

SHUT RDWR (2), further sends and receives will be disallowed.

socket Create a Socket

Syntax SOCKET socket(int domain, int type, int protocol);

Parameters

domain Socket domain (AF INET)

type Socket type (SOCK_DGRAM, SOCK_STREAM, SOCK_RAW)

protocol Socket protocol (Normally IPPROTO_TCP or IPPROTO_UDP, but can be anything

when type is set to SOCK_RAW)

Return Value If it succeeds, the function returns a file descriptor representing the socket. Otherwise, a

value of INVALID_SOCKET is returned and the function fdError() can be called to

determine the error:

EPFNOSUPPORT The specified domain was not AF_INET.

EPROTOTYPE The *type* parameter does not support the *protocol* parameter.

ESOCKTNOSUPPORT The specified socket type is not supported.

ENOMEM Memory allocation error allocating socket buffers.

EMFILE The descriptor table is full.

Description The socket() function creates a socket, an endpoint for communication and returns the

socket in the form of a file descriptor.

The *domain* parameter specifies a communications domain within which communication will take place; this selects the protocol/address family that should be used. These families are defined in the include file INC\SOCKET.H. This will always be AF_INET

(AF_INET) in this implementation.

The socket type parameter specifies the semantics of communication. Currently defined

types are:

STRUMENTS

socket — Create a Socket www.ti.com

SOCK_STREAM Provides sequenced, reliable, two-way connection based byte streams. An

out-of-band data transmission mechanism is supported.

SOCK_STREAMNC Identical to SOCK_STREAM except that received data is not coalesced into a

receive holding buffer. This eliminates one or two receive data copies (depending on which recv() socket function is used), but has the potential of tying up multiple data packets. It should only be used when the socket is to receive data in large bursts. Out-of-band data is supported, but only when the

traditional recv() socket calls are used.

SOCK_DGRAM Supports datagrams - connectionless, unreliable messages of a fixed (typically

small) maximum length.

SOCK_RAW Similar to SOCK_DGRAM, only allows the use of any protocol that must be

manually constructed in each datagram by the programmer.

The *protocol* parameter specifies a particular protocol to be used with the socket. In this implementation of the stack, SOCK_STREAM must use IPPROTO_TCP, SOCK_DGRAM must use IPPROTO_UDP, and SOCK_RAW is unrestricted. To remain compatible with the industry, this parameter can be set to NULL on SOCK_STREAM or SOCK_DGRAM.



3.4 Raw Ethernet Sockets Programming Interface

Raw Ethernet sockets are a special type of sockets that allow an application to send and receive entire Ethernet packets without any intermediate processing by the stack, like stripping off headers, checksum calculations, etc., that are typically done for IPv4, IPv6 sockets. These sockets are expected to be used by applications that have very definite performance requirements and need ultimate control over packet processing. The Raw Ethernet sockets have both *no-copy* send and receive APIs. This facilitates the application's performance requirements even further by reducing any overhead on the send or receive data paths due to memory allocation and copying. A corresponding *Raw Ethernet Module* has also been added to the core NDK stack that interfaces with the NIMU layer to send/receive data. For more details on the Raw Ethernet module, see Section A.17 of this document.

3.4.1 Function Overview

The following is a complete list of socket APIs implemented for the Raw Ethernet socket family (AF_RAWETH).

socket Creates a raw Ethernet socket shutdown Close one half of the socket getsockopt Gets the value of a socket option setscokopt Sets the value of a socket option

send Sends raw Ethernet data using a previously opened raw Ethernet socket

getsendncbuff Allocate space for a raw Ethernet packet and retrieve handle for the data buffer.

This is used in conjunction with sendnc API for no-copy send.

sendnc Send out raw Ethernet data without making a copy of it during the Tx path

sendncfree Free buffer obtained from *getsendncbuff()* API

recvnc Free buffer obtained from recvnc() API

3.4.2 Raw Ethernet Sockets API Functions

This section describes the socket APIs listed before in detail and in particular when used with AF_RAWETH family sockets.

socket Create a raw Ethernet socket.

Syntax SOCKET socket(int domain, int type, int protocol);

Parameters

domain Socket domain (AF_RAWETH) type Socket type (SOCK_RAWETH)

protocol Socket protocol (can be set to any custom value other than the well known types:-

IP (0x800), IPv6 (0x806), VLAN (0x8100), PPPoE Control (0x8863), PPPoE Data

(0x8864) is acceptable)

Return Value If it succeeds, the function returns a file descriptor representing the socket. Otherwise, a

value of INVALID SOCKET is returned and the function fdError() can be called to

determine the error:

EPFNOSUPPORT The specified domain was none of the supported families, i.e.,

AF INET, AF INET6, AF RAWETH.

EINVAL The protocol parameter supplied is not valid. IP (0x800), IPv6 (0x806),

VLAN (0x8100), PPPoE Control (0x8863), PPPoE Data (0x8864) are

not valid values for the protocol argument.

ESOCKTNOSUPPORT The specified socket type is not supported for this protocol.



ENOMEM Memory allocation error allocating socket buffers.

EMFILE The descriptor table is full.

Description

The socket () function creates a socket, an endpoint for communication and returns the socket in the form of a file descriptor. The *domain* parameter specifies a communications domain within which communication will take place; this selects the protocol/address family that should be used. These families are defined in the include file *INC\SOCKET.H.* To create a raw Ethernet socket, the domain must be specified as AF_RAWETH. The socket type parameter specifies the semantics of communication. For raw Ethernet sockets, this parameter must be set to SOCK_RAWETH. The protocol parameter specifies the protocol to be used for the socket. This can be set to any custom protocol type for a raw Ethernet socket. Standard protocol types like IP (0x800), IPv6 (0x806), VLAN (0x8100), PPPoE Control (0x8863), PPPoE Data (0x8864) must not be used here for protocol parameter.

shutdown Close one half of a connected socket.

Syntax int shutdown(SOCKET s, int how);

Parameters

s Socket

how Manner of shut down

Return Value If it succeeds, the function returns 0. Otherwise, a value of -1 is returned and the

function fdError() can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

ENOTSOCK The file descriptor does not reference a socket.

Description The *shutdown()* function causes all or part of a full-duplex connection on the socket

associated with a socket to be shut down. If how is SHUT_RD (0), further receives will be disallowed. If how is SHUT_WR (1), further sends will be disallowed. If how is

SHUT RDWR (2), further sends and receives will be disallowed.

getsockopt Get the value of a socket option.

Syntax int getsockopt(SOCKET s, int level, int op, void *pbuf, int *pbufsize);

Parameters

s Socket

level Option level (SOL_SOCKET only for AF_RAWETH sockets)

op Socket option to get pbuf Pointer to memory buffer

pbufsize Pointer to size of memory buffer

Return Value If it succeeds, the function returns 0. Otherwise, a value of -1 is returned and the

function *fdError()* can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

ENOTSOCK The file descriptor does not reference a socket.

EINVAL Buffer arguments are invalid.



Description

The getsockopt() function returns the options associated with a socket. Options are always present at the uppermost socket level (SOL SOCKET) for raw Ethernet sockets. When manipulating socket options, the level at which the option resides and the name of the option must be specified. The parameters pbuf and pbufsize identify a buffer in which the value for the requested option(s) are to be returned. pbufsize is a value-result parameter, initially containing the size of the buffer pointed to by pbuf, and modified on return to indicate the actual size of the value returned.

The following socket (SOL SOCKET) level options are recognized for raw Ethernet sockets:

SO_IFDEVICE

Specifies a uint index (1 to n) of the designated interface for sending and receiving raw Ethernet packets.

NOTE: The SO_IFDEVICE option must be configured to successfully use a raw Ethernet socket for communication.

SO PRIORITY

Specifies a unit value (0 to 7) configured as the priority to be marked on all flowing packets using this socket. This priority can be used by the Ethernet driver in turn to differentiate between packets and apply any desired QoS scheme. It can be also used by a driver/application to map the priority to certain transmission properties like the EMAC channel number on which the packets are to be transmitted. Only unsigned integer values between 0 to 7 are acceptable values for this field. When a value of 0xFFF is set to this option, it resets the priority back to its default value.

SO_RCVTIMEO

Is an option to set a timeout value for input operations. It accepts a struct timeval parameter with the number of seconds and microseconds used to limit waits for input operations to complete.

This timer is restarted each time additional data are received by the protocol, and therefore, the limit is in effect an inactivity timer. If a receive operation has been blocked for this much time without receiving additional data, it returns with a short count or with the error

EWOULDBLOCK if no data were received.

SO SNDBUF SO_RCVBUF SO_RCVLOWAT

Is an option to set the minimum size of data in bytes for input

operations. The default value for SO RCVLOWAT is 1. Receive calls may still return less than the amount specified by SO_RCVLOWAT or

the amount requested if an error occurs.

SO ERROR Returns any pending error on the socket and clears the error status. It

may be used to check for any asynchronous errors.

SO_TYPE Returns the type of the socket. Always returns SOCK_RAWETH for raw

Ethernet sockets.

Buffer size for output

Buffer size for input

NOTE: Options like SO SNDWAT, SO SNDTIMEO, etc., are not supported for raw Ethernet sockets, since there is no buffering on the send path and the operation is synchronous; i.e., once send()/sendnc() APIs are invoked for raw Ethernet sockets, these calls actually return only after enqueuing the data in the driver queue. Hence, no buffering or timeouts are required.



setsockopt Set the value of a socket option.

Syntax int setsockopt(SOCKET s, int level, int op, void *pbuf, int bufsize);

Parameters

s Socket

level Option level (SOL SOCKET only for AF RAWETH sockets)

op Socket option to set pbuf Pointer to memory buffer

bufsize Size of memory buffer pointed to by pbuf

Return Value If it succeeds, the function returns 0. Otherwise, a value of -1 is returned and the

function fdError() can be called to determine the error:

EBADF The file descriptor (socket) is invalid.

ENOTSOCK The file descriptor does not reference a socket.

EINVAL Buffer arguments are invalid.

Description The setsockopt() function sets option values associated with a socket. Options are

always present at the uppermost socket level (SOL_SOCKET) for raw Ethernet sockets. When manipulating socket options, the level at which the option resides and the name of the option must be specified. The parameters *pbuf* and *bufsize* identify a buffer that holds the value for the specified option. Most socket-level options utilize an int parameter

for pbuf.

The socket options supported for setsockopt() are the same as the ones specified in the

getsockopt() API.

send Transmit raw Ethernet data using a socket.

Syntax int send(SOCKET s, void *pbuf, int size, int flags);

Parameters

s Socket

pbuf Data buffer holding data to transmit

size Size of data flags Option flags

Return Value If it succeeds, the function returns the number of bytes sent. Otherwise, a value of -1 is

returned and the function *fdError()* can be called to determine the error:

ENOTSOCK The file descriptor does not reference a socket.

EINVAL The input is invalid.

ENOBUFS Memory allocation failure while attempting to send data.

ESHUTDOWN The socket has been shut down for writes.

EMSGSIZE The size of the data being sent exceeds the MTU of the interface or the

Maximum Transmit buffer size configured using SO_SNDBUF option,

whichever is the smaller value of the two.

ENXIO No egress interface specified for this socket to send out data. Use

SO_IFDEVICE socket option and specify an interface before retrying to

send out data using this socket.

www.ti.com getsendncbuff — Retrieve handle to a buffer into which the application can fill any raw Ethernet data to send.

Description

The send() function attempts to send data on a socket. The data to send is contained in the buffer specified by pbuf, with a length specified by size. The options in flags can be used to change the default behavior of the operation. Currently no flag options are defined for raw Ethernet sockets. The functions returns the length of the data transmitted on successful completion.

The data buffer specified here is allocated and freed up by the application itself. The packet buffer is copied over to the packet allocated on the transmit path by the Raw Ethernet module and hence the application buffer (pbuf) freeing is the responsibility of the application when this API returns. Based on the socket handle specified to this call, the raw Ethernet module retrieves the socket priority and device on which this packet needs to be transmitted and does the needful to transmit the data. All packets transmitted using the specified socket would inherit their priority from the socket.

The format of the data buffer sent as input to this function is shown as follows:

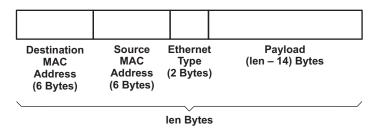


Figure 3-1. Raw Ethernet Buffer Format

getsendncbuff

Retrieve handle to a buffer into which the application can fill any raw Ethernet data to send.

Syntax

int getsendncbuff(SOCKET s, UINT32 bufSize, void** phBuf, HANDLE* phPkt);

Parameters

s Socket

bufSize Size of data buffer to allocate
phbuf Pointer to send data buffer pointer
phPkt Pointer to packet buffer handle

Return Value

If it succeeds, the function returns 0. Also, the phbuf and phPkt pointers are filled in with valid pointers to the data and packet buffers just allocated. Otherwise, a value of -1 is returned and the function *fdError()* can be called to determine the error:

ENOBUFS Out of memory. Couldn't allocate memory required for the packet and

data buffer.

EMSGSIZE The size of the data buffer requested exceeds the MTU of the interface

or the Maximum Transmit buffer size configured using SO_SNDBUF option, whichever is the smaller value of the two on the specified

socket.

Description

This API needs to be called by the raw Ethernet application to obtain a buffer handle to use to transmit data without copy using the <code>sendnc()</code> API. This function ensures that <code>bufSize</code> byte memory is allocated for the raw Ethernet data buffer. It also allocates memory for the packet to hold this data buffer. The application can fill the required data in the <code>buffer</code> just obtained and needs to send both the data <code>buffer</code> and the packet pointers to <code>sendnc()</code> API to finally send out the packet. This packet and the data <code>buffer</code>



are freed by the Ethernet driver once the transmit completes successfully. However, if the application would like to free up the buffer obtained because of some error it encountered during send process, it would have to use the *sendncfree* API and specify the packet buffer handle as a parameter and both the data buffer and packet buffer will be freed up.

sendnc Send data out on the socket without any copy on transmit path.

Syntax int sendnc(SOCKET s, void *pbuf, int size, HANDLE hPkt, int flags);

Parameters

s Socket

pbuf Pointer to send data buffer

hPkt Packet buffer handle obtained from the getsendncbuff() API

Flags Option flags

Return Value

If it succeeds, the function returns number of bytes transmitted. Otherwise, a value of -1 is returned, and the function *fdError()* can be called to determine the error:

EINVAL The input is invalid

ESHUTDOWN The socket has been shut down for writes ENOTSOCK The file descriptor does not reference a socket

ENXIO No egress interface specified for this socket to send out data. Use

SO_IFDEVICE socket option and specify an interface before retrying to

send out data using this socket.

Description

The sendnc() API function attempts to send the data buffer and packet specified using the raw Ethernet socket handle provided. It doesn't make any copies of the data on the transmit path and, therefore, provides a significant performance gain to the application using it. The buffer pointer and the packet handle must be obtained using the getsendncbuff() API before this function is called. The size of data buffer specified as input to this function must not exceed the size of buffer allocated using the getsendncbuff() API. No option flags are defined at this time for this API. This packet and the data buffer are freed by the Ethernet driver once the transmit completes successfully. However, If an error is returned from this API, the application is responsible for freeing up the packet and data buffers obtained earlier from the getsendncbuff() API by calling the sendncfree() API with the packet handle as input.

The format of the data buffer sent as input to this function is expected to be the following:

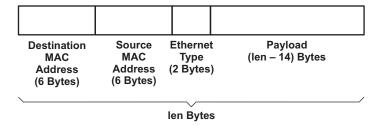


Figure 3-2. Raw Ethernet Buffer Format



sendncfree Free the packet and data buffers obtained using the getsendncbuff() API.

Syntax void sendncfree(HANDLE hFrag);

Parameters

Handle to send buffer to free hFrag

None Return Value

The sendncfree() function frees the packet and data buffer obtained from calling the Description

getsendncbuff() API. The calling parameter, hFrag, is the handle of the packet buffer to

free (not the pointer to the buffer handle).

Receive data from a socket without buffer copy recvnc

int recvnc(SOCKET s, void **ppbuf, int flags, HANDLE *phBuffer); **Syntax**

Parameters

Socket s

Pointer to receive data buffer pointer ppbuf

flags Option flags

Pointer to receive buffer handle phBuffer

Return Value

If it succeeds, the function returns the number of bytes received. Otherwise, a value of -1 is returned and the function *fdError()* can be called to determine the error:

EBADF The file descriptor (socket) is invalid

EINVAL Attempt to read (or calling arguments) invalid for this socket

ENOTSOCK The file descriptor does not reference a socket

EWOULDBLOCK The receive timeout configured on the socket has expired and no data

received so far.

ENXIO No egress interface specified for this socket to receive from. Use

SO IFDEVICE socket option and specify an interface before retrying to

receive data using this socket.

Description

The recvnc() function attempts to receive a data buffer from a socket. A pointer to the data buffer is returned in pobuf. A system handle used to free the buffer is returned in phBuffer. Both of these pointers must be valid. The options in flags can be used to change the default behavior of the operation. No flags are defined currently for raw Ethernet sockets. The functions returns the length of the message on successful completion. The receive operation always returns one packet buffer. The caller has no control over the size of the data returned in this buffer. If no messages are available at the socket, this call waits for a message to arrive for the receive timeout specified on this socket. If no timeout is specified this call blocks forever waiting for data to arrive on the socket. The function returns the data buffer available. When the caller no longer needs the data buffer, it is returned to the system by calling recvncfree(). Repeated failure to free buffers eventually causes the stack to stop receiving data.

NOTE: Take care when using the *recvnc()* API, because packet buffers come from the driver; there may be a limited supply available. The packet buffers must be promptly freed up by the application once processing is complete.



recvncfree Return a data buffer obtained from a no-copy receive operation

Syntax void recvncfree(HANDLE hBuffer);

Parameters

hBuffer Handle to receive buffer to free

Return Value None

Description The recvncfree() function frees a data buffer obtained from calling recvnc(). The calling

parameter *hBuffer* is the handle of the buffer to free (not the pointer to the buffer).

3.5 Full Duplex Pipes Programming Interface

Although sockets can be used for inter-task communications, it is not the most efficient method. The stack provides a second data communications model called pipes, which allow for local connection oriented communications.

A pipe is a full duplex connection oriented file descriptor. When a pipe is created, both ends of the pipe are returned to the caller as file descriptors.

Communication is performed using the standard file and sockets API functions. All the file descriptor functions are supported with pipes: fdSelect(), fdClose(), fdError().

Also, socket functions *send()* and *recv()* write and read data through the pipe. Both functions also support the following standard sockets message flags when using pipes:

MSG_PEEK Examine data but do not consume it.

MSG_DONTWAIT Do not block on send/recv operation (by default, pipe operations always block).

Pipes are connection oriented, thus, when one end closes, the other end is altered by an error return from send() or recv(). It is therefore possible to make a blocking call on recv() without concern that the function will be deadlocked if the other end terminates the connection.



3.5.1 Pipe API Functions

Because pipes share file descriptor and IO functions with sockets, the only pipe oriented function is the creation of the connected pair.

pi	pe	Create a	Full	Duplex Pipe	è
г-					

Syntax int pipe(HANDLE *pfd1, HANDLE *pfd2);

Parameters

pfd1 Pointer to file descriptor to first end of pipe.
pfd2 Pointer to file descriptor to second end of pipe.

Return Value Returns zero on success or -1 on error. A more detailed error code can be found by

calling fdError().

Description Creates a pre-connected full duplex pipe. The returned file descriptors can be used with

all the fd file descriptor functions, as well as the send() and recv() socket functions.

Pipes are connection oriented, so like TCP, a read or write call can return ENOTCONN

when the connection is broken by one side or the other.

NOTE: Both file descriptors must be closed to correctly close down (and free) a

pipe.

3.6 Internet Group Management Protocol (IGMP)

Internet Group Management Protocol (IGMP) is designed to help routers in routing IP multicast traffic. Each router can have multiple ports, and it is inefficient for the router to replicate every IP multicast packet out of each active port. Using the IGMP protocol, the multicast router is able to keep track of which IP multicast addresses need to be routed to each individual port. This allows the router to limit IP multicast transmission to only those ports that require the multicast traffic.

The IGMP protocol assumes a client/server relationship between endpoints. The IGMP server is run by the multicast router to get IP multicast information about all the client on each of its individual ports. The IGMP client is only concerned with communicating its own multicast requirements to the local IGMP server, so that it will get the IP multicast packets that it requires.

The NDK does not currently support IP multicast routing, so there is no need to use IGMP in server mode. However, the software does support IGMP client operation.

The IGMP client module indicates to the IGMP server which multicast IP addresses that the client needs to receive. The IGMP API will also maintain the Ethernet multicast MAC address list at the Ethernet driver level.

An application can join or leave a multicast group using the well-known <code>setsockopt()</code> API. It is recommended that you no longer use the IGMPJoinHostGroup and IGMPLeaveHostGroup APIs. Instead, we recommend that you use the <code>setsockopt()</code> and <code>getsockopt()</code> APIs with the IP_ADD_MEMBERSHIP and IP_DROP_MEMBERSHIP options. For more details on options for joining or leaving a multicast group, see <code>getsockopt()</code> and <code>setsockopt()</code>.



Initialization and Configuration

This chapter discusses the initialization sequence for the NDK. In previous versions, this chapter also discussed the configuration manager API in detail. Since configuration via XGCONF is now recommended, documentation of the configuration API has been moved to an appendix for use in legacy applications.

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www.ti.com Configuration Methods

4.1 **Configuration Methods**

To simplify the configuration process, the NDK now allows you to use the XGCONF configuration tool within CCS to configure an application's use of NDK modules. Graphical displays let you enable and set properties as needed, and context-sensitive help provides information about individual fields. XGCONF is the same configuration tool used to configure SYS/BIOS. The same configuration in one project can configure both NDK and SYS/BIOS modules and objects.

To open XGCONF, simply double-click the *.cfg file in your application's project. See the steps in the TI Network Developer's Kit (NDK) User's Guide. (SPRU523) for using XGCONF with the NDK. For more about using XGCONF, see Chapter 2 of the TI SYS/BIOS Real-time Operating System User's Guide (SPRUEX3).

Internally, the XGCONF configuration tool generates C code that calls into and updates the configuration database used in previous versions of the NDK. In fact, you can still use the configuration database if you have legacy applications. However, you must choose one method or the other to configure your application. XGCONF is the recommended configuration method.

NOTE: You should not mix configuration methods. If you have legacy NDK applications that use the old C-based configuration method, you should either continue to use that method or convert the configuration entirely to an *.cfg file configuration. If a project uses both methods, there will be conflicts between the two configurations.

Appendix G describes the programming API that legacy NDK applications use to create a system configuration.

Network Control Initialization Procedure (NETCTRL) 4.2

The stack library includes code to perform system initialization based on the configuration. Initialization of the scheduling routines is performed by a network control layer called NETCTRL.

If you use the XGCONF configuration tool to configure the NDK, the following custom C functions are generated for you to manage NDK startup and thread scheduling. See the TI Network Developer's Kit (NDK) User's Guide (SPRU523) for details. You should take care not to write application functions with these names.

- ti_ndk_config_Global_stackThread(): The NDK stack thread function.
- NetworkOpen(): function that is called automatically by NC NetStart().
- *NetworkClose()*: function that is called automatically by *NC_NetStart()*.
- NetworkIPAddr(): function that is called automatically by NC NetStart().
- ti_ndk_config_Global_serviceReport(): Service report callback function.

4.2.1 Initialization Procedure

If you use the XGCONF configuration tool to configure the NDK, the ti ndk config Global stackThread() function is automatically generated to handle the initialization process and to act as the NDK scheduler thread. You can use XGCONF to configure Hook functions to be called at various point during the initialization and thread scheduling. See the section on "Global Hook Configuration" in the TI Network Developer's Kit (NDK) User's Guide (SPRU523).

If you are not using the XGCONF configuration tool, see Section G.4 for the stack initialization process.

If you use the XGCONF configuration tool to configure the NDK, the basic process of stack initialization is as follows:

- 1. Run the Stack Thread Begin (Global.stackBeginHook) hook function if one is configured. Note that no NDK-related code can run in this hook function because the NC_SystemOpen() function has not yet
- 2. Initialize the operating system environment with the initialization function NC SystemOpen(Priority, OpMode). This function must always be called first - before any other NDK related function. The calling parameters determine the priority and operating mode of the network event scheduler.



- 3. Create a new configuration via CfgNew() (which is called from generated code).
- 4. Run the **Stack Thread Initialization** (Global.stackInitHook) hook function if one is configured.
- 5. The generated *ti_ndk_config_Global_stackThread()* function builds the new configuration via code generated from the XGCONF configuration.
- Boot the stack with the configuration by calling NC_NetStart(hCfg, pfnStart, pfnStop, pfnNetIP) with a
 handle to the configuration, plus pointers to the three generated functions for start, stop, and IP
 address change operations. The NC_NetStart() function does not return until the stack session has
 terminated.
- 7. After some preliminary initialization, the NC_NetStart() function creates a new thread that calls the generated NetworkOpen() function.
- 8. Run the Network Open (Global.networkOpenHook) hook function if one is configured.
- 9. The NetworkOpen() function creates task threads for its networking requirements.
- 10. Under normal operation, the network does not shut down until the NC_NetStop() function is called. NC_NetStop() is called by the generated NetworkClose() function.
- 11. Run the **Network Close** (Global.networkCloseHook) hook function if one is configured. In this hook function, the application should shut down any operation it initiated in the Network Open hook function and free any allocated resources.
- 12. After the NetworkClose() function returns, NDK functionality is no longer available.
- 13. The original call to NC_NetStart() returns with the return value as set by the return parameter passed in the call to NC_NetStop().
- 14. The application can immediately reboot the NDK by calling *NC_NetStart()* again, with or without reloading a new configuration. This is useful for a reboot command.

When the system is ready for a final shutdown, the following actions are performed:

- When NC_NetStart() returns and the session is over, run the Stack Thread Delete (Global.stackDeleteHook) hook function if one is configured.
- 2. Call the CfgFree() function to free the configuration handle created with CfgNew().
- 3. After all resources have been freed, call the NC_SystemClose() function to complete the system shutdown.

4.2.2 Function Overview

The system initialization access functions (in functional order) are as follows:

NC_SystemOpen() Initiate a system session NC_SystemClose() Full system shutdown

NC_NetStart() Start the network with a supplied configuration

NC_NetStop() Halt the network, and pass a return code the caller of the NC_NetStart()

function



4.2.3 Network Control API Functions

NC_SystemOpen Initiate a System Session

Syntax int NC_SystemOpen(int Priority, int OpMode);

Parameters

Priority Network event scheduler task priority
OpMode Network event scheduler operating mode

Return Value Returns the status of the open call, zero on success, or one of the following on error.

NC_PRIORITY_HIGH.

NC_OPMODE_INTERRUPT. Or, attempt to combine NC_OPMODE_POLLING with NC_PRIORITY_HIGH.

NC_OPEN_MEMINIT_FAILED Memory initialization failed. NC_OPEN_EVENTINIT_FAILED Event initialization failed.

Description This is the first function that should be called when using the stack. It initializes the

stack's memory manager, and the OS (or OS adaptation layer). It also configures the

network event scheduler's task priority and operating mode.

Priority is set to either NC_PRIORITY_LOW or NC_PRIORITY_HIGH, and determines

the scheduler task's priority relative to other networking tasks in the system.

OpMode is set to either NC_OPMODE_POLLING or NC_OPMODE_INTERRUPT, and determines when the scheduler attempts to execute. The interrupt mode is used in the

vast majority of applications.

Note that polling operating mode attempts to run continuously, so when polling is used,

Priority must be set to NC PRIORITY LOW.

NC_SystemClose Shutdown the System

Syntax void NC_SystemClose();

Parameters None.

Return Value None.

Description This is the last function that should be called when using the stack. It shuts down the

memory manager and performs a final memory analysis.



NC_NetStart

Start Network

Syntax

int NC_NetStart(HANDLE hCfg, void (*NetStartCb)(), void (*NetStopCb)(), void (*NetIPCb)(IPN,uint,uint));

Parameters

hCfg Handle to network configuration

NetStartCb Pointer to callback function called when network is started
NetStopCb Pointer to callback function called when network is stopped

NetIPCb Pointer to callback function called when an IP address is added or removed from

the system

Return Value

Returns the integer value passed to NC_NetStop().

Description

This function is called to boot up the network using the network configuration supplied in hCfg. Along with the network configuration, three callback function pointers are provided. These callback functions are called at distinct times. *NetStartCb()* is called when the system is first ready for the creation of application supplied network tasks, *NetStopCb()* is called when the network is about to shut down, and *NetIPCb()* is called when an IP address is added or removed from the system. If any of these callback functions are not required, the function pointers can be set to NULL.

The NC_NetStart() function will not return until the entire network session has completed. Thus, all user supplied network code (creation of user tasks) should be included in the NetStartCb() function.

When *NetStartCb()* is called, the configuration handle supplied in *hCfg* is the default configuration handle for the system. The execution thread on which *NetStartCb()* is called is not critical to event scheduling, but it should return eventually; i.e., the application should not take control of the thread. If system shutdown is initiated before this callback function returns, some resources may not be freed.

Excluding critical errors, $NC_NetStart()$ will return only if an application calls the $NC_NetStop()$ function. The parameter passed to $NC_NetStop()$ becomes the return value returned by $NC_NetStart()$.

Sometime after $NC_NetStop()$ is called, but before $NC_NetStart()$ returns, the $NC_NetStart()$ thread will make a call to the application's NetStopCb() callback function. In this callback function, the application should shut down any task initiated in its NetStartCb() callback.

When an IP addressing change is made to the system, the *NetIPCb()* function is called. The callback function is declared as:

IPAddr IfIndex fAdd IP Address being added or removed

Index of physical interface gaining or losing the IP address

Set to 1 when adding an address, or 0 when removing an address

The NetIPCb() callback is purely informational, and no processing is necessary on the information provided.

There is an option for immediately calling *NC_NetStart()* again upon return, which provides a good stack reboot function. Optionally, the configuration can also be reloaded, which allows the stack to be restarted after a major configuration change.



NC_NetStop Stop Network

Syntax void NC_NetStop(int StopCode);

Parameters

StopCode Return code to be returned by NC_NetStart().

Return Value None.

Description This function is called to shut down a network initiated with *NC_NetStart()*. The return

value supplied in the StopCode parameter becomes the return value for NC_NetStart().

See the description of NC_NetStart() for more detail.



Network Tools Library - Support Functions

Included with the stack package is a library of network tools. It provides auxiliary functionality to the stack library and contains source written to the socket layer that would normally be considered application level code. The library file is called NETTOOLS.LIB, and can be accessed by an application that includes the file NETTOOLS.H.

The support supplied by NETTOOLS can be categorized into two classes: support functions and services. The support functions consist of a programming API that can aid the development of network applications, while services are servers that execute on the stack platform.

This section describes the NETTOOLS support functions. Please note that these services are all IPv4 based. Based on the IPv6 documentation, these applications can be easily re-written to use IPv6 sockets instead for communication.

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www.ti.com Generic Support Calls

5.1 Generic Support Calls

This section contains a selection of functions that can be very useful when programming network applications. Some are standard Berkeley Software Distribution (BSD) Socket APIs while others are custom to the stack - designed to save you the time and trouble of programming directly to the stack API.

5.1.1 Function Overview

The following is a summary of the support functions described in this section:

inet_addr() Convert a string to a 32 bit IP address in network format

inet_aton()

Convert a string to an *in_addr* structure record

NtAddNetwork()

Add a host network to a logical interface handle

NtRemoveNetwork()

Remove a network added with *NtAddNetwork()*Add a static gateway route to the route table

NtRemoveStaticGateway() Remove a static gateway route

Ntlfldx2lp() Get the IP host address assigned to a physical interface Index

NtGetPublicHost() Get the system public IP address and domain name NtIPN2Str() Convert 32 bit IP address in network format to string

5.1.2 Network Tools Support API Functions

inet_addr Return 32-bit Binary Network Ordered IPv4 Address

Syntax IPN inet_addr(char *strptr);

Parameters

strptr Pointer to character string

Return Value IP address or NULL.

Description This function converts an IP address printed in a character string to a 32-bit network

ordered IP address value. Note that leading 0s in the address string are interpreted as

octal. The function returns NULL on failure.

This function actually calls <code>inet_aton()</code>, which is the better form of the function.



inet_aton Convert IP Address from String and Return in in_addr Structure

Syntax int inet_aton(char *strptr, struct in_addr *pa);

Parameters

strptr Pointer to character string pa Pointer to address structure

Return Value 1 on success or 0 on failure.

Description This function converts an IP address printed in a character string to a 32-bit network

ordered IP address value. Note that leading 0s in the address string are interpreted as octal. The function return writes the IP address into the *in_addr* structure pointed to by

the pa parameter. The function returns 1 on success and 0 on failure.

NtAddNetwork Add Host Network to Interface by IF Handle

Syntax HANDLE NtAddNetwork(HANDLE hIF, IPN IPHost, IPN IPMask);

Parameters

hIF Handle to target interface

IPHost Address (in network format)
IPMask IP Host Subnet Mask (in network format)

Return Value Handle to network binding on success or NULL on failure.

Description This function attempts to add the specified IP host address (and mask) to the specified

logical interface handle. The function returns a handle to the binding that binds the IP address to the interface. On an error, the function returns NULL. The most common error would be that adding the host address caused a duplicate IP indication from

another host.

NOTE: In place of this function, consider using the configuration system with the

CFGTAG_IPNET configuration entry (see Section G.3.3).

NtRemoveNetwork Remove Host Network from Interface

Syntax void NtRemoveNetwork(HANDLE hBind);

Parameters

hBind Handle to network binding returned by *NtAddNetwork()*.

Return Value None.

Description This function removes a network that was previously added with *NtAddNetwork()*.



NtAddStaticGateway Add Static Gateway Route to the Route Table

Syntax HANDLE NtAddStaticGateway(IPN IPDestAddr, IPN IPDestMask, IPN IPGateAddr);

Parameters

IPDestAddr IP address of destination (in network format) **IPDestMask** IP subnet mask of destination (in network format) **IPGateAddr** IP address of next hop gateway (in network format)

Handle to newly created route or NULL on error. Return Value

This function adds a static gateway route to the system route table. Description

> IPDestAddr is the IP base address of the IP network of the network that is made accessible via the IP gateway. This value should be pre-masked with the IPDestMask so

that:

(IPDestAddr & IPDestMask) = IPDestMask

This is used as a sanity check by the system. For a default route, the value is zero.

IPDestMask is the mask of the IP network accessible by the IP gateway. For a host route, the value is 0xFFFFFFF, while for a default route, the value is zero.

IPGateAddr is the IP address of the gateway through which the specified IP network is accessible. It must be an IP address that is available on a locally connected network, i.e., one gateway cannot point to another.

The function returns a handle to the route created by this configuration entry. All routes are represented as route handles internally to the stack. This is discussed further in the appendices at the end of this document. Note that the handle returned here is not referenced (see the appendix for more details). All it means for the purposes of this function is that the handle can be discarded by the caller. It will remain valid until the route is removed via NtRemoveStaticGateway().

NOTE: In place of this function, consider using the configuration system with the

CFGTAG_ROUTE configuration entry (see Section G.3.4).

NtRemoveStaticGateway Remove Static Gateway Route from the Route Table

int NtRemoveStaticGateway(IPN IPTarget); **Syntax**

Parameters

IPTarget IP address of destination to remove (in network format)

Return Value Returns 1 if the route was removed, or 0 if it was not found.

Description This function removes a static gateway route from the system route table. It searches for

> the route by destination IP address and will remove the first matching static route it finds. Note that only routes with both the GATEWAY and STATIC flags set are considered for

removal.



Ntlfldx2lp Get the 32-bit Representation of the IP Address of an Interface Index

Syntax int Ntlfldx2lp(uint lfldx, IPN *pIPAddr);

Parameters

IfIdx Index of physical interface pIPAddr Pointer to receive IP address

Return Value Returns 1 if an address was found, or 0 if it was not found.

DescriptionThis function obtains the first IP host address found that is assigned to the supplied

interface Index. The host address (in network format) is written to the pointer pIPAddr.

NtGetPublicHost Get the System Public IP Address and Domain Name

Syntax int NtGetPublicHost(IPN *pIPAddr, uint MaxSize, UINT8 *pDomain);

Parameters

pIPAddr Pointer to receive IP address

MaxSize Size of string buffer pointed to by *pDomain*pDomain Pointer to string buffer to receive domain name

Return Value Returns 1 if information was found, or 0 if it was not found.

Description This function gets the best IP address and domain name to use for access to the

external network. For determining the best address and domain name, public addresses and domain names are preferred over IP addresses and domain names of virtual networks. The IP address (in network format) is written to *pIPAddr*, and the domain

name is copied to *pDomain*.

NtIPN2Str Convert 32-bit IP Address in Network Format to String

Syntax void NtIPN2Str(IPN IPAddr, char *pStrBuffer);

Parameters

IPAddr IP address in network format

pStrBuffer Pointer to receive IP address string

Return Value None.

Description This function performs a *sprintf()* of the IP address supplied in IPAddr to the buffer

supplied in *pStrBuffer*. Note that no buffer size is provided. This is because the size is deterministic, and will not exceed 16 characters (including the NULL terminator).



www.ti.com DNS Support Calls

5.2 DNS Support Calls

The concepts and code behind the Unix *gethostbyname()* and *gethostbyaddr()* functions is extensive, and there are public domain versions available, which can be easily run on the IP stack library.

Although the code to support the whole name, address and server database is quite large, the basic name resolution functions are quite useful. For this reason, the stack provides a basic form of these function calls, without incurring the overhead associated with a full implementation. The DNS resolver used by these client functions is the same as accessed by the DNS server. When the configuration contains client machine records (i.e., controls local domain names), these entries are checked when the matching domain is encountered. Otherwise (and for all other queries), the query is resolved via external DNS servers.

In addition to providing a more compact implementation, the calls provided here are reentrant, which is not true of the standard Unix counterparts.

5.2.1 Function Overview

The following is a summary of the support functions described in this section:

DNSGetHostname() Return the hostname of the current host DNSGetHostByAddr() Resolve a hostname from an IP address

DNSGetHostByName() Resolve a hostname and IP address from a hostname

5.2.2 Standard Types and Definitions

5.2.2.1 Host Entry Structure

The DNS client functions all take a pointer to a buffer. They treat this buffer as a pointer to a host entry structure. If the function takes a pointer to a scrap buffer, a host entry structure is allocated from the start of this scrap buffer. Thus, on successful return from one of these calls, the pointer to the scrap buffer may be treated as a pointer to a host entry structure.

The structure differs slightly from the conventional definition. It is defined as follows:



5.2.2.2 Function Return Codes

DNS functions that return an error code use the following definitions. Those that are obtained directly from a DNS response packet are so noted:

NOERROR 0 (DNS Reply Code) No error **FORMERR** 1 (DNS Reply Code) Format error 2 **SERVFAIL** (DNS Reply Code) Server failure

NXDOMAIN 3 (DNS Reply Code) Non existent domain **NOTIMP** 4 (DNS Reply Code) Not implemented **REFUSED** 5 (DNS Reply Code) Query refused

OVERFLOW 16 Scrap Buffer Overflow

Memory Allocation Error (used for packets and temp storage) **MEMERROR** 17

SOCKETERROR Socket Error (call *fdError()* for socket error number) 18

NODNSREPLY 19 No DNS server response

5.2.3 DNS Support API Functions

Return the Hostname of the Current Host DNSGetHostname

int DNSGetHostname(char *pNameBuf, int size); **Syntax**

Parameters

Pointer to a buffer to accept the hostname pNameBuf

Size of the supplied buffer in bytes size

Return Value Error code as defined above.

Description This function is quite similar to BSD's gethostname(). It requests the hostname of the

system's public IP address (as obtained from NtGetPublicHost()). The hostname is

copied into the buffer pointed to by pNameBuf with a maximum size of size. The name is

NULL terminated when space allows.



DNSGetHostByAddr Resolve a Hostname from an IP Address

Syntax int DNSGetHostByAddr(IPN IPAddr, void *pScrapBuf, int size);

Parameters

IPAddr IP address to resolve, in network format

pScrapBuf Pointer to a scrap buffer from which a HOSTENT structure will be allocated

size Size of the supplied scrap buffer in bytes

Return Value Error code as defined above.

Description This function is quite similar to BSD's *gethostbyaddr()*. It uses DNS to resolve a

hostname from the supplied IP address. On a successful return, *pScrapBuf* can be treated as a HOSTENT structure. The size of the scrap buffer (*size*) must be greater than the size of the structure as the structure will contain pointers into the scrap buffer, and the scrap buffer is also used for temporary name storage. 512 bytes should be

sufficient for most requests.

DNSGetHostByName Resolve a Hostname/Address from a Hostname

Syntax int DNSGetHostByName(char *Name, void *pScrapBuf, int size);

Parameters

Name Null terminated Hostname to resolve (with or without trailing '.')

pScrapBuf Pointer to a scrap buffer from which a HOSTENT structure will be allocated

size Size of the supplied scrap buffer in bytes

Return Value Error code as defined above.

Description This function is quite similar to BSD's *gethostbyname()*. It uses DNS to resolve an official

hostname and address from the supplied hostname. On a successful return, pScrapBuf can be treated as a HOSTENT structure. The size of the scrap buffer (size) must be greater than the size of the structure as the structure will contain pointers into the scrap buffer, and the scrap buffer is also used for temporary name storage. 512 bytes should

be sufficient for most requests.

If the hostname *Name* is terminated with a dot (.), the dot is removed prior to lookup. If a dot appears anywhere in *Name*, an initial lookup on the unaltered name is attempted. If *Name* does not contain a dot, or if the initial lookup fails, the default domain name (from *NtGetPublicHost()*) is appended to the end of the supplied name. For example, if the domain name obtained from *NtGetPublicHost()* was ti.com, then a request for host.sc would attempt to resolve host.sc first, and then host.sc.ti.com, while a request for host

would attempt to resolve host.sc.ti.com on the initial attempt.



TFTP Support www.ti.com

5.3 TFTP Support

TFTP is supported via the received function. More information on TFTP can be found in RFC783, released by the Internet Engineering Task Force (IETF) organization.

5.3.1 TFTP Support API Functions

TFTP is accessed through this API. The network tools include the file NETTOOLS.H, which is required.

NtTftpRecv	Retrieve Data from a TFTP Server	
Syntax	int NtTftpRecv(UINT32 TftpIp, char *szFileName, char *pFileBuffer, UINT32 *pFileSize, UINT16 *pErrorCode);	

Parameters

Tftplp	IP Address in network format
szFileName	Pointer to null terminated filename string
pFileBuffer	Pointer to buffer to receive file data
pFileSize	Pointer to size of buffer on input, returns as size needed or used
pErrorCode	Pointer to where to write TFTP server error code (if any)

Return Value This function returns an error code indicating the results of the operation. Negative

codes are error conditions.

In the following cases, *pFileSize* is set to the actual file size:

0 Successful transfer and copy

1 Successful transfer, with partial copy (file size too large)

In the following cases, *pFileSize* is set to the actual number of bytes copied:

TFTPERROR_ERRORREPLY	Error returned by TFTP server (see below)
TFTPERROR_BADPARAM	Invalid calling parameters
TFTPERROR_RESOURCES	Memory allocation error during transfer
TFTPERROR_SOCKET	Internal socket error during transfer
TFTPERROR_FAILED	TFTP failed (e.g., server did not reply)

In the case of TFTPERROR_ERRORREPLY, the server error code written to *pErrorCode should be one of the following standard TFTP codes, and the error message is copied to *pFileBuffer:

0	Not defined, see error message (if any).
1	File not found.
2	Access violation.
3	Disk full or allocation exceeded.
4	Illegal TFTP operation.
5	Unknown transfer ID.
6	File already exists.
7	No such user.



Description

TFTP (Trivial File Transfer Protocol), allows files to be transferred from a remote machine.

This function attempts to receive the file with the filename designated by *szFileName* from the TFTP server with the IP address in *TftpIp*, and copy the data into the memory buffer pointed to by *pFileBuffer*. Note that when specifying the name of the file in *szFileName*, certain operating systems have case sensitive naming conventions.

On entry, the parameter *pFileSize* must point to the size of the buffer pointed to by *pFileBuffer*. If the value at **pFileSize* is null, the *pFileBuffer* parameter can be NULL.

This function attempts to receive the entire file, even if the buffer space is insufficient. The return value indicates if the file was received.

A return value of 1 indicates that the file was received and copied into the buffer. A return value of 0 indicates that the file was received, but was too large for the specified buffer. In both these cases, the actual size of the file in bytes is written back to *pFileSize.

A negative return value indicates that an error has occurred during transfer. In this case, the number of bytes actually consumed in the buffer is written back to *pFileSize. An error return of TFTPERROR_ERRORREPLY is a special return value that indicates that an error code was returned from the TFTP server. In this case, the server's TFTP error code is written to *pErrorCode, and the server's TFTP error message string is copied to the data buffer pointer to by pFileBuffer.

5.4 TCP/UDP Server Daemon Support

A server daemon is a single network task that monitors the socket status of multiple network servers. When activity is detected, the daemon creates a task thread specifically to handle the new activity. This is more efficient than having multiple servers, each with their own listening thread.



5.4.1 Server Daemon Support API Functions

Entries in the server daemon are created and destroyed through the following APIs. The network tools include the file NETTOOLS.H, which is required.

DaemonNew Create a New TCP/UDP Server Entry

Syntax HANDLE DaemonNew(uint Type, IPN LocalAddress, uint LocalPort, int

(*pCb)(SOCKET,UINT32), uint Priority, uint StackSize, UINT32 Argument, uint

MaxSpawn);

Parameters

Type Socket type (SOCK_STREAM, SOCK_STREAMNC, or SOCK_DGRAM)

Local Address Local IP address (set to NULL for wildcard)
Local Port to serve (cannot be NULL)

pCb Pointer to callback to handle server event (connection or activity)

Priority Priority of new task to create for callback function
StackSize Stack size of new task to create for callback function
Argument (besides socket) to pass to callback function

MaxSpawn Maximum number of callback function instances (must be 1 for UDP)

Return Value This function returns a handle to a daemon, or NULL on error.

DescriptionOnce a new entry is created, the daemon will create the desired TCP or UDP socket, and start listening for activity.

and start listening for activity.

In the case of TCP, when a new connection is established, a new task thread is created, and a socket session is opened. Then the user's callback function is called on the new task thread, being supplied with both the socket to the new connection and the caller specified argument (as supplied to *DaemonNew()*). The callback function can keep the socket and task thread for as long as necessary. It returns from the callback once it is done with the connection. The function can choose to close the socket if desired. The return code informs the daemon whether the socket has been closed (0) or is still open (1).

In the case of UDP, when any data is available on the UDP socket, a new task thread is created, and a socket session is opened. Then the user's callback function is called on the new task thread, being supplied with both the UDP socket and the caller specified argument (as supplied to *DaemonNew()*). The callback function can keep the socket and task thread for as long as necessary. It returns from the callback only when it is done with the data. (While the callback function holds the UDP socket, the daemon will ignore further activity on it.) The callback should return 1, as it should not close the UDP socket.

DaemonFree Destroy a TCP/UDP Server Entry

Syntax void DaemonFree(HANDLE hEntry);

Parameters

hEntry Handle to server entry returned from *DaemonNew()*

Return Value None.

Description Destroys a daemon entry, and closes the socket session of all child tasks spawned from

the entry. Closing the socket sessions will result in all socket functions returning

SOCKET_ERROR in all spawned child tasks. Thus, all spawned tasks should error out

and return to the daemon, allowing them to be freed.



5.4.2 Server Daemon Example

The following is an example TCP echo server using the server daemon. The TCP server will use SOCK_STREAMNC for non-copy TCP. Its only job is to read from the socket, and write back what it reads.

To install the server on port 7, use the following code:

This code allows up to three echo sessions to be running simultaneously on different threads. Note the IP specified is NULL, allowing echo connection on any local IP address assigned to the system.

To destroy the server and all its instances, the hEcho handle returned from DaemonNew() is used:

```
DaemonFree( hEcho );
```

The code for the callback function dtask_tcp_echo() is as follows:

```
int dtask_tcp_echo( SOCKET s, UINT32 unused )
    struct timeval to;
    int I;
    char *pBuf;
    HANDLE hBuffer;
    (void)unused;
    // Configure our socket timeout to be 5 seconds
    to.tv\_sec = 5;
    to.tv_usec = 0;
    setsockopt( s, SOL_SOCKET, SO_SNDTIMEO, &to, sizeof(to) );
    setsockopt( s, SOL_SOCKET, SO_RCVTIMEO, &to, sizeof(to) );
    setsockopt( s, IPPROTO_TCP, TCP_NOPUSH, &I, 4 );
    for(;;)
    {
        I = (int)recvnc( s, (void **)&pBuf, 0, &hBuffer );
        // If we read data, echo it back
        if(I > 0)
        {
            if(send(s, pBuf, I, 0) < 0)
                break;
            recvncfree( hBuffer );
        }
        // If the connection got an error or disconnect, close
        else
           break;
    fdClose( s );
    // Return "0" since we closed the socket
    return(0);
}
```



Network Tools Library - Services

Included with the stack package is a library of network tools. It provides auxiliary functionality to the stack library and contains source written to the socket layer that would normally be considered application level code. The library file is called NETTOOLS.LIB, and can be accessed by an application that includes the file NETTOOLS.H.

The support supplied by NETTOOLS can be categorized into two classes: support functions and services. The support functions consist of a programming API that can help develop network applications, while services are servers that execute on the stack platform.

This section describes the NETTOOLS services. Note that these services are all IPv4 based. Based on the IPv6 documentation, these applications can be easily re-written to use IPv6 sockets instead for communication.

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6.1 Service Calling Conventions

6.1.1 Specifying Network Services Using the Configuration

If you are using XGCONF to configure your application, you can configure network services to be enabled in the application by checking the box in the property sheet to add the module to your configuration. See the SPRU523 (TI Network Developer's Kit (NDK) User's Guide.) and the context-sensitive help for details.

For use in legacy applications, this manual contains descriptions of the direct and configuration APIs used to add services to an application. If you are using XGCONF for configuration, you can ignore these APIs.

Although each service has it own specific API, it is usually more convenient to add services by specifying the service in the system configuration as opposed to calling their individual Open and Close API functions. Included in the description of each network service is a description of its direct API, as well as an example of specifying the service in the system configuration.

6.1.1.1 Service Report Function

All the configuration examples in this section use a common service report callback function. The following is a very simple implementation of a service report function that calls printf() to print service status.

Note that this function relies on the physical value of items in the configuration specification found in the file: inc\nettools\netcfg.h.

6.1.2 Invoking Network Services by NETTOOLS API

If you are using XGCONF to configure your application, you can configure network services to be enabled in the application by checking the box in the property sheet to add the module to your configuration. See the SPRU523 (TI Network Developer's Kit (NDK) User's Guide.) and the context-sensitive help for details.

For use in legacy applications, this manual contains descriptions of the APIs used to add services to an application. Calls to these APIs are generated automatically by the XGCONF configuration. If you are using XGCONF for configuration, you can ignore the APIs described here.

Each service API uses a common calling format. This allows the services to be invoked by the configuration system using callback functions provided in the Network Control software (which also performs system initialization). It is preferable to launch services via the configuration system, instead of manually calling each Open and Close function described in the following sections. However, because the source to the Network Control software uses these calls, they are documented here.

The common calling interface consists of a simple Open and Close concept. The Open function initiates the service and returns a service handle, while the Close function shuts down the service using the service handle returned from the Open call.

Each service Open call takes at least one parameter. This parameter is a pointer to a common argument structure called NTARGS. The specification of this structure is as follows:



Note that this entry structure is a simplified version of that provided by the configuration system. This structure also contains a callback function. The callback function is a subset of that in the configuration system, and codes returned by this callback are passed through the configuration callback to the application.

The individual fields are defined as follows:

• int CallMode;

This parameter determines how the service is launched, either by IP address or by interface index (1 to n). Some services can be launched either on a specific interface (1 to n) or on a specific IP address, which can also be the wildcard INADDR_ANY. Generally, any service that accepts an IP address can also accept an interface. The service will look up the IP address for the specified interface.

Other services can only be executed by interface and are independent of IP address. These are said to be compatible with NT_MODE_IFIDX only.

The value of *CallMode* can be one of the following:

NT_MODE_IFIDX Call by specifying the interface Index (1 to n)
NT_MODE_IPADDR Call by specifying IP address in network format

• int IfIdx;

This is the physical interface index (1 to n) on which the service is to be executed. For example, when launching a DHCP server service, the physical interface is that connected to the home network. For more generic services (like Telnet), the service can be launched by a pre-defined IP address (or INADDR_ANY as a wildcard). When launching by IP address only, this field is left NULL. When this field is used, *CallMode* should be set to NT MODE IFIDX.

• IPN IPAddr;

This is the IP address (in network format) on which to initiate the service. This IP address can specify the wildcard INADDR_ANY, in which case the service will accept connections to any valid IP address on any device. Note that some services (like DHCP server) do not support being launched by IP address. When this field is used, *CallMode* should be set to NT_MODE_IPADDR.

HANDLE hCallback;

This is the caller supplied handle that is passed back to the caller when the status callback function is invoked (see below).

void (*pCb)(HANDLE, uint);

This is a pointer to a caller supplied callback function by which the service reports status.

The specification of this callback is:

hCallback Handle supplied to the service by the caller

NtStatus NetTools Service Status code

The *NtStatus* parameter consists of an upper byte that is predefined, and a lower byte that is specific to the service. When masked with ~0xFF (NOT 0xFF), the value will be one of the following:

NETTOOLS_STAT_NONE. Nothing reported

NETTOOLS_STAT_RUNNING Service is initialized (running)

NETTOOLS_STAT_PARAMUPDATE The service parameter structure has changed (the

configuration containing this structure should be

saved)

NETTOOLS_STAT_COMPLETED The service has run to completion NETTOOLS_STAT_FAULT The service has halted due to a fault



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Note that this callback function does not go directly to the application when using the configuration system. These codes are supplied to the configuration service callback in the *Code* parameter.

An optional second parameter to each service Open function is a pointer to a private service parameter structure. In the configuration section of this document, the individual service parameter structures were included in the specification of the configuration entry instance structure for each service.

6.2 Telnet Server Service

If you are using XGCONF to configure your application, you can configure Telnet to be enabled in the application by checking the box in the property sheet to add the module to your configuration. See the SPRU523 (TI Network Developer's Kit (NDK) User's Guide.) and the context-sensitive help for details.

The Telnet Server service provides a mechanism for exposing a stream IO connection to any remote telnet client console.

A telnet connection is basically just a TCP connection to the well-known port designated for telnet. However, there is some data translation that occurs on the stream. Telnet has a set of commands that can change the behavior of the terminal, and can perform some character translation. The telnet server supplied here is designed to convert a normal TTY stream to a telnet stream and back. This allows any application to treat a telnet session as any other TTY session (like a serial port).

Connection to an application is achieved by use of an application supplied callback function that telnet calls when a new connection is established. This callback function returns the file descriptor of one end of a full duplex communications pipe. By allowing multiple calls to the callback function, console applications can be written to work with multiple IO streams.

6.2.1 Telnet Parameter Structure

This section describes a data structure that is generated automatically by the XGCONF configuration. If you are using XGCONF for configuration, you can ignore the structure described here.

The following structure defines the unique parameters of the Telnet service. It is located in the file: inc\nettools\inc\telnetif.h.

MaxCon Port Callback Maximum number of simultaneous telnet sessions (1 to 24) TCP port to use for Telnet (set to zero for Telnet default) Pointer to a callback function that takes a pointer to a sockaddr structure, and returns a local file descriptor to one end of a full duplex communications pipe

This structure is used both when specifying the service to the configuration system or when bypassing the configuration and invoking the service API directly.



6.2.2 Invoking the Service via NETTOOLS API

In addition to the configuration option, this service can also be created and destroyed directly through this NETTOOLS API. If an application wishes to bypass the configuration system and launch the service directly, these calls can be used.

TelnetOpen Create an Instance of the Telnet Server

Syntax HANDLE TelnetOpen(NTARGS *pNTA, NTPARM_TELNET *pNTP);

Parameters

pNTA Pointer to common argument structure used by all services

pNTP Pointer to Telnet parameter structure

Return Value Returns a handle to the new telnet server instance, or NULL if the service could not be

created. This handle is used with *TelnetClose()* to shut down the server when it is no

longer needed.

Description When a telnet session is established, a telnet child task is spawned that will call the

supplied callback function. This callback function should return a local file descriptor of one end of a full duplex pipe. If the callback function returns -1, the connection is aborted. When either the terminal or telnet connection end of the pipe is broken, the

other connection is closed and the session is ended.

TelnetClose Destroy an Instance of the Telnet Server

Syntax void TelnetClose(HANDLE hTelnet);

Parameters

hTelnet Handle to telnet server instance obtained from TelnetOpen()

Return Value None.

Description Destroys the instance of the telnet server indicated by the supplied handle. Once called,

the server is shut down and no further telnet sessions can be established. Also, all

spawned connections are immediately terminated.

6.3 DHCP Server Service

When acting as a router, the NDK may also need to maintain the network configuration on one of its network devices. A DHCP server allows the stack to maintain the IP address of multiple Ethernet client devices. When combined with Network Address Translation (NAT), the DHCP server can be used to establish client membership in a private virtual network.

If you are using XGCONF to configure your application, you can configure the DHCP server to be enabled in the application by checking the box in the property sheet to add the module to your configuration. See the SPRU523 (TI Network Developer's Kit (NDK) User's Guide.) and the context-sensitive help for details.

6.3.1 Operation

The DHCP server can be optionally configured to allocate IP addresses out of a pool that is specified by an IP base address and the number of addresses in the pool. If no pool is specified, the server will use static client entries in the configuration system to resolve client address requests.

The server will respond to DHCP requests from a single Ethernet device. This allows for isolation of clients for a given interface, and allows multiple instances of the DHCP server to manage different IP address pools for different interfaces.



6.3.2 DHCP Server Parameter Structure

This section describes a data structure that is generated automatically by the XGCONF configuration. If you are using XGCONF for configuration, you can ignore the structure described here.

The following structure defines the unique parameters of the DHCP server service. It is located in the file: inc\nettools\inc\dhcpsif.h.

Flags - Execution control flags. Can be any combination of the following:

DHCPS FLG LOCALDNS Causes DHCPS to report its own IP address as the local

DNS server to clients. If this flag is not set, DHCPS reports the DNS servers as contained in the SYSINFO

portion of the configuration.

DHCPS_FLG_LOCALDOMAIN Causes DHCPS to report the local domain name

assigned to the virtual network to clients. If this flag is not set, DHCPS reports the public domain name to clients.

- PoolBase The first IP address (in network format) of the address pool.
- PoolCount The number of addresses in the address pool.

This structure is used both when specifying the service to the configuration system or when bypassing the configuration and invoking the service API directly.

6.3.3 Invoking the Service via NETTOOLS API

In addition to the configuration option, this service can also be created and destroyed directly through this NETTOOLS API. If an application wishes to bypass the configuration system and launch the service directly, these calls can be used.

DHCPSOpen	Open a DHCP Server
Syntax	HANDLE DHCPSOpen(NTARGS *pNTA, NTPARAM_DHCPS *pNTP);
Parameters	
pNTA pNTP	Pointer to common argument structure used by all services. Pointer to DHCP parameter structure
Return Value	Returns a HANDLE to a DHCPS instance structure that is used in calls to other DHCPS functions like <i>DHCPSClose()</i> .
Description	This function is called to initiate DHCPS control of an IP address pool on a given interface. The base address of the address pool does not have to be the first IP address in the subnet.
	The DHCP Server executes on a specific interface. Thus, it is compatible with NT_MODE_IFIDX only.



DHCPSClose Close an Instance of the DHCP Server

Syntax void DHCPSClose(HANDLE hDHCPS);

Parameters

hDHCPS Handle to a DHCP server instance obtained from DHCPSOpen()

Return Value None.

Description This function is called to terminate DHCPS control of the previously supplied interface.

This call also destroys the supplied DHCP server instance handle hDHCPS.

6.4 DHCP Client Support

At system start up, the DHCP client will try and acquire an IP address from the DHCP servers available on the network.

Note that the client will accept the first IP address offered and that the INIT-REBOOT State (which requests a previously assigned IP address) is not currently implemented.

More information on DHCP can be found in RFC2131 and RFC2132, released by the Internet Engineering Task Force (IETF) organization.

If you are using XGCONF to configure your application, you can configure the DHCP client to be enabled in the application by checking the box in the property sheet to add the module to your configuration. See the SPRU523 (*TI Network Developer's Kit (NDK) User's Guide.*) and the context-sensitive help for details.

6.4.1 Operation

The DHCP client is a special service that always executes immediately in a system. It is usually after the DHCP client obtains a public IP address that most of the other services in the system can initialize.

The DHCP client code makes more use of the service status report callback function than most of the other services. Recall from the beginning of this section that the least significant byte of the report code is reserved for service specific information.

The following report codes are returned in the LSB of the report code sent by the DHCP service:

DHCPCODE_IPADD An IP client address had been added to the system

DHCPCODE_IPREMOVE An IP client address has been removed from the system

DHCPCODE_IPRENEW An IP client address has been renewed

Note that in each of the above cases, the DHCP portion of the system information configuration (the first 256 entries of CFGTAG_SYSINFO) has been erased and potentially reprogrammed. If an application needs to share the DHCP portion of the system information configuration, these DHCP report codes can be used to signal when to add additional application specific tags. For more information on DHCP and the CFGTAG_SYSINFO tag, see Section G.3.7.



6.4.2 DHCP Client Parameter Structure

This section describes a data structure that is generated automatically by the XGCONF configuration. If you are using XGCONF for configuration, you can ignore the structure described here.

The following structure defines the unique parameters of the DHCP client service. It is located in the file: inc\nettools\inc\dhcpif.h.

```
//
// DCHP Parameter Structure
//
#define DHCP_MAX_OPTIONS 64 // Max number of allowed options
typedef struct _ntparam_dhcp {
    UINT8 *pOptions; // Options to request
    int len; // Length of options list
} NTPARAM_DHCP;
```

pOptions Pointer to additional DHCP option tags to request. The list is used

when additional information must be obtained from the DHCP server. Up to DHCP_MAX_OPTIONS tags can be specified. This

pointer can be NULL when len is set to 0.

len Specifies the length in bytes of the list pointed to by pOptions.

This structure is used both when specifying the service to the configuration system or when bypassing the configuration and invoking the service API directly.

6.4.3 Invoking the Service via NETTOOLS API

In addition to the configuration option, this service can also be created and destroyed directly through this NETTOOLS API. If an application wishes to bypass the configuration system and launch the service directly, these calls can be used.

DHCPOpen	Open a DHCP Server		
Syntax	HANDLE DHCPOpen(NTARGS *pNTA , NTPARAM_DHCP *pNTP);		
Parameters			
pNTA	Pointer to common argument structure used by all services		
pNTP	Pointer to DHCP parameter structure		
Return Value	Returns a HANDLE to a DHCP instance structure, which is used in calls to other DHCP functions like <i>DHCPClose()</i> .		

Description This function is called to initiate DHCP control of a given device.

DHCPOpen() starts the DHCP process. This process will discover if there are any DHCP servers on the network and request an IP address. The result of the search for an IP address will be passed to the application via the standard network tools status callback.

The Client will remain running so it can renew the IP address when necessary.

For any additional option tags entered into the DHCP client parameter structure, the resulting information from the DHCP server is written to the system configuration under the CFGTAG SYSINFO entry. See Section G.3.7 for more information.

The DHCP Client executes on a specific interface. Thus, it is compatible with NT_MODE_IFIDX only.



DHCPClose Close an Instance of the DHCP Client

Syntax void DHCPClose(HANDLE hDHCP);

Parameters

hDHCP Handle to a DHCP server instance obtained from DHCPSOpen()

Return Value None.

Description This function is called to terminate DHCP control of the previously supplied interface and

frees the supplied DHCP server instance handle hDHCP.

Note this function will also remove any IP address it has added to the system. In the case of a service shutdown, there will be no status callback indicating the address

removal.

6.5 HTTP Server Support

An HTTP (Hypertext Transfer Protocol) Server allows a remote browser to view content on the server file system. Files can be stored for viewing and forms can also be stored to allow remote interaction with the system. Form POST functions become calls to application defined C functions that allow the embedded system to be remotely controlled via a HTTP browser.

If you are using XGCONF to configure your application, you can configure the HTTP server to be enabled in the application by checking the box in the property sheet to add the module to your configuration. See the SPRU523 (TI Network Developer's Kit (NDK) User's Guide.) and the context-sensitive help for details.

6.5.1 Operation

The HTTP Server service provides a mechanism for serving HTTP content to remote HTTP client applications. It uses the Embedded File System contained in the OS adaptation layer. These functions in the EFS programming API include a prefix of efs_. Modifying the EFS functions in the OS adaptation layer allows the system programmer to support a variety of file storage options, including memory, flash cards and hard drives.

6.5.2 HTTP Server Parameter Structure

This section describes a data structure that is generated automatically by the XGCONF configuration. If you are using XGCONF for configuration, you can ignore the structure described here.

The following structure defines the unique parameters of the HTTP server service. It is located in the file: inc\nettools\inc\httpif.h.

```
//
// HTTP Parameter Structure
//
typedef struct _ntparam_http {
    int MaxCon; // Max number of HTTP connections
    int Port; // Port (set to NULL for HTTP default)
} NTPARAM_HTTP;
```

MaxCon Maximum number of simultaneous telnet sessions (1 to 24)
Port TCP port to use for HTTP (set to zero for HTTP default)

This structure is used both when specifying the service to the configuration system or when bypassing the configuration and invoking the service API directly.



6.5.3 Using the HTTP Server and Adding Web Content

This section discusses how to invoke and monitor the status of the HTTP server. Web application developers will be more interested in how to add Web content, including HTML pages and CGI functions. These topics are discussed in Appendix E.

6.5.4 Invoking the Service via NETTOOLS API

In addition to the configuration option, this service can also be created and destroyed directly through this NETTOOLS API. If an application wishes to bypass the configuration system and launch the service directly, these calls can be used.

httpOpen	Start the HTTP Server
Syntax	HANDLE httpOpen(NTARGS *pNTA, NTPARAM_HTTP *pNTP);
Parameters	
pNTA pNTP	Pointer to common argument structure used by all services. Pointer to HTTP client parameter structure.
Return Value	Returns a handle to the HTTP Server instance, or NULL if the HTTP Server task could not be created. This handle is used with <code>httpClose()</code> to shut down the client when it is no longer needed.
Description	httpOpen() starts the HTTP server process. This process will create a connection to the HTTP Port and listen. When a connection is made, another task will be created to service the request.
httpClose	Destroy an instance of the HTTP Server
Syntax	void httpClose(HANDLE hHTTP);
Parameters	
hHTTP	Handle to a HTTP server instance obtained from httpOpen()

Return Value None.

Description Destroys the instance of the HTTP Server indicated by the supplied handle. Once called,

the Server is shut down.

6.6 DNS Server Service

The DNS server service allows clients on a home network to resolve host names and addresses for clients on both the home and public networks.

If you are using XGCONF to configure your application, you can configure the DNS server to be enabled in the application by checking the box in the property sheet to add the module to your configuration. See the SPRU523 (TI Network Developer's Kit (NDK) User's Guide.) and the context-sensitive help for details.



6.6.1 Operation

The NDK contains a small DNS resolver that can resolve hostnames and addresses that are local to the system via the configuration, or those outside the system by using an external DNS server.

The DNS server service described here allows the same internal DNS resolver to be accessed by clients on a virtual (home) network. This allows clients on a home network to look up peers on the home network using the same DNS server that is used for external lookups. Thus, DNS service for the home network is transparent to these clients.

Because the DNS server service uses the same internal DNS resolver as the client services discussed earlier, the server adds very little overhead to the system.

6.6.2 DNS Server Parameter Structure

The DNS server service does not require a parameter structure.

6.6.3 Invoking the Service via NETTOOLS API

In addition to the configuration option, this service can also be created and destroyed directly through this NETTOOLS API. If an application wishes to bypass the configuration system and launch the service directly, these calls can be used.

DNSServerOpen	Create an Instance of the DNS Serve	r
---------------	-------------------------------------	---

Syntax HANDLE DNSServerOpen(NTARGS *pNTA);

Parameters

pNTA Pointer to common argument structure used by all services.

Return Value Returns a handle to the new server instance, or NULL if the service could not be

created. This handle is used with DNSServerClose() to shut down the server when it is

no longer needed.

Description Creates a DNS server task that can service external DNS requests using UDP.

DNSServerClose Destroy an Instance of the DNS Server

Syntax void DNSServerClose(HANDLE hDNSS);

Parameters

hDNSS Handle to DNS server instance obtained from DNSServerOpen()

Return Value None.

Description Destroys the instance of the DNS server indicated by the supplied handle. Once called,

the server is shut down. It waits for all spawned sessions to complete.

6.7 Network Address Translation (NAT) Service

The NAT service allows for the establishment of a home virtual network that is isolated and protected from the external public network. It provides a port based address translation function that allows all the clients on the home network to share a single public IP address. Thus, multiple clients can share the same ISP account.

If you are using XGCONF to configure your application, you can configure the NAT service to be enabled in the application by checking the box in the property sheet to add the module to your configuration. See the SPRU523 (TI Network Developer's Kit (NDK) User's Guide.) and the context-sensitive help for details.



6.7.1 Operation

The NDK contains both a network address translation module and an IP filtering model. When the translation service is enabled, any packet received from a client on a virtual network that is destined for the external public network is adjusted to use the stack's public IP client address.

The translation is performed by allocating a translation record and holding it for a period of time. The translation records are timed out based on their protocol. In TCP, records are timed out based on the state of their TCP connection. UDP and ICMP translations time out based on when they were last used.

In addition to translation, the stack contains an IP filter option (always enabled by this service) that filters packets from the public network from being seen by the private network. For example, if someone on a public network knew the IP address and the subnet mask of the router's (stack in route mode) private network, it could set a gateway route to the router's public IP host address and the router would route packets from the public to the private network and back (internally it does not distinguish between public and private while routing). The IP filter prevents this. It also prevents an entity on a public network from accessing protocol servers (like HTTP or Telnet) that are running on the private network. This allows the router to present different HTTP or Telnet interfaces to the public than it does to clients in the home.

The NAT service is executed on the public interface - i.e., the interface that is assigned a valid public IP host address (used to carry traffic for the virtual client addresses). There can only be one instance and thus only one public IP address, but the service can serve multiple virtual (home) networks in the system so long as they can be combined and still exclude the public IP. If the combination of these networks results in an overlap with the public network, the service fails.

For example, assume interface If-1 is connected to the physical network 128.32.12.x/255.255.255.0, and there are two home networks (192.168.0.x/255.255.255.0) on If-2 and (192.168.1 .x/255.255.255.0) on If-3. To run NAT on both home networks, the NAT interface would be If-1 (the public interface), and the NAT group (virtual) network would be 192.168.0.0/255.255.254.0, which covers both home networks.

For more information on NAT operation, including how to program proxy filters, see Appendix B, Network Address Translation.

6.7.2 NAT Server Parameter Structure

This section describes a data structure that is generated automatically by the XGCONF configuration. If you are using XGCONF for configuration, you can ignore the structure described here.

The following structure defines the unique parameters of the NAT server service. It is located in the file: inc\nettools\inc\natif.h.

IPVirt NAT Group virtual network address

IPMask Subnet mask of NAT Group virtual network

MTU IP MTU Limit (1500 for Ethernet, 1492 for PPPoE, etc.)

This structure is used both when specifying the service to the configuration system or when bypassing the configuration and invoking the service API directly.

6.7.3 Invoking the Service via NETTOOLS API

In addition to the configuration option, this service can also be created and destroyed directly through this NETTOOLS API. If an application wishes to bypass the configuration system and launch the service directly, these calls can be used.



NATOpen Enable the NAT Service

Syntax HANDLE NATOpen(NTARGS *pNTA, NTPARAM_NAT *pNTP);

Parameters

pNTA Pointer to common argument structure used by all services.

pNTP Pointer to NAT parameter structure.

Return Value Returns a handle to the NAT instance (1), or NULL if the service could not be created.

This handle is used with NATClose() to disable the service when it is no longer needed.

Description Enables the Network Address Translation Service. Although the function returns a

handle for compatibility with the standard NETTOOLS API, only one instance of the NAT

service is allowed.

This service utilizes the virtual and external network information using the configuration

system. If the configuration system was not used to create the network records, this

function will fail.

The NAT service executes on a specific public interface. Thus, it is compatible with

NT MODE IFIDX only.

NATClose Disable the NAT Service

Syntax void NATClose(HANDLE hNAT);

Parameters

hNAT Handle to NAT service obtained from NATOpen()

Return Value None.

Description Disables the NAT service.



Internal Stack Functions

In the source code to the network control functions, there are several calls to internal stack functions. This is similar to calling the kernel in other operating environments. This section contains a partial list of internal stack functions provided to aid in the comprehension of kernel oriented calls.

Note the following points for this section:

- 1. This section is required only for system programming that needs low level access to the stack for configuration and monitoring. This API does not apply to general sockets application programming.
- 2. In addition to the internal functions described here, there are scheduling and configurations tools available that make any direct coding to these functions unnecessary.

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A.1 Overview

The control API is the collection of functions supplied in the stack library. The entire API is exposed, although the vast majority of functions and objects will only be used internally to the stack.

A.1.1 Interrupts and Preemption

It should be noted that no part of the stack is interrupt driven. Neither can any stack function be called at interrupt time. All interrupt processing is performed in the HAL or OS libraries, and is thus externally-defined code, which allows the development of a HAL/OS architecture that is best suited for a given operating environment, without affecting the operation of the stack.

The stack may or may not be preempted, depending on the operating environment in use. A non-preemptive architecture is possible because the stack code does not use polling loops nor make any internal blocking type calls, but preemption is also supported.

A.1.2 Proper Use of the ||Enter() and ||Exit() Functions

The internal stack functions are not designed to be reentrant. This allows the stack to operate freely without the concept of a critical section, which is implementation dependent and potentially detrimental to real-time operation. Thus, access to stack functions must be strictly controlled. The form of this control is dependant on the system environment, and is embodied as two low level OS library functions, *IlEnter()* and *IlExit()*. These functions are called before and after a section of code where any stack functions are called. For example:

```
llEnter();
StackFunction1();
StackFunction2();
llExit();
```

These functions can be thought of as entering and exiting kernel mode.

To make normal user functions appear to be re-entrant, some user functions (like the sockets API) make internal calls to <code>//Enter()</code> and <code>//Exit()</code> when calling into the stack. If an application needs to call both user functions and internal stack functions, care must be taken so that standard user functions are not called between an <code>//Enter() / IlExit()</code> pair (this would cause an error if they in turn called <code>//Enter()</code>).

The following are good general guidelines:

- Always call IIEnter() before calling a stack function, and IIExit() when done calling stack functions.
- Try and keep all code that requires *IlEnter()* and *IlExit()* in a single module. They are only required for system maintenance.
- Do not call a normal user function (like a socket function) between an IIEnter()/IIExit() pair.
- Never call IIEnter() or IIExit() from an ISR.

A.1.3 Objects

Many of the control API functions deal with object handles. These handles are created by a variety of class functions contained in the stack. When using an object handle, it is important to realize how the object handle will be treated by the function being called.

Associated with every object is the concept of who owns it, who is using it, and who will eventually free it. In general, when an application creates an object, the application owns it, the application is the only one using it, and the application must eventually free it. Unfortunately, the matter becomes somewhat confused when object handles are shared between applications — especially when the scope of the handle creator may be shorter than the handle itself.



www.ti.com Stack Executive (Exec)

In this system, there are two basic object types:

Static Objects - The static object is one that is created by a designated task, and destroyed by that
task or a task where the object has been passed. In most cases, the task that created the object also
destroys it.

Referenced Objects - A referenced object is one that may be used by other tasks after the original creator is through with it. This type of handle is useful when an object is needed for a task of indeterminate length, where the creator of the handle does not need or may not be able to track it.
 Under the referenced handle scheme, all tasks that access the object handle make a specific RefXxx() call so that references may be tracked. Whenever a task is finished with the handle, it calls the object's de-reference function. The object is not freed until the reference count reaches zero.

A.2 Stack Executive (Exec)

At the heart of the stack is the Executive API (Exec). The Executive acts as a message dispatcher for the internal stack components. This action is mostly hidden from the application, but there are some public functions.

A.2.1 API Functions

_ ^		. –
ExecOpen	Prepare the System t	for Execution

Syntax void ExecOpen();

Description Prepares the stack for execution by initializing the individual components. Until

ExecOpen() is called, the system cannot do any work, but after calling this function,

objects like routes and bindings can be created.

ExecClose Shutdown Stack and Cleanup

Syntax void ExecClose();

Description Completes stack execution. This function is called to perform final clean up on the

system after all user objects (like devices and bindings) have been destroyed.

ExecLowResource Signal Low Resource Condition

Syntax void ExecLowResource();

Description Informs the stack that memory resources are getting dangerously low. As a result of this

call, the stack will abandon certain operations that hold excessive resources. (Pending ARP packets are thrown away, IP packet fragments pending reassembly are abandoned,

etc.)

ExecTimer Signal 1/10th Second Timer Tick

Syntax void ExecTimer();

Description This function is called ten times a second to inform the stack that one tenth of a second

has elapsed. This function is called from a normal task thread, never an ISR. In theory, the function can be called from anywhere, but in practice, it is always called from a scheduler thread that also handles network packets. For more information, see the description of the NETCTRL functions in the *TI Network Developer's Kit (NDK) User's*

Guide (SPRU523).



A.3 Packet Buffer Manager (PBM) Object

The NDK uses a common packet buffer object that is managed by a module called the Packet Buffer Manager (PBM). The implementation of this manager determines the buffer strategy for the entire system.

Internally, the packet buffer objects are pointers to a structure of type PBM_Pkt; however, the buffers are abstracted into a handle of type PBM_Handle for use by code outside of the NDK. This helps protect the reserved members of the packet buffer structure from being misused.

If you are using XGCONF to configure your application, you can configure the size and location of the buffers managed by the PBM in the **Buffers** page of the NDK Global module configuration. See the SPRU523 (*TI Network Developer's Kit (NDK) User's Guide.*) and the context-sensitive help for details.

A.3.1 Object Type

Static - PBM objects are owned by a single entity and destroyed by their owner. Ownership of a packet buffer changes as it is passed via function calls.

A.3.2 API Function Overview

The PBM API functions are as follows:

Initialization/Shutdown Functions:

PBM_open() Open the Packet Buffer Manager PBM_close() Close the Packet Buffer Manager

Create/Destroy Functions:

PBM_alloc() Create New Packet Buffer
PBM_free() Destroy (Free) Packet Buffer

PBM_copy() Create an exact copy of the Packet Buffer

Property Functions:

PBM_getBufferLen() Get the length of the physical data buffer

PBM_getDataBuffer() Get a pointer to the physical data buffer

PBM_getValidLen() Get the length of the valid data in the buffer

PBM_getDataOffset() Get the buffer offset to the start of the valid data

PBM_getIFRx() Get the device handle of the ingress Ethernet device

PBM_setValidLen() Set the length of the valid data in the buffer PBM_setDataOffset() Set the buffer offset to the start of the valid data PBM_setIFRx() Set the device handle of the ingress Ethernet device



A.3.3 API Function Description

PBM_open Open the Packet Buffer Manager

uint PBM open(); **Syntax**

Parameters None.

Function returns 1 on success, and 0 on failure. Return Value

This function is called once to open the PBM module and allow it to initialize its internal Description

queues.

PBM_close Close the Packet Buffer Manager

Syntax void PBM close();

Parameters None. **Return Value** None.

This function is called at system shutdown to allow the PBM module to shut down and Description

free any memory it has allocated.

PBM_alloc Create New Packet Buffer

PBM_Handle PBM_alloc(uint MaxSize); **Syntax**

Parameters

MaxSize Maximum size of the physical data buffer required

Return Value Handle to the packet buffer or NULL on memory allocation error.

Description This function is called to create a new packet buffer handle. When first created, the

packet is entirely uninitialized, except for the physical characteristics of the data buffer (the buffer pointer and its physical length). The length of the buffer will be the same or

greater than that specified by the caller in MaxSize.

PBM free Destroy (Free) Packet Buffer

void PBM_free(PBM_Handle hPkt); **Syntax**

Parameters

hPkt Handle to packet buffer to free

Return Value None.

Description This function is called to destroy a packet buffer. When called, all objects associated

with the packet buffer are dereferenced or destroyed.



PBM_copy Create an exact copy of the Packet Buffer

Syntax PBM_Handle PBM_copy(PBM_Handle hPkt);

Parameters

hPkt Handle to packet buffer to copy

Return Value Handle to the new copy of the packet buffer or NULL on memory allocation error.

Description This function makes a duplicate copy of a packet buffer. It is usually called to copy a

packet to be distributed to multiple destinations, or to be sent to multiple egress devices.

PBM_getBufferLen Get the Length of the Physical Data Buffer

Syntax uint PBM_getBufferLen(PBM_Handle hPkt);

Parameters

hPkt Handle to packet buffer

Return Value Length of the physical data buffer in bytes.

Description This function is called to get the length of the physical data buffer associated with the

packet buffer handle. Note that the buffer length is fixed for the life of the buffer and

cannot be changed.

PBM_getDataBuffer Get a Pointer to the Physical Data Buffer

Syntax UINT8 * PBM_getDataBuffer(PBM_Handle hPkt);

Parameters

hPkt Handle to packet buffer

Return Value Pointer to the physical data buffer.

Description This function is called to get a pointer to the physical data buffer associated with the

packet buffer handle. Note that the physical buffer is fixed and cannot be changed.

PBM getValidLen Get the Length of the Valid Data in the Buffer

Syntax uint PBM_getValidLen(PBM_Handle hPkt);

Parameters

hPkt Handle to packet buffer

Return Value Byte length of the valid data stored in the packet buffer.

DescriptionThis function is called to get the length of the valid data currently held in the packet

buffer. When a packet buffer is created, it has no valid data, so this value is initially zero.



PBM_getDataOffset Get the Buffer Offset to the start of the Valid Data

Syntax uint PBM_getDataOffset(PBM_Handle hPkt);

Parameters

hPkt Handle to packet buffer

Return Value Byte offset from the start of the physical data buffer to the first byte of valid data.

Description This function is called to get the offset in bytes from the start of the physical data buffer

to the first byte of valid data. When a packet buffer is created, it has no valid data, so

this value is initially zero.

PBM_getIFRx Get the Device Handle of the Ingress Ethernet Device

Syntax HANDLE PBM_getIFRx(PBM_Handle hPkt);

Parameters

hPkt Handle to packet buffer

Return Value NULL for locally created packets, or a handle to the device on which the packet was

received.

Description This function is called to get the handle to the ingress device where the packet contained

in the packet buffer originated. Packet drivers in the HAL (both serial and Ethernet based) record the logical handle associated with all incoming packets. This identifies the

packet type as well as the interface on which the packet was received.

PBM_setValidLen Set the Length of the Valid Data in the Buffer

Syntax void PBM_setValidLen(PBM_Handle hPkt, uint length);

Parameters

hPkt Handle to packet buffer

length Length of the valid data held in the packet buffer

Return Value None.

Description This function is called to set the length of the valid data in the packet buffer. It informs

the system of the number of bytes of valid data that are stored in the physical data buffer. When a packet buffer is created, it has no valid data, so this value is initially zero.



PBM_setDataOffset Set the Buffer Offset to the Start of the Valid Data

Syntax void PBM_setDataOffset(PBM_Handle hPkt, uint offset);

Parameters

hPkt Handle to packet buffer

offset Offset from start of data buffer to valid data

Return Value None.

Description This function is called to set the offset in bytes from the start of the physical data buffer

to the first byte of valid data. It informs the system of where valid data is stored in the physical data buffer. When a packet buffer is created, it has no valid data, so this value

is initially zero.

PBM_setIFRx Set the Device Handle of the Ingress Ethernet Device

Syntax void PBM_getIFRx(PBM_Handle hPkt, HANDLE hDevice);

Parameters

hPkt Handle to packet buffer

hDevice Handle to packet ingress device

Return Value None.

Description This function is called to set the handle to the ingress device where the packet contained

in the packet buffer originated. Packet drivers in the HAL (both serial and Ethernet based) record the logical handle associated with all incoming packets. This identifies the

packet type, as well as the interface on which the packet was received.

A.4 Packet Buffer Manager Queue (PBMQ) Object

The PBM module also includes a queue object that can be used to queue packet buffers for later use. The queue is a first in first out system, so it can be used to queue in-order packets as well as free buffers.

The PBMQ object is just a structure of type PBMQ. Once this structure is declared and initialized, it is ready for use.

A.4.1 Object Type

Static - PBMQ objects are owned by a single entity and destroyed by their creator.

A.4.2 API Function Overview

The PBM API functions are as follows:

PBMQ_init() Initialize a PBMQ object for use

PBMQ_count() Return the number of PBM packet buffers on the queue

PBMQ_enq() Enqueue a PBM packet buffer onto the queue PBMQ_deq() Dequeue a PBM packet buffer off the queue



A.4.3 API Function Description

PBMQ_init Initialize a PBMQ Object for Use

Syntax void PBM init(PBMQ *pQ);

Parameters

pQ Pointer to a structure of type PBMQ

Return Value None.

Description This function is called once to initialize a PBMQ structure for use.

PBMQ_count Return the Number of PBM Packet Buffers on the Queue

Syntax uint PBM_count(PBMQ *pQ);

Parameters

pQ Pointer to a structure of type PBMQ

Return Value Number of queued buffers.

Description This function is called once to return the number of PBM packet buffers currently on the

indicated queue.

PBMQ_enq Enqueue a PBM Packet Buffer onto the Queue

Syntax void PBM_enq(PBMQ *pQ, PBM_Handle hPkt);

Parameters

pQ Pointer to a structure of type PBMQ

hPkt Handle to PBM packet buffer to add to queue

Return Value None.

Description This function is called to add the supplied PBM packet buffer to the indicated queue.

PBMQ_deq Dequeue a PBM Packet Buffer Off the Queue

Syntax PBM Handle PBM deg(PBMQ *pQ);

Parameters

pQ Pointer to a structure of type PBMQ

Return Value Handle to PBM packet buffer, or NULL on empty queue.

Description This function is called to remove a PBM packet buffer from the indicated queue. The

function returns a handle to the PBM packet buffer removed from the queue, or NULL if

the queue was empty.



A.5 Jumbo Packet Buffer Manager (Jumbo PBM) Object

The PBM object is capable of handling memory allocations only up to buffer sizes of maximum MMALLOC_MAXSIZE (3068 bytes). For handling memory allocation for jumbo frames, i.e., packets typically larger than 1500 bytes in size, and that could be as large as 10K bytes, the PBM object invokes the Jumbo PBM APIs internally. The Jumbo PBM is responsible for handling memory allocation and deallocation for Jumbo frames.

The following are some of the main features of Jumbo PBM:

- The Jumbo PBM implementation is similar to the PBM implementation, except that it can handle larger block sizes than the ones in PBM and ranges between 3K and 10K bytes by default.
- Jumbo PBM does not use any SYS/BIOS APIs or dynamic memory allocation method for its memory allocation and, therefore, can be used safely in interrupt context. It uses a static memory allocation method, i.e., it reserves a chunk of memory in the far section of the device memory and uses it to allocate for the packet buffers required.
- The Jumbo PBM allocates memory off a separate section in the memory than the PBM. The PBM uses
 the memory sections NDK_PACKETMEM, NDK_MMBUFFER for its memory allocation. On the other
 hand, Jumbo PBM defines and uses a section called NDK_JMMBUFFER for its memory allocation.
 The size of this section and its placement are all customizable by an application user.
- A sample implementation of the Jumbo PBM is provided in the NDK OS abstraction layer (OS AL). The
 customer is expected to customize this implementation according to their application needs and
 system's memory constraints. The memory section sizes, block sizes, and the allocation method is all
 up for customization.
- Jumbo PBM APIs are not expected to be invoked directly. The application and driver must call the PBM_alloc()/PBM_free() APIs only. These APIs in turn invoke the Jumbo PBM APIs to allocate/cleanup memory if the memory requested is larger than what PBM can handle, i.e., 3K bytes.

For a sample implementation of the Jumbo PBM, refer to the source file JUMBO_PBM.C under \SRC\OS \JUMBO PBM.C.

A.5.1 API Function Overview

The Jumbo PBM API are as follows:

_jumbo_mmInit() API to initialize the Jumbo PBM object

jumbo_mmAlloc() Allocates memory requested for the new packet buffer

jumbo_mmFree() Frees up the memory held in the packet buffer

_iumbo_mmCheck() Dump the current memory usage in Jumbo PBM object

A.5.2 API Function Description

ĺ	iumbo mmln	it <i>Initializ</i>	e the Jumbo	PBM ob	ject for use.

Syntax int _jumbo_mmInit();

Parameters None

Return Value Always returns 1 to indicate success.

Description This function is called during the system initialization to initialize the Jumbo PBM

memory and any relevant data structures.



jumbo_mmAlloc Allocate a new Jumbo packet buffer.

Syntax void *jumbo_mmAlloc(uint Size);

Parameters Size Size of the packet buffer to allocate.

Return Value Pointer to the newly allocated packet buffer.

Description This function is called by the PBM object when an application/driver requests for a

packet buffer larger than what it can handle, i.e., MMALLOC_MAXSIZE (3068 bytes). This API allocates memory out of jumbo memory pool and returns a pointer to the packet

buffer just allocated.

jumbo_mmFree Frees up memory held by the packet buffer.

Syntax void jumbo_mmFree(void *p);

Parameters Handle to the packet buffer that was obtained earlier using jumbo_mmAlloc API and that

needs to be freed up.

Return Value None

Description This API returns the packet buffer to the jumbo memory pool for use again by the

application. The packet buffer handle passed as an argument to this function must be a

valid handle obtained using jumbo_mmAlloc() API earlier.

_jumbo_mmCheck Dumps the memory usage stats for jumbo PBM object.

Syntax void _jumbo_mmCheck(uint CallMode, int (*pPrn)(const char *,...));

Parameters

CallMode Specifies the type of stats that need to be printed out

The 3 supported call modes are:

MMCHECK MAP Map out allocated memory, but don't dump IDs

MMCHECK_SHUTDOWN Dump all allocated blocks and free pPrn Callback function pointer to be notified

Description This function iterates through the Jumbo PBM object's memory allocation table and

dumps the current memory usage stats according to the arguments specified.



A.6 Stack Event (STKEVENT) Object

Although technically not part of the NDK, the STKEVENT event object is a central component to the low level architecture. It ties the HAL layer to the network scheduler thread. The network scheduler thread waits on events from various device drivers in the system including the Ethernet, serial, and timer drivers. The device drivers use the STKEVENT object to inform the scheduler that an event has occurred.

A.6.1 Object Type

Static - The STKEVENT object is created and owned by the network scheduler.

A.6.2 API Function Overview

The STKEVENT object is implemented entirely via #define MACROs and therefore, does not have a true API. This allows the network scheduler to present an abstracted API to the HAL layer for network events. The STKEVENT object is a simple structure and manipulated directly by the network control module (NETCTRL). This is discussed further in the TI Network Developer's Kit (NDK) User's Guide (SPRU523).

The two MACRO functions are as follows:

Property Functions:

STKEVENT_init() Initialize a new STKEVENT object to NULL STKEVENT_signal() Signal a new STKEVENT event code

A.6.3 API Function Description

STKEVENT_init Initialize a new STKEVENT object to NULL

Syntax void STKEVENT_init(STKEVENT_Handle hEvent, Semaphore_Handle hSem)

Parameters

hEvent Handle to STKEVENT object

hSem Handle to Semaphore object to use in STKEVENT (if any)

Return Value None.

Description This function is called once to initialize the STKEVENT object so it is ready for use.

NOTE: This function is implemented as a multi-line macro, so care should be

taken when using it in the body of an if/else statement.



STKEVENT_signal Signal a New STKEVENT Event Code

Syntax void STKEVENT_signal(STKEVENT_Handle hEvent, uint EventCode, uint fHwAsynch)

Parameters

hEvent Handle to STKEVENT object EventCode Type of event being signaled

fHwAsynch Flag indicating event triggered by an asynchronous hardware event (e.g., ISR,

PRD).

Return Value None.

Description This function is called from a device driver to signal an event to the network scheduler

for further processing. The STKEVENT handle *hEvent* is an event handle supplied to the device driver when the driver is first initialized. The *EventCode* parameter specifies the

type of event. The currently defined events include the following:

STKEVENT TIMER 100 ms Timer Tick Event

STKEVENT_ETHERNET One or more Ethernet packets received STKEVENT_SERIAL One or more serial packets received

The *fHwAsynch* flag specifies whether the event was triggered by an external asynchronous hardware source. Examples of asynchronous events include hardware interrupts or timer PRDs. An example of a non-asynchronous event would be detecting an event from within a driver service check function. Service check functions are called periodically (or polled) by the scheduler.

NOTE:

This function is implemented as a multi-line macro, so care should be

taken when using it in the body of an if/else statement.

A.7 Link Layer Information (LLI) Object

To make full use of the stack objects described in this section, it is necessary to understand some of the stack's basic building block components. One such component is the Link Layer Information Object, or LLI for short.

An LLI object is an ARP table entry. This implementation of the IP stack combines the traditional route table and ARP table into a single table with a single API. Routes that need to use the ARP function include an ARP status object, called LLI. Normally, you only use an LLI object to inspect the ARP status of the route table.



The ARP entries can be of two types:

Dynamic

These ARP entries are managed using the Address Resolution Protocol (ARP), i.e., through exchange of ARP Request and ARP Reply messages between the NDK stack and the networking device engaged in communication with it. These entries are dynamic and have a keep-alive timeout associated with them. An ARP/LLI entry's lifetime is extended using ARP revalidation logic if it has been active, i.e., if it has been used by an application in the system in the last ARP inactivity timeout seconds. These keep-alive and ARP inactivity timeouts are configurable in NDK and can be tuned as per the application and system needs. However, if the ARP entry was inactive or idle, or if the ARP revalidation process failed, the ARP entry is deleted and the communication between the NDK stack and the networking device in question is broken unless it is re-established using ARP protocol again. To configure a dynamic ARP entry, the NDK stack internally uses the LLIValidateRoute() API. This API is documented in the following section.

Static

On the other hand, static entries are ARP entries that are manually configured by an application in the stack and they have no timeout associated with them. They remain valid until the application or user deletes them. No ARP request-reply transactions are performed here.

Both the dynamic and static ARP entries are supported in NDK stack, however there were no clear APIs defined earlier for configuration of the Static ARP entries. Such support has now been added to the NDK stack. The next section discusses the APIs exported by NDK stack to configure dynamic and static ARP entries.

A.7.1 ARP Revalidation Logic

Each dynamic LLI/ARP entry in NDK is associated with a non-zero Keep-alive timeout (controlled using CFGITEM_IP_RTKEEPALIVETIME). This timeout determines the length of time in seconds that an LLI entry and its associated route entry is valid. The routing module in the stack internally runs a timer and periodically checks to see if any routes or associated LLI entries are about to expire. If it finds a route/LLI entry that is about to expire, it checks to see if that LLI entry is active, i.e., if it has been used in the last Route Inactivity timeout seconds (configured using CFGITEM IP RTARPINACTIVITY). If so, the LLI module initiates an ARP Request/Reply exchange to revalidate the LLI entry even before it expires and disrupts any ongoing communication. If an ARP reply is received successfully for the request sent out earlier, the LLI entry is marked valid again for another Keep-alive timeout seconds and any packets using the route/LLI entry are sent out of the device. However, if no ARP reply is received, the ARP request is retransmitted and this process is repeated 3 times before the revalidation process is aborted and the associated LLI/Route entries are deleted. Also, if the LLI/Route entry was inactive or never used in the last Route Inactivity Timeout seconds ARP revalidation process is not done for such an entry and is deleted immediately from the system. Once the LLI/Route entries are deleted they have to be re-established using a successful ARP Request-Reply exchange triggered by an application's attempt to transmit packets to the intended destination.

A.7.2 Object Type

Static - LLI objects are owned and destroyed by their creator.



A.7.3 Information Structure

The following data structure is used to hold information regarding an ARP/LLI entry in the NDK stack. This structure is especially useful in presenting the LLI entry info in a simple, compact way to an application requesting information about the LLI entries configured in the stack.

```
/**
* @brief
   This structure describes the LLI/ARP Information Object.
* @details
 * This data structure is used by the LLI module to populate
  LLI/ARP Entry information contained in the NDK Kernel
 * in a simple, user-friendly way to the application.
* /
typedef struct _lli_info
    * @brief Links to other LLI_INFO Objects
   LIST_NODE Links;
     * @brief Boolean Flag to indicate whether this LLI
     * entry is a static / dynamic entry.
    * /
   UINT8
             IsStatic;
    * @brief The 4 byte IPv4 address associated with this
     * LLI/ARP Entry.
    * /
   IPN
             IPAddr;
     * @brief The 6 byte Ethernet MAC address associated with this
     * LLI/ARP Entry.
   UINT8
             MacAddr[6];
} LLI_INFO;
```

A.7.4 API Function Overview

The LLI API functions are as follows:

LLIGetMacAddr()	Get the Mac Address Associated with this LLI
LLIValidateRoute()	Free an LLI
LLIAddStaticEntry	Add a new static ARP entry/update an existing static ARP entry/modify a dynamic entry to a static ARP entry in the stack.
LLIRemoveStaticEntry	Remove a previously configured static ARP entry from the stack
LLIGetStaticARPTable	Retrieve a copy of the static ARP table from the stack
LLIFreeStaticARPTable	Cleans the memory allocated by a previous call to LLIGetStaticARPTable API



A.7.5 API Functions

LLIGetMacAddr Get the Mac Address Associated with this LLI

Syntax uint LLIGetMacAddr(HANDLE hLLI, UINT8 *pMacAddr, uint MaxLen);

Parameters

hLLI Handle to LLI object

pMacAddr Pointer to buffer to write Mac address data

MaxLen Maximum byte length of buffer (must be at least 6)

Return Value Returns 1 if the Mac address for the LLI is valid and it was successfully written to the

supplied buffer.

Returns 0 if the LLI does not contain a valid Mac address, or one of the calling

parameters is invalid.

Description This function is called to return the six byte Mac address associated with the LLI. It is

used in system programming to obtain the hardware address from an LLI contained in a

route entry.

LLIValidateRoute Validate an IP Address/MAC Address Pairing in the Route Table

Syntax HANDLE LLIValidateRoute(HANDLE hIF, IPN IPAddr, UINT8 *MacAddr);

Parameters

hIF Handle to the interface on which the target IP address/MAC address appears

IPAddr IP address to validate

MacAddr Six byte MAC address corresponding to the supplied IP address

Return Value Referenced handle to route or NULL if there was no room to create the entry.

Description This function is called to create or update an entry in the stack route table for the

supplied IP address. The entry for the given IP address is marked as valid, and assigned the supplied MAC address. Packets sent to the IP address will be assigned the given

MAC address, and no ARP request will be sent.

This function also updates the route in the LLI (ARP) expiration list. It allows an application to change the state of the ARP entry even if the stack has already created the route. It should be used when it is unclear if the route (really ARP table entry)

already exists or not.

Note that this function returns a referenced route handle. This handle must be dereferenced using the RtDeRef() function when it is no longer required. Because the route is treated as a standard ARP entry (with a standard expiration time as supplied in

the configuration structure), the route can be dereferenced immediately.



www.ti.com LLIAddStaticEntry — Add/update a static ARP entry or change a dynamic entry to a static ARP entry

LLIAddStaticEntry Add/update a static ARP entry or change a dynamic entry to a static ARP entry

Syntax int LLIAddStaticEntry(IPN IPAddr, UINT8 *pMacAddr);

Parameters

IP Address pMacAddr IPv4 address of the device

6 byte EMAC address of the device corresponding to the supplied IPv4 address.

Return Value

Returns 0 on success or -1 on invalid input/error in LLI entry creation.

Description

This API validates the input and returns an error (-1) if any of the following conditions are met:

- No MAC Address specified
- IPv4 address specified is either a broadcast/multicast address
- IPv4 address specified is a local IP address, i.e., the IP address specified is in use by a local interface attached to the NDK stack.
- IPv4 address is not reachable using the routes currently configured, i.e., there is no Network / Cloning route (no local interface is on the same subnet as specified IPv4 address) that can be used to reach the IPv4 address specified.
- Memory allocation issue.

If no error encountered, this API does the following:

- Tries to find a duplicate static entry matching the IP Address Specified. If a duplicate static entry found, updates the entry with the new MAC address specified. Returns Success (0).
- Checks for any dynamic LLI/route entries matching the IPv4 address. If found, deletes this entry and creates a new static LLI entry and host route with the IPv4 address and new MAC address specified. Returns Success (0). This ensures that Static LLI entries always override the dynamic ones automatically configured by the stack.
- If no duplicate static/dynamic entry already exists, adds a new static LLI entry and an associated Host route to the stack using the IPv4 address and MAC address specified. Returns Success (0).

The static LLI entries have to be removed by an application manually if not in use or will be deleted when the NDK stack is shutdown.

This API is an application level API and can be called from outside the kernel mode.

LLIRemoveStaticEntry Remove a previously configured static ARP entry from the stack.

Syntax int LLIRemoveStaticEntry(IPN IPAddr);

Parameters

IPAddr IPv4 address of the device

Return Value Returns 0 on success or -1 on invalid input/error in LLI entry removal.

Description

This API searches for a static route and associated LLI entry in the NDK stack using the IPv4 address specified and if no entry found returns an error, i.e., -1. If a valid entry is found, it removes the route and corresponding LLI entries and cleans up any memory associated with them. On successful clean up, returns 0. If this API is not explicitly called to remove a previously configured static ARP entry, it is cleaned up only during the NDK stack shutdown.

This API is an application level API and can be called from outside the kernel mode.

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LLIGetStaticARPTable Retrieve a copy of the static ARP table from the stack.

Syntax void LLIGetStaticARPTable(UINT32* pNumEntries, LLI_INFO** pStaticArpTable);

Parameters

pNumEntries Pointer to hold the number of static ARP entries in the stack.
pStaticArpTable Pointer to hold the replicated static ARP table returned by this API

Return Value Updates pNumEntries with the number of static ARP Entries and pStaticArpTable with a

list of LLI_INFO structures containing the information of all static ARP entries configured

in the stack.

Description This API can be used to retrieve the number of static ARP entries and a replicated list of

such entries configured in the system. This API traverses through the route and LLI (ARP) table configured in NDK, finds any static routes/LLI entries configured, and creates a copy of them and returns them as a linked list of LLI_INFO structures for the requesting application to use. In case of a memory allocation error or if no static ARP entries found, this API returns the number of entries (pNumEntries) as zero to indicate

the same.

This API is an application level API and can be called from outside the kernel mode.

LLIFreeStaticARPTable Cleans the memory allocated by a previous call to LLIGetStaticARPTable API.

Syntax void LLIFreeStaticARPTable (LLI_INFO* pStaticArpTable);

Parameters

pStaticArpTable This is the head of the duplicated static ARP table list which has to be cleaned up

Return Value None

Description This function is called to clean the memory allocated by a previous call to

LLIGetStaticARPTable API. This function cleans the replicated copy f the static ARP

table.

This API is an application level API and can be called from outside the kernel mode.

A.8 Interface (IF) Object

The Interface (or IF) object is an abstraction of any physical interface in the system capable of transmitting and receiving packet (PKT) objects. In the current software, an interface object can represent either a PPP based device or an Ethernet (Ether) based device. However, there is no interface object, but rather PPP device objects and Ether device objects can both be treated as IF type objects for a small collection of functions. This section documents these API functions.

The IF object API covers three general areas. First, it provides a couple of generic functions to obtain information about a device, such as its type, MTU, etc.. In addition, the API also tracks physical device indices for device handles, and mapping from one to the other. This is useful for the application programming environment and configuration system, which deals in device indices instead of device handles. The last function of the IF API is to provide a generic way of creating packets for the system, keeping track of all device's header and padding requirements.

A.8.1 Object Type

Static - IF objects represent PPP or Ether objects, which are created and destroyed by the same entity.



A.8.2 API Function Overview

The following is a complete list of the IF object API. Some of these functions are only called from physical device objects like Ether or PPP.

IFInit() Initialize handle to index mapping tables

IFIndexNew() Allocate a new physical index for a device handle

IFIndexFree() Free a previously allocated physical index IFMaxIndex() Get the highest device index currently in use

IFIndexGetHandle() Get the device handle corresponding to a physical index IFGetIndex() Get a physical index corresponding to a device handle

IFGetType() Get the interface handle type
IFGetMTU() Get the MTU of a device

IFSetPad() Set device header and padding requirements
IFCreatePacket() Create a packet object for transmission

A.8.3 API Function Description

IFInit Initialize Handle to Index Mapping Tables

Syntax void IFInit();

Return Value None.

Description This function is called from *ExecOpen()*, before any physical devices are initialized. It will

prepare the IF system to correctly process IFIndexNew() commands that are called

when Ether and PPP devices are created.

IFIndexNew Allocate a New Physical Index for a Device Handle

Syntax uint IFIndexNew(HANDLE hIF, uint Index);

Return Value Allocated device index, or NULL on error.

Description This function is called from PPP and Ether when new physical device handles are

created. IF allocates and returns a physical Index for the supplied device handle. If a specific index is required, it is passed in the *Index* parameter, otherwise *Index* is set to

NULL.

IFIndexFree Free a Previously Allocated Physical Index

Syntax void IFIndexFree(uint Index);

Return Value None.

Description This function is called from PPP and Ether when physical device handles are destroyed.

IF frees the supplied physical Index, and can reallocate it in future calls to IFIndexNew().

The Index should not be used once freed.



IFMaxIndex Get the Highest Device Index Currently in Use

Syntax uint IFMaxIndex();

Return Value Maximum logic device index currently in use.

Description This function returns the highest device index that is currently in use in the system.

When there are no holes in the index map, this value is also the number of devices

currently active.

IFIndexGetHandle Get the Device Handle Corresponding to a Physical Index

Syntax HANDLE IFIndexGetHandle(uint Index);

Return Value Handle to device corresponding to supplied index, or NULL on error.

Description This function is called to convert a physical device index to a device handle.

IFGetIndex Get the Physical Index Corresponding to a Device Handle

Syntax uint IFGetIndex(HANDLE hIF);

Return Value Physical device index corresponding to supplied device handle, or NULL on error.

Description This function is called to convert a device handle to a physical device index.

IFGetType Get the Interface Handle Type

Syntax uint IFGetType(HANDLE hIF);

Return Value Handle type of supplied handle.

Description This function is called to get the handle type of the supplied device handle. When called

correctly, the return value should be one of the following:

HTYPE_ETH Ether Device
HTYPE PPP PPP Device

IFGetMTU Get the MTU of a Device

Syntax uint IFGetMTU(HANDLE hIF);

Return Value MTU of the device indicated by the supplied handle.

Description This function is called to get the MTU (maximum transmit unit) size of the indicated

device. The MTU value does not include the device's layer 2 header. Thus, for Ethernet and serial PPP, the MTU will normally be 1500; however, for protocols like PPPoE, the

MTU will be smaller.

IFSetPad Set Device Header and Padding Requirements

Syntax void IFSetPad(uint Header, uint Padding);

Return Value None.

Description This function is called by a physical device object to set the layer 2 header and padding

requirements for a packet. For example, with Ethernet, the header is normally 14. Plus, if

the Ethernet checksum appears in the packet body, the value of padding is 4.



IFCreatePacket Create a Packet Object for Transmission

Syntax HANDLE IFCreatePacket(uint size);

Return Value Handle to new packet buffer (PBM), or NULL on allocation error.

Description This function is probably the most useful of the IF functions. It is called to create a

packet object to send packets out of the stack. It uses information collected from the physical devices to create a packet that can be transmitted on any of the physical devices in the system. It does this by applying worst case header and padding sizes. The handle returned by this function references a packet buffer created by the packet buffer manager (PBM). The packet buffer object is described in Section A.3. This function is preferred over calling PBM_alloc() because it sets up the packet for use by the stack. The data offset property is set to where the IP header should be placed. This offset guarantees that the packet can be transmitted on any packet device in the system.

A.9 Ether Object

The Ether object is really just the generic portion of the packet driver. It knows how to process an Ethernet MAC header, and handles incoming and outgoing packets. It interfaces directly to the HAL packet driver. For each Ethernet based packet device in the system, an Ether object is created to represent this device to the stack.

A.9.1 Object Type

Static - Ether objects are generally created and destroyed by the same entity.

A.9.2 API Function Overview

The following is a complete list of the Ether object API.

Create/Destroy Functions:

EtherNew() Create New Ether Object
EtherFree() Destroy Ether Object

EtherConfig() Configure Ether Object Header Parameters

Addressing Functions:

EtherGetMacAddr() Get the Device's Unicast MAC Address

EtherAddMCast() Add Multicast Ethernet Address
EtherDelMCast() Delete Multicast Ethernet Address
EtherClearMCast() Clear All Multicast Ethernet Addresses

Filtering Functions:

EtherSetPktFilter() Set Receive Packet Filter Value

EtherGetPktFilter() Get Current Receive Packet Filter Value

Hardware Event Functions:

EtherRxPacket() Indicate a New Rx Packet to the Ether Object



A.9.3 API Functions

Although the Ether object API is larger than that discussed here, this section covers the portion of the API that is useful to a system application.

EtherNew Create New Ether Object

Syntax HANDLE EtherNew(uint PhysIndex);

Return Value Returns a handle to the Ether object, or NULL on a memory allocation error.

Description Installs a new Ether object in the system. This call should be made for every ethernet

device installed. Once called, the stack will make calls to the HAL packet driver interface to get more information about the device. The argument is the physical device id used by

the HAL to identify the device.

EtherFree Destroy Ether Object

Syntax void EtherFree(HANDLE hEther);

Description Destroys the indicated Ether object, and frees its associated memory. This function

should be called to remove devices after the stack has shut down. Calling this function

will not result in any calls to the HAL.

EtherConfig Configure Ether Object

Syntax void EtherConfig(HANDLE hEther, uint PhysMTU, uint EthHdrSize, uint OffDstMac, uint

OffSrcMac, uint OffEthType, uint PacketPad, TimestampFxn timestampFxn);

Description Describes to the Ether object how the Ethernet header is constructed on this device.

Although the MAC address is assumed to be 6 bytes long, various devices have a small variety of packet variances. The Ether device object must know this information to both

process and construct packets in buffers that are native to the physical device.

The arguments are defined as follows:

PhysMTU Physical MTU of the packet (usually 1514)

EthHdrSize Minimum (non-802.2 SNAP) header size (usually 14)
OffDstMac Byte offset from header start to DST Mac Addr (usually 0)
OffSrcMax Byte offset from header start to Src Mac Addr (usually 6)
OffEthType Byte offset from header start to ether type (usually 12)
PacketPad Required byte pad at end of frame (usually 0 or 4)

timestampFxn Specifies a call-out function to allow timestamping of received UDP datagrams per

interface basis. This function is called by the NDK scheduler. The function

prototype of the call-out is "typedef void (*TimestampFxn)(UINT8 *plpHdr)", and is defined in "socket.h". This call-out function is responsible for updating the UDP

checksum accordingly.



EtherGetMacAddr Get the Device's Unicast MAC Address

Syntax uint EtherGetMacAddr(HANDLE hEther, UINT8 *pMacAddr, uint MaxLen);

DescriptionRetrieves the unicast MAC address of the physical Ethernet device. The MAC address is written to the pointer *pMacAddr*. The maximum length of the buffer must be at least 6

bytes and is specified in MaxLen. The function returns 1 on success and 0 on failure.

EtherAddMCast Add Multicast Ethernet Address

Syntax uint EtherAddMCast(HANDLE hEther, UINT8 *pMCastAddr);

Description Adds an Ethernet multicast address to the list of addresses received by the Ethernet

hardware when the Rx filter is set to ETH_PKTFLT_MULTICAST. The multicast address is specified by the pointer *pMCastAddr*, pointing to a 6-byte MAC address. The multicast address list can be manipulated in its raw form at the *IIPacket* layer (see Section D.4).

EtherDelMCast Delete Multicast Ethernet Address

Syntax uint EtherDelMCast(HANDLE hEther, UINT8 *pMCastAddr);

Description Removes an Ethernet multicast address from the list of multicast addresses previously

added via *EtherAddMCast()*. The multicast address to remove is specified by the pointer *pMCastAddr*, pointing to a 6-byte MAC address. The multicast address list can be

manipulated in its raw form at the IIPacket layer (see Section D.4).

EtherClearMCast Clear All Multicast Ethernet Addresses

Syntax void EtherClearMCast(HANDLE hEther):

Description Called to remove all Ethernet multicast addresses from the list of multicast addresses

previously added via a call to EtherAddMCast(). After calling this function, the Ethernet

adapter will not receive any multicast addresses when the Rx filter is set to ETH_PKTFLT_MULTICAST or below. The multicast address list can also be

manipulated in its raw form at the IIPacket layer (see Section D.4).

EtherSetPktFilter Set Receive Packet Filter Value

Syntax void EtherSetPktFilter(HANDLE hEther, uint PktFilter);

Description Called to indicate the level of filtering for Ethernet packets. By default, the driver is

opened with filter value: ETH PKTFLT MULTICAST. Valid filter values are as follows:

ETH_PKTFLT_NOTHING No Packets

ETH PKTFLT DIRECT Only directed Ethernet

ETH_PKTFLT_BROADCAST Directed plus Ethernet Broadcast

ETH_PKTFLT_MULTICAST Directed, Broadcast, and selected Ethernet Multicast

ETH_PKTFLT_ALLMULTICAST Directed, Broadcast, and all Multicast

ETH_PKTFLT_ALL All packets

For selecting multicast addresses as the ETH_PKTFLT_MULTICAST level, see

EtherAddMCast().



EtherGetPktFilter	Get Current Receive Packet Filter Value
-------------------	---

Syntax uint EtherGetPktFilter(HANDLE hEther);

Description Called to retrieve the current level of filtering for Ethernet packets. See the description of

EtherSetPktFilter() for more information.

EtherRxPacket Indicate a New Rx Packet to the Ether Object

Syntax void EtherRxPacket(PBM_Handle hPkt);

DescriptionCalled to indicate the reception of a new packet to the corresponding Ether object. The

Ether object takes ownership of the indicated packet buffer, until it is returned via a call

to the packet buffer manager (PBM).

The argument hPkt is the handle of a standard packet buffer object. The valid data, offset, and receiving interface fields must be valid. The packet buffer object is described

in Section A.3.

A.10 Binding Object

For a device object to live on the network, it must have an IP address and knowledge of its IP subnet. The process of assigning an IP address and subnet to a device binds the device with the desired IP addressing.

A.10.1 Object Type

Static - Binding objects are generally created and destroyed by the same entity.

A.10.2 BIND API Functions

Although the Bind object API is larger than that discussed here, this section covers the portion of the API that is encountered by a system application.

BindNew	Create New IP Binding	
Syntax	HANDLE BindNew(HANDLE hIF, IPN IPAddr, IPN IPMask);	
Return Value	Returns a handle to the Bind object, or NULL on error.	

DescriptionBinds the indicated IP address and mask to the supplied Ether device. The handle to the Ether device object is specified as hIF - or an handle to an *interface*, because the

interface may or may not be an Ethernet device (but always is in this version).

The IP address and mask arguments are given the type IPN, which is an unsigned 32 bit value. IPN stands for IP Network format, meaning that the IP data must be supplied in network format. If unsure of the network format for your hardware, use the htonl() macro

function on the native format (where 1.2.3.4 = 0x01020304).

BindFree Destroy IP Binding Object

Syntax void BindFree(HANDLE hBind);

Description Destroys the indicated Bind object, and frees its associated memory. This function

removes the IP address and subnet association in the system route table. It has no

effect on the Ether object involved in the binding.



BindGetFirst Start Enumeration of Binding Objects

Syntax HANDLE BindGetFirst();

Description Returns a handle to the first binding installed in the system (or NULL if no bindings

exist).

BindGetNext Continue Enumeration of Binding Objects

Syntax HANDLE BindGetNext(HANDLE hBind);

Description Returns a handle to the binding in the installed binding list that follows the indicated

binding (or NULL if no more bindings exist). Note that bindings are not internally kept in

chronological order in which they were installed.

BindGetIF Get the Ether Object that is Bound by this Binding Object

Syntax HANDLE BindGetIF(HANDLE hBind);

Description Returns a handle to the Ether object that is bound by this binding object. Note that a

binding is nothing more than an assignment of an Ether object to an IP address/network.

BindGetIP Get the IP Address/Network that is Bound by this Binding Object

Syntax void BindGetIP(HANDLE hBind, IPN *pIPHost, IPN *pIPNet, IPN *pIPMask);

Description Returns the IP address and mask as requested by the calling arguments. Any of the

pointer arguments can be NULL if the information is not required.

The arguments are defined as follows:

pIPHost Pointer to the local IP address assigned by this binding

pIPNet Pointer to the network assigned by this binding (IP address AND IP Mask)

pIPMask Pointer to the subnet mask of the network assigned by this binding



Route Object www.ti.com

A.11 Route Object

The route manager maintains IP routing information. It is called by various routines to get and set route information. A route object is a destination on the network. Locally, it consists of an egress interface and a next hop IP address.

This section describes a subset of the route object. Flags, features, and API calls have been omitted for simplicity. Also, documenting the entire API would require the documentation of other stack objects that are not covered in this document.

A.11.1 Object Type

Referenced - Route objects are referenced and dereferenced as needed. The object is removed when the reference count reaches ZERO.

A.11.2 Route Entry Flags Definition

Associated with each route is a collection of entry/status flags. These flags indicate the type of route and its status. Most system programming is not concerned with the route entry flags. They are listed here for completeness. The definition of the various flags is as follows:

• FLG_RTE_UP - Entry is up

When set, indicates that the route is valid. The only time this flag is cleared is when the route is being initialized, or when an error condition is signaled via RtSetFailure(). The flag is reset to TRUE by calling RtSetFailure() with NULL failure code, or if the route is modified.

• FLG_RTE_EXPIRED - Entry is expired

When set, indicates that the route is expired. The flag cannot be cleared. A new route must be created. Expired routes are never found, but a route cached by another entity may expire while it is being held.

• FLG_RTE_STATIC - Entry is static

This flag is set when a route should remain in the routing table even if it has no references. Various routes can be static. Static routes are manually referenced by the system during create, and manually de-referenced by the system during system shutdown.

- FLG_RTE_BLACKHOLE Entry is a blackhole
 - When set, indicates that the route is a black hole. All packets destined for this address are silently discarded.
- FLG_RTE_REJECT Entry is rejected

When set, indicates that the route is to an invalid address. All packets destined for this address are discarded with an error indication.



www.ti.com Route Object

FLG_RTE_MODIFIED - Route has been auto modified

When set, indicates that the route has been modified as a result of an ICMP redirect message. This can occur only to GATEWAY routes, and only if ICMP modifications are enabled in the stack configuration.

FLG RTE DYNAMIC - Route has been auto created

When set, indicates that the route has been created as a result of an ICMP redirect message. ICMP can only create GATEWAY routes, and may do so only if ICMP modifications are enabled in the stack configuration.

FLG RTE PROXYPUB - Reply to ARP with client's MAC address

This flag indicates that the router is a proxy publisher of another entity's MAC address. When set, the ARP protocol will respond to ARP requests for the route's IP address with the supplied static MAC address when the host is on the same IF device as the incoming ARP request. This allows support of hosts that do not implement ARP but are on the same physical Ethernet network. PROXYPUB entries are always created with a MAC address and contain a static LLI (link-layer info, i.e., ARP entry).

• FLG_RTE_PROXY - Reply to ARP with router's MAC address

This flag indicates that the router is acting as a proxy for this host or network route. When set, the ARP protocol will respond to ARP requests with its own MAC address for the associated IP host or network when the network appears on a different IF device from the incoming ARP request. The MAC address supplied in the reply is the local MAC of the ingress IF device. This technique tricks clients into sending packets to the router when subnets are split across physical devices on a router.

One potential use applies when the stack is acting as a PPP server and Ethernet router. If a PPP client is made part of the same IP subnet as an Ethernet based interface, the stack acts as the PPP client's proxy so that Ethernet peers can communicate via ARP.

· FLG RTE CLONING - Cloning route to a local IP subnet

When set, indicates that the network route is a cloning route. Cloning routes clone (spawn to) host routes when a route search is performed on a host address that is a member of the cloning route's network (via the address and subnet mask). Cloned host routes take on most of the properties of their parent network route, with the following alterations:

- Any MODIFIED or DYNAMIC flags are cleared.
- The STATIC flag is never set.
- The HOST flag is set and the netmask is set to 1s.
- The CLONING flag is cleared.

NOTE:

Cloning routes are routes to a network (IP and subnet). These routes are added automatically when an IP network is added to a device via a Bind object. Take care when adding this type of route manually.

FLG RTE HOST - Host route (no subnet mask)

When set, indicates that the route entry is a host route. A host route has no subnet mask (or rather a subnet mask of all 1's). When searching for a route, host routes always match before network routes (but this behavior can be overridden).

• FLG RTE_GATEWAY - Destination is available via a Gateway

When set, indicates that the host or network route is indirectly accessible via an IP gateway. For a route with this flag set, the GateIP address is always valid. Most GATEWAY routes will also be network routes; however, a host redirect from ICMP can create a host route with a different gateway than its parent route. When searching for a route, gateway routes always match before host routes (but this behavior can be overridden).



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FLG_RTE_IFLOCAL - IP address is Local to the stack

When set, indicates that the host route does not have a valid LLI (ARP) entry because the host is local to the stack. The MAC address of this local IP host address can be obtained from the interface handle associated with the route.

NOTE

Local routes are in the routing table to route packets that originate in the stack's upper layers. When handling ARP requests and routing of incoming packets from outside the stack, the IP address list published via the Bind object is used. The ARP will not respond to, nor will the IP accept, packets addressed to an IP address that is not in the Bind list, even if an IFLOCAL address entry exists in the route table. As with a cloning route, the Bind object is the best way to create a local route.

A.11.3 Route Entry Flags Guidelines

See the following for some general guidelines to use when creating new routes. Use the definitions listed above with the following legal flag combinations:

- Setting FLG_RTE_BLACKHOLE FLG_RTE_REJECT - must be OFF
- Setting FLG_RTE_REJECT
 FLG_RTE_BLACKHOLE must be OFF
- Setting FLG_RTE_CLONING
 FLG_RTE_HOST must be OFF
 FLG_RTE_GATEWAY must be OFF
 FLG_RTE_IFLOCAL must be OFF
- Setting FLG_RTE_HOST FLG_RTE_CLONING - must be OFF
- Setting FLG_RTE_GATEWAY FLG_RTE_CLONING - must be OFF FLG_RTE_IFLOCAL - must be OFF
- Setting FLG_RTE_IFLOCAL FLG_RTE_HOST - must be ON FLG_RTE_CLONING - must be OFF FLG_RTE_GATEWAY - must be OFF
- Setting FLG_RTE_PROXYPUB
 FLG_RTE_HOST must be ON
 FLG_RTE_CLONING must be OFF
 FLG_RTE_GATEWAY must be OFF
- Setting FLG_RTE_PROXY
 FLG_RTE_CLONING must be OFF
 FLG_RTE_GATEWAY must be OFF



A.11.4 API Functions

The Route API is the most extensive API that a system task uses outside of the stack routines themselves. As with the other stack APIs, this guide does not document the entire API.

Calls that accept a CallFlags argument can be supplied with the FLG_RTF_REPORT flag to indicate that the call should result in a route report to the route control object. The route control object is described later in this section.

RtRef Reference a Route

Syntax void RtRef(HANDLE hRt);

Description Called to add one to the reference count of a route. An application that keeps a route it

did not create itself should reference the route before it uses it, and dereference it when

it is through.

RtDeRef Dereference a Route

Syntax void RtDeRef(HANDLE hRt);

Description Called to remove one from the reference count of a route. An application dereferences a

route when it is through with it. This is the same (to the application) as destroying the

route. The route is actually destroyed when its reference count reaches zero.

Syntax HANDLE RtCreate(uint CallFlags, uint RtFlags, IPN IPAddr, IPN IPMask, HANDLE hIF,

IPN IPGateway, UINT8 *pMacAddr);

Parameters

CallFlags Call Type Flags
RtFlags Route Type Flags

IPAddr Destination IP address of route

IPMask Destination IP Mask of route (or NULL)

hIF Interface (or NULL)

IPGateway Gate IP address (or NULL)

pMacAddr Pointer to six byte MAC address (or NULL)

Call Flags

FLG_RTF_REPORT Reports new route (NEW)

Return Value Referenced handle to newly created route.

Description Called to create a new host or network route and add it to the route table. Existing routes

cannot be modified via this call.

Some flag combinations are incorrect, and the following rules are strictly enforced.

FLG_RTE_UP flag is always SET.

- FLG_RTE_EXPIRED and FLG_RTE_MODIFIED flags are always CLEARED.
- If FLG_RTE_HOST is set, then the route is a host route and *IPMask* is ignored, and FLG_RTE_CLONING cannot be set.
- If FLG_RTE_GATEWAY is set, then IPGateway must specify a valid (reachable) IP address.



RtFind — Find a Route www.ti.com

- If FLG_RTE_GATEWAY is not set, then hIF must be valid.
- If FLG_RTE_IFLOCAL is set, then the specified host address is local to this machine, and FLG_RTE_HOST must also be set, FLG_RTE_GATEWAY cannot be set, and hIF must be valid.
- If FLG_RTE_CLONING is specified in Flags, the route is a cloning network route.
 The IPMask argument must be valid, and neither FLG_RTE_HOST nor FLG_RTE_GATEWAY may be set.
- If FLG_RTE_STATIC is specified in Flags, the route is referenced once by the route code, and later dereferenced during shut down.

RtFind Find a Route

Syntax

void RtFind(uint CallFlags, IPN IPAddr);

Call Flags

FLG_RTF_REPORT Reports any new (cloned) or unfound route (NEW or MISS)

Return Value

Referenced handle to best match route (or NULL)

Description

This call searches the route table for a route that matches the supplied IP address. The search always returns the best match for a route. The best match is a match with the most bits in the subnet mask. Thus, a host match takes priority over a network match.

When there is more than one route with the same subnet mask, the following matching guidelines are used (listed from best to worst):

- Route has a local destination (occurs with host addresses only).
- · Route has a gateway destination.
- Route has a subnet destination on a connected interface.

Sometimes a search is desired where particular matches are desired. The following flags can be combined with the value of *CallFlags* to change the behavior of the search:

FLG_RTF_CLONE FLG_RTF_HOST Clone a network route to a host route if host not found

_RTF_HOST Find only non-gateway host routes

RtSetTimeout

Set the Timeout for a Non-static Route

Syntax

void RtSetTimeout(HANLE hRt, UINT32 dwTimeOut);

Description

This call allows an application to specify that the stack should time out a referenced route. When the route is added to the timeout list, the system will add a reference. Thus, once the application sets the timeout value, it should call RtDeRef() to dereference the route. The route will stay valid until the timeout value is exceeded, after which it is dereferenced by the system. Note that if this function is called and the route is not dereferenced by the caller, it will still be removed from the system route table when the expiration time elapses, but the object will not be freed.



RtSetFailure Set the Timeout for a Non-Static Route

Syntax void RtSetFailure(HANLE hRt, uint CallFlags, uint FailCode);

Call Flags

FLG_RTF_REPORT Reports the status change of the route (UP or DOWN)

Description This call allows an application to specify a particular error with a route, or clear a

previously indicated error. Setting an error clears the FLG_RTE_UP bit in the flags. When use of the route is attempted, the specified error is returned. Defined error codes

for the FailCode argument are:

NULL Route is operating normally (sets FLG_RTE_UP flag)

RTC_HOSTDOWN Host is down
RTC_HOSTUNREACH Host unreachable
RTC_NETUNREACH Network unreachable

RtRemove Remove Route from System Route Table

Syntax void RtRemove(HANLE hRt, uint CallFlags, uint FailCode);

Call Flags

FLG_RTF_REPORT Reports the removal of the route (REMOVED)

Description

This call allows an application to remove a route from the system route table independently of any held references to the route. It is similar to the *RtSetFailure()* call, but differs in two ways:

- 1. It removes the route from the system route table so that it can no longer be returned by *RtFind()*.
- 2. It calls the IP and Sockets layers to flush the route from any local cache.

Calling this function clears the FLG_RTE_UP bit in the flags. When use of the route is attempted, the error specified in *FailCode* is returned. Defined error codes for the *FailCode* argument are:

RTC_HOSTDOWN Host is down
RTC_HOSTUNREACH Host unreachable
RTC_NETUNREACH Network unreachable



RtGetFailure Set the Timeout for a Non-Static Route

Syntax uint RtGetFailure(HANLE hRt);

Return Value Failure code or NULL for normal operation.

Description This call allows an application to retrieve the error code of a route where the

FLG RTE UP bit is not set in the route flags. Defined error codes are:

RTC_HOSTDOWN Host is down
RTC_HOSTUNREACH Host unreachable
RTC_NETUNREACH Network unreachable

RtGetFlags Get the Route Flags

Syntax uint RtGetFlags(HANLE hRt);

Description This function returns the state of the route flags for the indicated route. The flag values

and definitions were discussed earlier in this section.

RtGetIPAddr Get the Route IP Address

Syntax IPN RtGetIPAddr(HANLE hRt);

Return Value IP host/network address.

Description This function returns the specified route's IP address in network format.

RtGetIPMask Get the Route IP Subnet Mask

Syntax IPN RtGetIPMask(HANLE hRt);

Return Value IP subnet mask.

Description This function returns the specified route's IP subnet mask in network format.

RtGetGateIP Get the Route Gateway IP Address

Syntax IPN RtGetGateIP(HANLE hRt);

Return Value IP address of the Gateway or NULL.

Description This function returns the Gateway IP address for the specified route (assuming the

FLG_RTF_GATEWAY bit is set in the route flags).

RtGetIF Get the Route's Destination Hardware Interface

Syntax HANDLE RtGetIF(HANLE hRt);

Return Value HANDLE to Ether Object representing target interface.

Description This function returns an Ether device handle to the egress (target) device of the route.

Even local IP addresses have target devices (the device they are bound to).



RtGetMTU Get the MTU of a Packet Sent via this Route

Syntax uint RtGetMTU(HANLE hRt);

Return Value Packet payload MTU in bytes.

Description This function returns the MTU (not including layer 2 header) of a packet sent via the

supplied route.

RtWalkBegin Start Walking the Route Table

Syntax HANDLE RtWalkBegin();

Return Value HANDLE to first route in system route table or NULL if no routes.

Description This function initiates a walk of the route table. It returns the first route in the table. The

walk must be terminated with RtWalkEnd() for the system to behave properly.

RtWalkNext Get Next Route While Walking the Route Table

Syntax HANDLE RtWalkNext(HANDLE hRt);

Return Value HANDLE to next route in system route table or NULL if no routes.

Description This function gets the next route (based off the previous route supplied) in a walk of the

route table. The walk must be terminated with RtWalkEnd() for the system to behave

properly.

RtWalkEnd Stop Walking the Route Table

Syntax void RtWalkEnd(HANDLE hRt);

Description This function completes the walk of the route table. The last route (if any) obtained from

RtWalkBegin() or RtWalkNext() is specified in the calling argument. Otherwise, NULL is

used.

A.12 Route Control Object

The route control object is more of a function than an object. It serves as a collection point for route related information in the system. A routing daemon may use this information, or it could simply be logged as debugging information.

When so configured, route control messages are transformed into debug messages by the stack and logged via *DbgPrintf()*. By default, the route control debug messages are disabled. Also, the message function can be hooked by an application.

Note, control messages can also be suppressed individually by not supplying the FLG_RTF_REPORT flag to the Route object API function when the call is made (as mentioned in the previous section).

A.12.1 Route Control Messages

The basic form of the route control message is an unsigned int message value, with two unsigned 32 bit values for additional data. In most cases these are immediate data. In one instance, the value is actually a 32 bit memory pointer.

Messages are passed internally to the stack via the function:

void RTCReport(uint Msg, UINT32 Param1, UINT32 Param2);

Applications should not call this function directly.

The possible values for *Msg* are as follows:



MSG_RTC_UP Route is Valid/Pending

Parameters

Param1 Route IP

Param2 Route IP Mask (all ones for host route)

Description Called after a down message indicating that a route that had previously been in the

down state is now up again. This does not mean that the route has been validated, but

only that it will attempt to validate itself if used.

MSG_RTC_DOWN Route is Down

Parameters

Param1 Route IP

Param2 Route IP Mask (all ones for host route)

Description Called when a route goes down due to an error. Packets sent via a route in this state will

generate an error. The most common reason for a route to go down is for a nonresponse to 5 successive ARP requests. In this case, the route will come back up after

the down time has expired.

MSG_RTC_MISS Route Find "Missed" on Route

Parameters

Param1 Route IP

Param2 Route IP Mask (all ones for host route)

Description Called when the route table was searched for a route and no matching route was found.

This message will never be sent when there is a default route in the table because all

searches will have a match (unless a special restricted search is performed).

MSG_RTC_NEW New Route has been Entered into the Route Table

Parameters

Param1 Route IP

Param2 Route IP Mask (all ones for host route)

Description Called when a new route is created and entered into the route table. Routes can be

created by applications, when new bindings are created, by ICMP redirects, or when

local host routes are cloned from local subnet routes.



MSG_RTC_EXPIRED Route has Expired

Parameters

Param1 Route IP

Param2 Route IP Mask (all ones for host route)

Description Called when a route with an expiration timeout has expired and been removed from the

table.

MSG_RTC_REMOVED Route has been Manually Removed

Parameters

Param1 Route IP

Param2 Route IP Mask (all ones for host route)

Called when a route has been manually removed from the table. This message is not Description

> generated when static routes are removed at system shutdown. Generally, a route can only be removed when its reference count reaches zero. This cannot happen to a static route or a route with an expiration timeout. For the former, no message is ever

generated. For the latter, the MSG RTC EXPIRED message is used.

MSG_RTC_MODIFIED Route has been Manually Modified

Parameters

Param1 Route IP

Param2 Route IP Mask (all ones for host route)

Description Called when a route has been manually modified via the RtModify() call. The stack does

not use this function, so if it is not called by an application, this message will never

occur.

MSG RTC REDIRECT Route has been Redirected

Parameters

Param1 Route IP

Param2 New Destination Gateway IP

Description Called when an ICMP redirect message is received for a given IP host address.

Because the invention of classless subnets, all redirects are treated as HOST redirects. If the stack is configured to generate redirect routes automatically (will do so by default), this message will occur after the new static host redirect route has been created (which will also generate a MSG_RTC_NEW message). If the stack does not create the redirect route, this message occurs before the socket layer is notified so that if a new route is

created as a result of this message, the sockets layer will find it.



MSG_RTC_DUPIP A Duplicate IP Address has been Detected in the System

Parameters

Param1 Duplicated IP

Param2 Pointer to 6 byte MAC address of offending device

Description Called when an ARP packet is received from a device that has an IP address that is the

same as the IP address of the stack on that physical interface. Depending on the age of

the address, the application may wish to destroy the binding.

A.12.2 Route Control API Functions

RTCAddHook Hook RTC Messages

Syntax uint RTCAddHook (void (*pfn)(uint, UINT32, UINT32));

Return Value 1 if the hook was installed, or NULL on an error (too many hooks).

Description Called to hook a message function to receive route control messages. The argument is a

pointer to a message function of the type:

void MyMsgFun(uint Msg, UINT32 Param1, UINT32 Param2);

Note that the supplied callback function is called from within an <code>IlExit()/IIEnter()</code> pair, and thus may call the stack API directly, but may not call any applications API functions, like sockets functions. If such action is required, the callback function may call <code>IlExit()</code> when

called and then *IIEnter()* before returning.

When the hook is no longer required, the function may be unhooked by calling

RTCRemoveHook().

RTCRemoveHook Unhook RTC Messages

Syntax void RTCRemoveHook (void (*pfn)(uint, UINT32, UINT32));

Return Value None.

Description Called to remove a previously hooked callback function.

A.13 Configuring the Stack

The stack has multiple configuration options that can be changed by the system programmer. This is possible by altering the default values in a stack configuration structure before the stack is initialized.



www.ti.com Configuring the Stack

A.13.1 Configuration Structure

This section describes a data structure that is generated automatically by the XGCONF configuration. If you are using XGCONF for configuration, you can ignore the structure described here.

The stack internal configuration structure is _ipcfg. Any element in this structure may be modified before the initial system call to ExecOpen(). This structure should not be modified after this initial call.

The _ipcfg structure is of type IPCONFIG, which is defined as follows:

```
typedef struct _ipconfig {
     uint IcmpDoRedirect;
                                    // Update RtTable on ICMP redirect (1=Yes)
     uint IcmpTtl;
                                   // TTL for ICMP messages RFC1700 says 64
     uint IcmpTtlEcho;
                                  // TTL for ICMP echo RFC1700 says 64
     uint IpIndex;
                                  // IP Start Index
     uint IpForwarding;
                                  // IP Forwarding (1 = Enabled)
                                  // IP NAT Enable (1 = Yes)
     uint IpNatEnable;
                                  // IP Filtering Enable (1 = Yes)
     uint IpFilterEnable;
uint IpReasmMaxTime;
                                   // Max reassembly time in seconds
           IpReasmMaxTime;
     uint IpReasmMaxSize;
                                   // Max reassembly packet size
     uint IpDirectedBCast;
                                   // Look for directed BCast IP addresses
     uint TcpReasmMaxPkt;
                                  // Max reasm pkts held by TCP socket
     uint RtcEnableDebug;
                                  // Enable Route Control Messages (1=On)
                                  // Time in sec to send RtAdv (0=don't)
     uint RtcAdvTime;
     uint RtcAdvLife;
                                  // Litetime of route in RtAdv
     int RtcAdvPref;
                                  // Preference Level (signed) in RtAdv
     uint RtArpDownrime.
uint RtKeepaliveTime;
                                  // Time 5 failed ARPs keep Rt down (sec)
                                   // VALIDATED route timeout (sec)
                                   // ARP Inactivity Timeout (sec)
     uint RtCloneTimeout;
                                   // INITIAL route timeout (sec)
     uint RtDefaultMTU;
                                  // Default MTU for internal routes
     uint SockTtlDefault;
                                  // Default Packet TTL
     uint SockTosDefault;
                                  // Default Packet TOS
                                  // Max Socket Connections
     int SockMaxConnect;
     uint SockTimeConnect;
                                  // Max time to connect (sec)
     uint SockTimeIo;
                                  // Default Socket IO timeout (sec)
          SockTcpTxBufSize; // TCP Transmit buffer size SockTcpRxBufSize; // TCP Receive buffer size
     int
                                   // TCP Receive buffer size (copy mode)
     int
          SockTcpRxLimit;
     int
                                   // TCP Receive limit (non-copy mode)
     int SockUdpRxLimit;
                                  // UDP Receive limit
     int SockBufMinTx;
                                  // Min Tx space for "able to write"
     int SockBufMinRx;
                                  // Min Rx data for "able to read"
     uint PipeTimeIo;
                                  // Default Pipe IO timeout (sec)
     int PipeBufSize;
                                  // Pipe internal buffer size
     int PipeBufMinTx;
                                  // Min Tx space for "able to write"
     int.
           PipeBufMinRx;
                                   // Min Rx data for "able to read"
     uint TcpKeepIdle;
                                   // Time (in 0.1 sec) connection muse be idle
                                    // for TCP to send first keepalive probe.
                                    // Time (in 0.1 sec) between consecutive TCP
     uint TcpKeepIntvl;
                                    // keep alive probes
                                    // Time (in 0.1 sec) that a TCP connection can
     uint TcpKeepMaxIdle;
                                    // go without responding to a probe before
                                    // being dropped
                                    // Don't Reply To ICMP ECHO REQ packets
     uint IcmpDontReplyBCast;
                                    // sent to BCast or Directed BCast
     uint IcmpDontReplyMCast;
                                   // Don't Reply To ICMP ECHO REQ packets
                                    // sent to Multi-Cast
     uint RtGarp;
                                    // How to handle received gratuitous ARP
     uint IcmpDontReplyEcho;
                                   // Don't Reply to ICMP ECHO packets
     uint UdpSendIcmpPortUnreach; // Send ICMP Port Unreach if UDP port
                                   // is opened or not.
     uint TcpSendRst;
                                   // Send RST if TCP port is opened or not.
     int
           SockRawEthRxLimit;
                                   // Raw Ethernet Receive limit
} IPCONFIG;
```



The structure entries are defined as follows:

_ipcfg.lcmpDoRedirect Update Route Table on ICMP Redirect

Default Value 1 (Yes)

Description When set, causes ICMP to automatically create a route to perform redirects on an IP

host to the gateway supplied in the redirect message. If set to false (0), you can take whatever action you feel necessary as the ICMP redirect will also generate a route

control message.

Default Value 64

Description This is the TTL value ICMP will use in messages it generates as a result of routing IP

packets. Legal values are in the range of (1-255).

_ipcfg.lcmpTtlEcho TTL for ICMP ECHO Reply Messages

Default Value 255

Description This is the TTL value ICMP will use in echo reply messages it generates in response to

receiving echo requests. Legal values are in the range of (1-255).

_ipcfg.lpIndex IP Start Index

Default Value 1

Description This is the initial value that is placed in the IP Id field for IP packets generated by the

system. Legal values are in the range of (1-65535).

_ipcfg.lpForwarding IP Forwarding Enable

Default Value 0 (No)

Description When set to true (1), this allows the stack to forward packets it receives for other IP

address to their next hop destination (i.e., it allows the stack to act as a router).

_ipcfg.lpNatEnable IP Network Address Translation Enable

Default Value 0 (No)

Description When set to true (1), this allows the stack to make use of the network address

translation (NAT) module. Note that in addition to setting this structure element, NAT

must also be configured. This is described in the following section.

_ipcfg.lpFilterEnable P Filtering Enable

Default Value 0 (No)

Description When set to true (1), this allows the stack to make use of the IP filtering module. Note

that this is automatically turned on when NAT is enabled in the stack. This module is

described in more detail in the NAT Service section of this document.



_ipcfg.lpReasmMaxTime Maximum IP Packet Reassembly Time in Seconds

10 **Default Value**

Description This is the maximum time that the stack will hold IP packet fragments while attempting to

assemble a complete packet. If the time expires before all the fragments arrive, the

packet is discarded.

ipcfg.lpReasmMaxSize Maximum IP Packet Reassembly Packet Size in Bytes

3020 **Default Value**

This is the maximum packet size that the stack will attempt to reassemble. As soon as Description

> the stack determines that the total packet size exceeds this value, the packet is discarded. The default size of 3020 is the maximum size given the default

implementation of the packet buffer manager (PBM). If a larger size is desired, then large buffer support must be added to the PBM module. This value is not otherwise

restricted. Note the MAC and IP headers are not included in this size limit.

_ipcfg.lpDirectedBCast Look for Directed Broadcast IP Packets

Default Value 1 (Yes)

Description A directed broadcast address is one where all the bits in the subnet portion of the

address are set to 1. For example, on the network 192.168.1.0:255.2555.255.0, the IP address 192.168.1.255 would be a directed broadcast IP. This address is treated as a broadcast for both IP send and receive. The IP layer can be told to disable directed broadcast by setting this value to zero. When disabled, the directed broadcast address is

treated like any other host address.

_ipcfg.TcpReasmMaxPkt Maximum Reassembly Packets Held by TCP Socket

2 **Default Value**

The TCP layer has its own packet reassembly module, allowing TCP packets to arrive Description

out of order, and yet be properly reassembled without the need to retransmit data. One potential issue with embedded environments where the socket receive buffers are large is that a significant number of packets can be tied up in TCP if the first packet of a large burst is lost. This value allows you to specify the maximum number of packets the TCP layer will hold per socket pending reassembly, or in other words, the maximum number

of out of order packets allowed.

Default Value 0 (No)

Description Route control messages keep the system informed of route updates. When set to Yes

(1), this variable causes RTC to process the route control message and convert the message into a debug call to IIDebugMessage(). Note that an application may also hook

into the RTC message loop using the RTCAddHook () function.

ipcfg.RtcAdvTime Time in Seconds to Send Router Advertisments

0 (Do not Send Router Advertisements) **Default Value**

The stack has the ability to automatically send ICMP router advertisements at a Description

predetermined interval. Setting this variable to a non-zero value determines the interval.



_ipcfg.RtcAdvLife Lifetime of Route in Router Advertisments

Default Value 120

Description If sending router advertisements (see above), this is the route lifetime that will be sent in

the ICMP message.

_ipcfg.RtcAdvPref Preference Level of Route in Router Advertisments

Default Value 0

Description If sending router advertisements (see above), this is the route preference level that will

be sent in the ICMP message. This value is signed.

_ipcfg.RtDownTime Time in Seconds a Route is "Down" Due to Failed ARP

Default Value 20

DescriptionTo stop an application from sending endless packets to a route that is not responding to

ARP, the route is brought down for a period of time so that the application will receive an error when IP attempts to send. After the designated time, the route is brought back up

and will attempt more ARP requests if used again.

Default Value 1200

Description Routes should not be held indefinitely. Use of a route is also not sufficient to keep the

route alive. This value represents the time an ARP validated route is held before it expires. If the route is revalidated via ARP during this period, the period is extended for

this interval from that point in time.

_ipcfg.RtArpInactivity ARP Inactivity timeout in seconds

Default Value 3

Description Time in seconds beyond which a route and an associated LLI/ARP entry if unused is

considered *inactive* or *idle*. Inactive ARP entries lifetime is not extended using ARP revalidation process and are instead deleted. The associated route entry is also

removed.

Default Value 120

Description When a host route is first cloned from a network route, it is assigned this default timeout.

Once the route is validated via ARP, the timeout is extended (see above).



_ipcfg.RtDefaultMTU Default MTU for Local Routes

Default Value 1500

Description When a route is created, it gets its MTU from the egress device. However, if the route is

local to the system, there is no egress device. In this case, a default MTU is used.

Default Value 64

Description This is the default IP packet TTL value of packets sent via a socket. Note that the

application can override this value with the sockets API.

_ipcfg.SockTosDefault Default TOS for Packets Sent via a Socket

Default Value 0

Description This is the default IP packet TOS value of packets sent via a socket. Note that the

application can override this value with the sockets API.

_ipcfg.SockMaxConnect Maximum Connections on a Listening Socket

Default Value 8

Description This is the maximum number of connections a socket will pend waiting for a sockets

accept() call from the application. Note: This value is also the upper bounds of the maximum connection argument supplied by an application via the sockets listen()

function (calls with higher values are silently rounded down).

_ipcfg.SockTimeConnect Maximum Time in Seconds to Wait on a Connect

Default Value 80

DescriptionThis is the maximum amount to time the sockets layer will wait on an actively connecting

socket. The default value of 80 is a few seconds longer than the TCP keep time, so TCP

will generate the official (more accurate) timeout error.

Default Value 0

Description This is the maximum amount of time the sockets layer will wait on a read or write

operation without any progress. For example, if the user calls send() with a very large buffer, the function will not time out so long as some fraction of the data is sent during the timeout period. After every successful transfer of data, the timeout period is reset. A

timeout value of ZERO means never time out.

_ipcfg.SockTcpTxBufSize TCP Transmit Buffer Size

Default Value 8192

Description This is the size of the TCP send buffer. A TCP send buffer is allocated for every TCP

socket. This value cannot be overridden by the sockets option function.



_ipcfg.SockTcpRxBufSize TCP Receive Buffer Size (Copy Mode)

Default Value 8192

Description This is the size of the TCP receive buffer allocated for a standard TCP socket. Note that

only SOCK_STREAM sockets use receive buffers. This value cannot be overridden by

the sockets option function.

_ipcfg.SockTcpRxLimit TCP Receive Limit (Non-Copy Mode)

Default Value 8192

Description This is the maximum number of cumulative bytes contained in packet buffers than can

be queued up at any given TCP based socket. Note that only TCP sockets using SOCK STREAMNC queue packet buffers directly to a socket. This value cannot be

overridden by the sockets option function.

_ipcfg.SockUdpRxLimit UDP Receive Limit

Default Value 8192

Description This is the maximum number of cumulative bytes contained in packet buffers than can

be queued up at any given UDP or RAW based socket. This value cannot be overridden

by the sockets option function.

_ipcfg.SockBufMinTx Min Size in Bytes for Socket "Able to Write"

Default Value 2048

Description This is the size in bytes required to be free in the TCP buffer before it is regarded as

able to write by the system. (Affects how the write fd set behaves in a *select()* call.) This value is usually about 25% to 50% of the send buffer size. UDP and RAW IP sockets are

always able to write.

_ipcfg.SockBufMinRx Min Size in Bytes for Socket "Able to Read"

Default Value 1

Description This is the size in bytes required to be present in a socket buffer for it to be regarded as

able to be read by the system. (Affects how the read fd set behaves in a select() call.)

Alter at your own risk.

ipcfg.PipeTimelo Maximum Time in Seconds to Wait on Pipe Read/Write

Default Value 0

Description This is maximum amount to time the file layer will wait on a read or write operation on a

pipe without any progress. For example, if the user calls *send()* with a very large buffer, the function will not time out as long as some fraction of the data is sent during the timeout period. After every successful transfer of data, the timeout period is reset. A

timeout value of ZERO means never time out.



_ipcfg.PipeBufSize Size in Bytes of Each End of a Pipe Buffer

Default Value 1024

Description This is the size of a Pipe send and receive buffer. This value is only examined when

pipes are created, so changing this value will not affect the buffering of existing pipes.

_ipcfg.PipeBufMinTx Min Size in Bytes for Pipe Able to Write

Default Value 256

Description This is the size in bytes required to be free in the Pipe buffer before it is regarded as

able to write by the system. (Affects how the write fd set behaves in a *select()* call.) It is usually about 25% to 50% of the send buffer size. This value is only examined when pipes are created, so changing this value will not affect the buffering of existing pipes.

_ipcfg.PipeBufMinRx Min Size in Bytes for Pipe "Able to Read"

Default Value 1

Description This is the size in bytes required to be present in the Pipe receive buffer for it to be

regarded as able to be read by the system. (Affects how the read fd set behaves in a *select()* call.) Alter at your own risk. This value is only examined when pipes are created,

so changing this value will not affect the buffering of existing pipes.

_ipcfg.TcpKeepIdle Keep Idle Time (0.1 Sec Units)

Default Value 72000 (2 hours)

Description This parameter only affects sockets that have specified the SO_KEEPALIVE socket

option. It is the time a TCP connection can be idle before KEEP probes are sent.

_ipcfg.TcpKeepIntvl Keep Probe Interval (0.1 Sec Units)

Default Value 750 (75 seconds)

DescriptionThis parameter only affects sockets that have specified the SO KEEPALIVE socket

option. It specifies the time between probe intervals once TCP begins sending KEEP

probes.

_ipcfg.TcpKeepMaxIdle Keep Probe Timeout (0.1 Sec Units)

Default Value 6000 (10 minutes)

DescriptionThis parameter only affects sockets that have specified the SO_KEEPALIVE socket

option. It is the time the TCP will continue to send unanswered KEEP probes before

timing out the connection.

_ipcfg.lcmpDontReplyBCast Do NOT Reply to ICMP Echo Request Packets Sent to broadcast/directed addresses

Default Value 0 (Reply to ICMP Echo Request packets sent to broadcast/directed broadcast

addresses)

Description When set, causes ICMP to not reply to ICMP Echo Request packets sent to broadcast or

directed broadcast addresses.



_ipcfg.lcmpDontReplyMCast Do NOT Reply to ICMP Echo Request Packets Sent to multicast addresses

Default Value 0 (Reply to ICMP Echo Request packets sent to multicast addresses)

Description When set, causes ICMP to not reply to ICMP Echo Request packets sent to multicast

addresses.

_ipcfg.RtGarp How to handle received gratuitous ARP packets

Default Value 0 (Discard received gratuitous ARP packets)

Description The hosts may send gratuitous ARP packets to broadcast their [IP number, MAC

address] information to inform other hosts in the network. This parameter determines the handling policy of received gratuitous ARP packets based on the following configuration

values:

0 - Discard the received gratuitous ARP packets. (default)

1 - If host is already in the routing table, update MAC address only.

2 - If host is already in the routing table, update MAC address. If host is not the routing table, add to the table. This option can cause growing of the table by adding entries for

not communicated host's information, and consumes more memory.

_ipcfg.lcmpDontReplyEcho Reply to ICMP Echo Request Packet

Default Value 0 (Reply to ICMP Echo Request packets with ICMP Echo Reply)

Description The ICMP Echo Request can be used to determine if a host on the Internet is

responding. The host receiving ICMP Echo Request replies with ICMP Echo Reply packet. The *ping* program uses ICMP Echo Request/Reply packets. It is a valuable tool diagnosing host and network problem. However, it can also be used to discover the IP numbers of hosts connected on the Internet. This option allows configuring to reply ICMP

Echo Request packets or not.

0 - Reply to ICMP Echo Request packets

1 - Do NOT reply to ICMP Echo Request packets

_ipcfg.UdpSendlcmpPortUnreach Reply with ICMP Port Unreachable if UDP port is not listened

Default Value 1 (Reply with ICMP Port Unreachable message)

Description The "port scanning" is used to discover which services is used on a host. If a UDP port

is not listened, the NDK replies with an "ICMP Port Unreachable" message to any received UDP datagram. So, you can find that if a UDP port is not open, and by exclusively determine which ports are open. This option allows configuring to reply or not

to not listened UDP ports.

0 - Do NOT reply with ICMP Port Unreachable message

1 - Reply with ICMP Port Unreachable message



_ipcfg.TcpSendRst Reply with RST message if TCP port is not listened

Default Value 1 (Reply with RST message)

Description The "port scanning" is used to discover which services is used on a host. If a TCP port is

not listened, the NDK replies with an RST message to a connection attempt (received SYN message). So, you can find that if a TCP port is not open, and by exclusively determine which ports are open. This option allows configuring to reply or not to not

listened TCP ports.

0 - Do NOT reply with RST message

1 - Reply with RST message

_ipcfg.SockRawEthRxLimit Raw Ethernet socket receive limit

Default Value 8192

Description This is the maximum number of cumulative bytes contained in packet buffers than can

be queued up at any given Raw ethernet socket. This value cannot be overridden by the

sockets option function.

A.14 Network Address Translation

The stack includes a small network address translation (NAT) function that can be used to setup virtual networks when the stack is acting as a router. When enabled, NAT will translate routed packets sent from or to a targeted virtual network.

If you are using XGCONF to configure your application, you can configure the NAT service to be enabled in the application by checking the box in the property sheet to add the module to your configuration. See the SPRU523 (TI Network Developer's Kit (NDK) User's Guide.) and the context-sensitive help for details.

A.14.1 Operation

NAT works by altering the TCP/UDP port numbers of a packet sent from a virtual network, and then using an alternate IP on the physical network to transfer the packet. For ICMP packets, the Id field of ICMP requests is used.

When configured, NAT will have a target virtual network that consists of a IP base address and a subnet mask. It also has a physical IP address that is used as a type of proxy for the translated packets.

The types of packets translated include:

- Any TCP or UDP packet
- ICMP ECHO and TSTAMP packets sent from the virtual network
- ICMP ECHOREPLY and TSTAMPREPLY packets sent to the virtual network
- ICMP error packets sent to the virtual network in response to a translated packet sent from the virtual network

The translation entries are created dynamically, and have a lifetime based on their protocol. ICMP and UDP translation entries have a fixed time limit based on the last time they were accessed. TCP expiration is based on the state of the TCP connection.

Note that some protocols (like FTP) communicate TCP/UDP port information in the packet payload. These types of protocols will not function under NAT without a custom proxy program to alter the packet payload. Individual proxies are not provided.



A.15 Network Interface Management Unit (NIMU)

A.15.1 Synopsis

NIMU architecture replaces the existing LL packet layer architecture, originally designed to communicate with only one instance of the device driver. It adds flexibility to the NDK core stack by adding the capability to communicate and control multiple device drivers simultaneously. In comparison to single-port serial device applications, the new NIMU architecture is best suited for Ethernet type devices where it is common to have multiple instances running concurrently.

NIMU implementation has two parts:

- NIMU NDK core layer that defines the APIs for the network applications to communicate with device drivers in an abstract manner. It also provides an interface between the NDK core stack and the device drivers.
- NIMU device driver interface counterpart that implements the NIMU APIs for the specific device driver.

Figure A-1 showcases NIMU architecture.

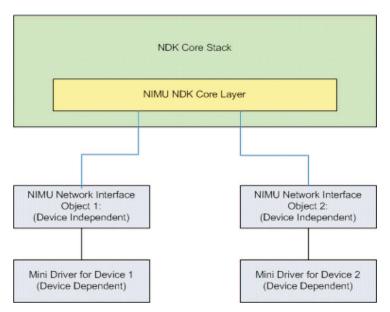


Figure A-1. NIMU Architecture

{



A.15.2 Data Structure Definition

The NIMU network interface object is equivalent to the device independent packet layer. Each NIMU network interface object is described with the following data structure:

```
typedef struct NETIF_DEVICE
   LIST_NODE links;
   /* Device Identification */
   uint index;
   char name[MAX_INTERFACE_NAME_LEN];
   /* Device Specific Information */
   uint flags;
   uint mtu;
   UINT8 mac_address[6];
   /* Internal Use: Number of references held. */
   uint RefCount;
   uint type;
   /* Pointer to 'driver specific private data' */
   void* pvt_data;
    /************************
    ******** Driver Interface Functions ***********
    ***********************
   int (*start)(struct NETIF_DEVICE* ptr_net_device);
   int (*stop)(struct NETIF_DEVICE* ptr_net_device);
   void (*poll)(struct NETIF_DEVICE* ptr_net_device, uint timer_tick);
   int (*send)(struct NETIF_DEVICE* ptr_net_device, PBM_Handle hPkt);
   void (*pkt_service) (struct NETIF_DEVICE* ptr_net_device);
   int (*ioctl)(struct NETIF_DEVICE* ptr_net_device, uint cmd,
        void* pbuf, uint size);
   int (*add_header) (struct NETIF_DEVICE* ptr_net_device, PBM_Handle hPkt,
        UINT8* dst_mac, UINT8* src_mac, UINT16 ether_type);
} NETIF_DEVICE;
```



The structure entries are described below:

links Pointers to the next and previous devices

Description Holds pointers to the previous and next devices in the chain of NIMU registered devices

in the system.

index Unique number to identity the device in the system

Description Numerically identifies devices uniquely in the system. Driver authors can specify a value

for the index; but in the case of conflicts its value will be modified to be unique in the system by the core. Therefore, if driver authors are using this in their code it is best to

re-read the value after the 'registration' process.

name Device name

Description Name of the device to identify it uniquely in the system. Driver authors can specify a

name for the device; but in the case of conflicts its value will be modified to be unique in the system. Therefore, if driver authors are using this in their code it is best to re-read

the value after the 'registration' process.

flags Device specific flags

Description Contains additional information which further describes the network device and its

properties. Driver authors should not set this value as this is used for internal operations

inside the NDK stack.

mtu Maximum transmission unit for the device

Description This defines the maximum size of a packet that can be transmitted over the device

without any fragmentation. Driver authors should configure this value to the maximum data payload that can be carried without the corresponding Layer2 header. For example, in Ethernet this will be 1514 (maximum data payload) - 14 (L2 Ethernet header) = 1500.

By default, the value for mtu is 1500.

mac_address Hardware address of this device

Description This is the hardware address of the device that uniquely identifies the device.

RefCount Reference count of the device

Description This indicates the number of references of network interface objects held by

components. Network Interface objects can only be removed from the system if there are no references of them held in the system. This is used internally by the NIMU control

module and should never be modified by the driver.

type Defines the interface type

Description For compatibility with the old network interface object, this is set to HTYPE_ETH or

HTYPE PPP depending on the type of network interface object. Moving forward, this

field will be obsolete and application authors should use the field instead.



pvt_data

Pointer to device-specific private data

Description

This can be used by the driver authors to store any additional driver-specific data. Memory allocation, Initialization and cleanup is the responsibility of the driver author the NDK NIMU module does not use this field in any way and is opaque to the NDK core stack.

The driver interface functions can be described as follows:

start Callback function registered by driver to open the controller

Syntax #include <stkmain.h>

int (*start) (NETIF_DEVICE* ptr_netif_device);

Return Value

The function returns a value of 0 on success and a negative value on error.

Description

The device start function is a registered call back function which is populated by the device driver author in the network interface object control block. Once the network interface object is registered with the NIMU NDK core stack during the registration process, the NDK core stack will call out this function. Device driver authors are recommended to place hardware initialization and start-up code in this callback function. After the successful completion of the API, the driver should be able to receive and transmit packets from the hardware. Driver authors must specify this callback function or else the NIMU registration will fail.

stop

Callback function registered by driver to close the controller

Syntax

#include <stkmain.h>

int (*stop) (NETIF_DEVICE* ptr_netif_device);

Return Value

The function returns a value of 0 on Success and a negative value on error.

Description

The device stop function is a registered call back function which is populated by the device driver author in the network interface object control block. The function is invoked by the NDK core stack when the NIMU network interface object is being unregistered from the NIMU system. Driver authors are recommended to place the hardware controller shutdown code in this API. After the successful completion of this API, the driver should not be able to receive or transmit packets. Driver authors must specify this callback function or else the NIMU registration will fail.



poll	Callback function registered by driver to be called periodically by the NDK.				
Syntax	#include <stkmain.h></stkmain.h>				
	<pre>void (*poll) (NETIF_DEVICE* timer_tick);</pre>	ptr_netif_device, uint			
Return Value	None				
Description	The call back function is used by the NDK core stack to periodically call the driver. Driver authors can use this function to monitor link activity or do any work outside the kernel mode context. The callback function registered here is not called from kernel mode.				
	Table A-1 summarizes the significance of tir	mer_tick.			

Table A-1. timer_tick

timer_tick	Definition
1	The polling function is called because of a timer event. It is recommended that device authors use this for doing periodic activities such as link management, watchdog timers, etc.
0	This indicates that the polling function has been called because the driver has indicated a STKEVENT_signal. This is useful for device authors to signify some activity outside kernel mode.

send	Callback function registered by driver to send packets.				
Syntax	<pre>#include <stkmain.h></stkmain.h></pre>				
	<pre>int (*send) (NETIF_DEVICE*</pre>				
Return Value	The function returns a value of 0 on success and a negative value on error. On success, the packet memory cleanup needs to be handled by the driver; but if an error is returned, the NDK core stack will cleanup the packet.				
Description	The device send function is an API which is used by the core NDK stack to pass packets to the driver for transmission. Driver authors must specify this callback function or else the NIMU registration will fail.				
	the Mino registration will fall.				
pkt_service	Callback function registered by driver for the NDK stack to receive packets				
pkt_service Syntax					
•	Callback function registered by driver for the NDK stack to receive packets				
•	Callback function registered by driver for the NDK stack to receive packets #include <stkmain.h></stkmain.h>				



ioctl Callback function registered by driver for the NDK stack to get/set configuration

Syntax #include <stkmain.h>

void (*ioctl) (NETIF_DEVICE* ptr_device, uint cmd,

void*pBuf, uint size);

Return Value The function returns a value of 0 on Success and a negative value on error.

Description This API is used by the NDK core stack to be able to get/set configuration in the drivers.

The interface can now be used to configure the multicast address list, change device MAC address, etc. Each NIMU network interface object can also identify its own custom IOCTL commands to do any device-specific configuration. This function is called from

kernel mode.

add_header Callback function registered by driver for the NDK stack to add custom L2 header

Syntax #include <stkmain.h>

void (*add_header)(NETIF_DEVICE* ptr_netif_device,
PBM_Handle hPkt, UINT8* dst_mac, UINT8* src_mac, UINT16

ether type);

Return Value None

Description This is a registered call back function added by the driver to add custom layer2 headers

on packets. This is called by the NDK core stack after layer3 has done its work. Ethernet driver authors can set this API to be NIMUAddEthernetHeader". However, if the driver is not a standard Ethernet driver, this can be used to add an appropriate layer2 header. For example, If the driver is USB-RNDIS, then this function can be defined to add not only the standard Ethernet header, but also the RNDIS header. If there are custom headers, then ensure there is sufficient head room in the packet buffers which are being allocated. Configuration of header and trailer sizes are provided by the NIMU exported

API NIMUSetRsvdSizeInfo. This function is called from kernel mode.

A.15.3 NIMU Configuration

For sample NIMU API usage, please refer to the DSK6455 and DM642 Ethernet driver code in the latest platform specific packages.

A.15.4 API Function Overview

NIMURegister Registers a NIMU compliant network interface object
NIMUUnregister Un-registers a NIMU compliant network interface object

NIMUGetRsvdSizeInfo Get current header and trailer size NIMUSetRsvdSizeInfo Set current header and trailer size

NIMUReceivePacket Interface API to pass packets to the NDK core stack
NIMUloctl Get/set configuration from the NIMU module and drivers



A.15.5 API Function Description

NIMURegister Callback Registers a NIMU compliant network interface object

Syntax #include <stkmain.h>

int NIMURegister (NETIF_DEVICE* ptr_netif_device);

Return Value The function returns a value of 0 on success and a negative value on error.

Description The API is used to register a NIMU compliant network interface object with the core NDK

NIMU module. As part of the registration process, the API will also invoke the start' API

to open and begin the corresponding the network device.

NIMUUnregister Un-registers a NIMU compliant network interface object

Syntax #include <stkmain.h>

int NIMUUnregister (NETIF_DEVICE* ptr_netif_device);

Return Value The function returns a value of 0 on success and a negative value on error.

Description The API is used to un-register a previously registered NIMU compliant network interface

object from the core NDK NIMU module. As part of the un-registration process, the API will also invoke the *stop* API to close the corresponding network device. This API can

only be called from within kernel mode.

NIMUGetRsvdSizeInfo Get current header and trailer size

Syntax include <stkmain.h>

void NIMUGetRsvdSizeInfo (int* hdr_size, int* trail_size);

Return Value The function returns the current header and trailer reserved space.

Description All packets set aside by the network interface management unit are allocated reserving

some space for headers and trailers. The API is used to get the current header and trailer size that NIMU will use from this point on. This API can only be called from within

kernel mode.

NIMUSetRsvdSizeInfo Set current header and trailer size

Syntax #include <stkmain.h>

void NIMUSetRsvdSizeInfo (int hdr_size, int trail_size);

Return Value None

Description All packets set aside by the network interface management unit are allocated reserving

some space for headers and trailers. The API is used to set the current header and trailer size that NIMU will use from this point on. There are no validations done on the header and trailer size values passed to the function. It is assumed that the system authors have configured this value correctly. This API can only be called from within

kernel mode.



NIMUReceivePacket Interface API to pass packets to the NDK Core stack

Syntax #include <stkmain.h>

int NIMUReceivePacket (PBM_Handle hPkt);

Return Value The function returns the 0 on success and <0 on error. Note that in case of error, the

function will clean the packet memory.

Description This is the interface function which has been exported by the NIMU module to pass

received packets to the networking stack. This API is available only for NIMU network interface objects and replaces the <code>EtherRxPacket</code> API, which handles the LL packet

architecture. This API can only be called from within kernel mode.

NIMUloctl Get/Set configuration from the NIMU Module and Drivers

Syntax #include <stkmain.h>

int NIMUIoctl(uint cmd, NIMU_IF_REQ* ptr_nimu_ifreq, void*

pBuf, uint size);

Return Value The function returns the 0 on success and a negative value on error.

DescriptionThis function is used to get and set configuration parameters from either the NIMU module or to the NIMU network interface objects driver attached to the NIMU module.

The NIMU_IF_REQ structure is defined as follows:

The structure is used to identify the NIMU network interface object which is being referred to. The introduction of NIMU network interface objects can be referred by a name or by a unique index. The NIMU IOCTL Interface searches for a matching device using the name; if no device is found then the device index is used to find a matching device. If none is found then an error is returned. The cmd parameter is used to specify the command, and pBuf and size are defined on a per command basis. Table A-2 summarizes the set of supported IOCTL commands and the values expected in the pBuf and size.



Table A-2. IOCTL Commands

Command	pBuf	Size	Description
NIMU_GET_DEVICE_HANDLE	&HANDLE	4	Use this to get the NIMU device handle associated with the device.
NIMU_GET_DEVICE_MTU	&UINT16	2	Use this to get the MTU associated with the device.
NIMU_SET_DEVICE_MTU	&UINT16	2	Use this to set the MTU associated with the device. No validations are done on this.
NIMU_GET_DEVICE_MAC	&UINT8[6]	6	Get the device MAC address.
NIMU_SET_DEVICE_MAC	&UINT8[6]	6	Set the device MAC address. In this case the MAC address is also passed down to the NIMU Network interface object so that the MINI-driver can also be reconfigured. If this is not supported by the driver the IOCTL fails.
NIMU_GET_DEVICE_NAME	&UINT8	20	Use this API to translate the device index to device name. The device name is returned in pBuf
NIMU_GET_DEVICE_INDEX	&UINT16	2	Use this API to translate the device name to device index. The device index is returned in pBuf
NIMU_ADD_MULTICAST_ADDRESS	&UINT8[6]	6	This API is used to add a multicast MAC address to the device multicast list. This IOCTL needs to be handled in the NIMU Network Interface Object Driver.
NIMU_DEL_MULTICAST_ADDRESS	&UINT8[6]	6	This API is used to delete a multicast MAC address to the device multicast list. This IOCTL needs to be handled in the NIMU Network Interface Object Driver.

Typically, most of the requests are done for a specific network interface object; but in some cases, configuration might be required for all NIMU network interface objects. In the case of these special cmd, the value of the interface request is NULL. These special case cmd are shown in Table A-3.

Table A-3. Special Case cmd

Command	pBuf	Size	Description
NIMU_GET_NUM_NIMU_OBJ	&UINT16	2	Use this to get the number of NIMU network interface objects active in the system.
NIMU_GET_ALL_INDEX &UINT16		(Number of NIMU Objects) * sizeof(UINT16)	The API is used to populate an array of all device index's present in the system. Memory allocated should be sufficient to store all this information. Use the above API to get an active count and allocate memory appropriately for pBuf.

This API cannot be called from kernel mode. It is recommended that system application authors use this API instead of directly trying to access low layer information.



A.16 Virtual LAN (VLAN) Support

A.16.1 Synopsis

Virtual LAN (VLAN) support in NDK adds the capability of receiving and transmitting VLAN tagged packets through the stack. VLAN support in NDK is available only in conjunction with NIMU architecture.

Figure A-2 highlights the VLAN module components in reference to the NIMU enabled NDK stack.

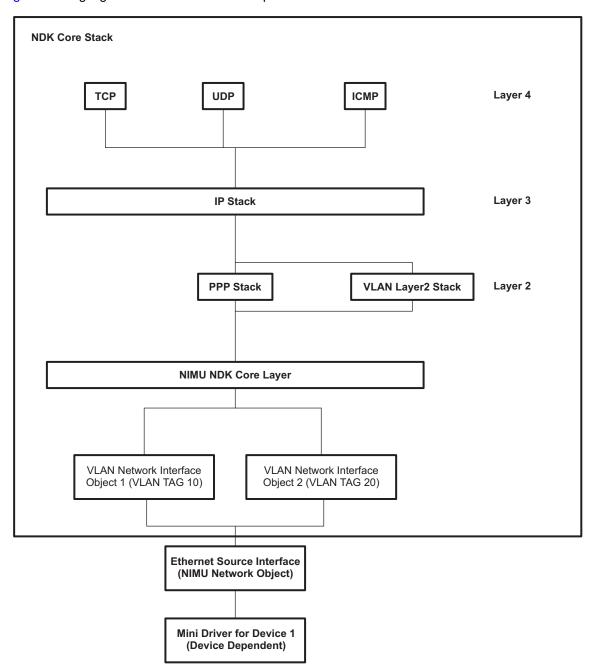


Figure A-2. VLAN Module Placement in NIMU Enabled NDK Stack

VLAN implementation has 2 parts:

- VLAN Layer2 stack that is responsible for the addition and deletion of VLAN headers in the transmit and receive paths.
- VLAN network interface objects which are instances of NIMU devices with VLAN specific attributes like



a VLAN Identifier, user priority, etc.

A VLAN network interface object is a NIMU device characterized additionally by these VLAN specific attributes:

- VLAN Identifier Each VLAN node is identified by a unique VLAN identifier per source interface.
- Source Interface The VLAN source interface is the actual physical interface on which the VLAN
 nodes are executing. This is the actual physical Ethernet interface on which packets are received and
 transmitted.
- Default Priority VLAN tagged packets carry a 16-bit tag also known as the tag control information (TCI) header. This field internally carries a 3-bit user priority. The value here is the *default priority* which is filled in these fields if the packet to be transmitted has no *priority specified*.
- User Priority Mapping The user priority mappings are specified to remap the packet priority to a 3-bit user priority.

A.16.2 User Priority Mapping Configuration

A user application can configure the user priority for a VLAN device using the well known setsockopt API which is discussed in great detail in Section 3.3.3. The following sections provide an example on how the VLAN user priority can be communicated by an application to the VLAN module in the core stack and how they are translated to bits in VLAN header of the packets.

A.16.2.1 User Priority Configuration

Figure A-3 shows two applications that use the NDK stack to communicate with other devices on the network through an Ethernet interface. The applications use the socket APIs described in Section 3.3.3 to send/receive packets through the device. With VLAN support, there should be a mechanism which the application authors will use to communicate the VLAN user priority value to associate their socket to the stack. This enables the stack to mark the user priority bits appropriately in the VLAN headers of the packets.

In Figure A-3, let's assume that Application1 is a high priority application and Application2 is a lower priority application. The network administrators on which the Ethernet is physically connected should have defined a *Traffic Conditioning Agreement*. All devices connected on that network should comply to this agreement that defines the user priority values for high and low priority application.

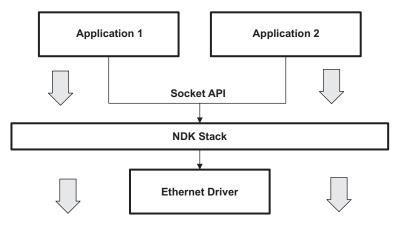


Figure A-3. VLAN Example



Assuming that the traffic condition agreement mentioned in Section A.16.2.1 is as follows:

Table A-4. User Priorities for Traffic Agreement

Application Priority	VLAN User Priority Bits
High	7
Low	5
Undefined	0

This implies that all packets generated by Application1 should be marked with the user priority value of 7. Similarly, all packets generated by Application2 should be marked with the user priority value of 5.

Each application is capable of sending and receiving packets only through the socket interface; therefore, you need to ensure that all sockets that send packets in Application1 are mapped to the correct priority level to ensure that they are marked to the user priority value of 7.

The other advantage of working out priority at the socket level instead of the application level is that granularity exists which allows prioritization even inside the applications. For example, one data flow in Application 1 could be low priority while the other could be high priority.

As mentioned before, the user priority can be communicated by the application using setsockopt API with the socket option parameter set to SO_PRIORITY and the value set to the appropriate user priority. Note that the valid range for the user priority is 0-7; although a value of 0xFFFF can be used to reset the priority back to default. For more details on how to get/set the user priority using getsockopt() and setsockopt() socket APIs, see Section 3.3.3.

Example

The following example configures the socket priority to be 0:

```
UINT16 priority = 0;
if (setsockopt(s, SOL_SOCKET, SO_PRIORITY, &priority, sizeof(priority) < 0)</pre>
    printf ("TEST Case Failed: 0x%x\n", fdError());
```

NOTE: Configuration of the socket priority is equivalent of indicating what the priority of the application is. The socket priority has no meaning outside the stack and is only used internally.



A.16.2.2 Marking Packet Priority

This section documents how the translation needs to be done to mark the *user priority bits*. Once an application has marked the socket priority, the VLAN module translates the socket priority to user priority bits using the following formula:

```
prio_mapping[socket_priority] = VLAN User Priority
```

Table A-4 shows the traffic conditioning agreement for the VLAN user priority bits. It indicates that Application1 has HIGH priority so the VLAN module should mark its VLAN user priority bits set to 7 and that Application2 has LOW priority so the VLAN module should mark its VLAN user priority bits set to 5.

To satisfy this requirement, Application1 should have the following code snippet:

```
UINT16 priority = 0;
if (setsockopt(s, SOL_SOCKET, SO_PRIORITY, &priority, sizeof(priority) < 0)
    printf ("TEST Case Failed: 0x%x\n", fdError());</pre>
```

The idea is that all packets generated by Application1 will have a socket priority of 0 (HIGH).

Similarly, Application2 should have the following code snippet:

```
UINT16 priority = 1;
if (setsockopt(s, SOL_SOCKET, SO_PRIORITY, &priority, sizeof(priority) < 0)
    printf ("TEST Case Failed: 0x%x\n", fdError());</pre>
```

The idea is that all packets generated by Application2 will have a socket priority of 1 (LOW).

The VLAN device should be created with the following code snippet:

```
/* By default: We configure the priority mapping to be as follows:-
 * Priority | VLAN User Priority
 *
      Λ
                  7
                  5
      1
      2
                  Ω
      3
      4
                  0
      5
                  0
                  0
      6
 * /
prio_mapping[0] = 7;
prio_mapping[1] = 5;
prio_mapping[2] = 0;
prio_mapping[3] = 0;
prio_mapping[4] = 0;
prio_mapping[5] = 0;
prio_mapping[6] = 0;
prio_mapping[7] = 0;
/* Use the VLAN API to create a new VLAN device. */
if (VLANAddDevice (src_index, 10, 0, prio_mapping) < 0)</pre>
    printf ("Error VLAN Failed errcode=%d\n");
```

The important point to note in this example is the configuration of the user priority table. This is basically the translation of the traffic conditioning agreement to an array.

With the VLAN device created as follows, if a packet is transmitted from Application1 it is marked with a socket priority of 0, and then it is translated by the VLAN module to user priority 7.



A.16.3 API Function Overview

The following are the APIs exported by the VLAN module in the core stack.

VLANInit Initializes the VLAN module in the core NDK stack.

VLANDeinit Deinitalizes the VLAN module and shuts down all the VLAN

enabled NIMU network interface objects in the system.

VLANReceivePacket Handles all VLAN tagged packets on the receive path.
VLANAddDevice Creates a VLAN device on a specified NIMU interface.

VLANDelDevice Deletes a previously created VLAN device.

A.16.4 API Functions

VLANInit Initializes the VLAN module in the core NDK stack.

Syntax #include <stkmain.h>

void VLANInit (void)

Return Value None

Description This function is used to initialize the VLAN module in the NDK core stack. It is for

internal stack usage only and should not be called by any application directly. This function is called as a part of the stack bring up, i.e., NC_NetStart invocation by the user application. It initializes the header and trailer sizes for VLAN NIMU objects that would

be created in the system later by a user application.

VLANDeinit Deinitalizes VLAN module and shuts down VLAN enabled NIMU network interface

objects

Syntax #include <stkmain.h>

void VLANDeinit (void);

Return Value None

Description This function is used to shutdown the VLAN module in the core stack. It closes and

shuts down any VLAN enabled NIMU network interface objects existent in the system. This function is for internal stack usage only and should not be called by any application directly. It is called as a part of stack teardown, i.e., when the user application invokes

NC NetStop function.

VLANReceivePacket Handles all VLAN tagged packets on the receive path

Syntax #include <stkmain.h>

uint VLANReceivePacket (PBM_Handle hPkt);

Return Value Returns 0xFFFF on error and on success returns the values of the encapsulated

protocol.

Description This function is called by the NIMU receive function when a VLAN tagged packet is

received. It validates the packet and ensures that there is a valid VLAN node on the system that can process the packet. This function is for internal stack usage only and

should not be called by any application directly.



VLANAddDevice Create a VLAN Network Interface object

Syntax #include <stkmain.h>

int VLANAddDevice (uint src_index, UINT16 vlan_id,

Return Value This function returns the device index of the new VLAN network interface object created

on a success or a negative value on error.

Description This API enables system developers to create a VLAN Network Interface object on a

specified NIMU source interface based on the arguments supplied. Note that this

function must be called from user mode only.

VLANDelDevice Deletes a previously created VLAN device

Syntax #include <stkmain.h>

int VLANDelDevice (UINT16 dev_index);

Return Value This function returns 0 on a success or a negative value on error.

Description This API deletes a previously created VLAN network interface object. The device index

passed is the index returned from the prior invocation of the VLANAddDevice API. Note

that this function must be called from user mode only.



www.ti.com Raw Ethernet Module

A.17 Raw Ethernet Module

A.17.1 Synopsis

A new module called the *Raw Ethernet Module* has been added to the NIMU enabled NDK stack to handle the Raw Ethernet packet traffic through NDK. A Raw Ethernet packet can be defined as an Ethernet packet whose Protocol type (Offset 12 in the Ethernet header) doesn't match any of the well known standard protocol types like IP (0x800), IPv6 (0x806), VLAN (0x8100), PPPoE Control (0x8863), PPPoE Data (0x8864). The Raw Ethernet Module interfaces with the application and the stack to provide the APIs required in configuring a raw ethernet socket, and in sending and receiving packets using it.

Figure A-4 shows the placement of the Raw Ethernet module in the NDK stack.

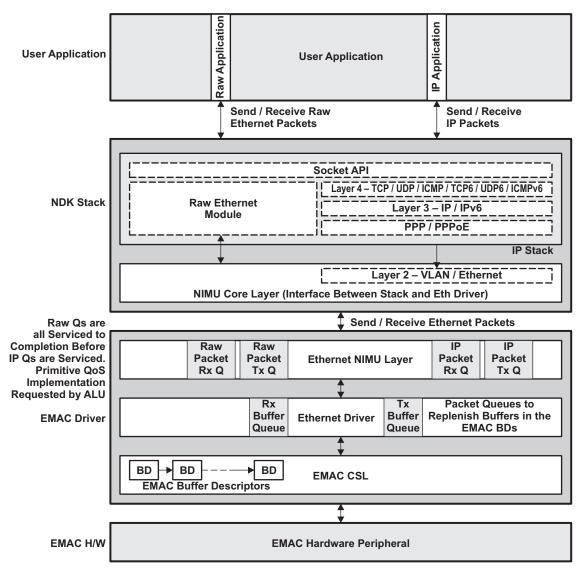


Figure A-4. Raw Ethernet Channel Manager Module in NDK



Raw Ethernet Module www.ti.com

As the Figure A-4 illustrates, traditional data path for the IP packets is different from the data path followed by the Raw Ethernet packets. The complete Layer 4, Layer 3 and Layer 2 processing in the NDK IP stack is bypassed for the Raw Ethernet packets. The Raw Ethernet packets alternatively travel through the Raw Ethernet Module which maintains a mapping between the custom Ethernet type configured and the interface on which the packets should be transmitted. This mapping is maintained in the "Raw Ethernet Socket" object structure. Also, shown in the above figure is the implementation of Raw Ethernet prioritization implementation in the driver using separate queues for IP and raw Ethernet traffic. This implementation is just an illustration of how this feature can be extended further to suit any application demands and is not really tied in with the design of Raw Ethernet Socket and Modules.

NOTE: The Raw Ethernet Module is supported only with NIMU enabled NDK stacks and drivers.

For more details on the Raw Ethernet Socket APIs, see Section 3.4 of this document.

A.17.2 Raw Ethernet Data Prioritization - Socket Priority Use Case

A user application can use the Socket Priority to add any sort of special differentiation that the raw Ethernet application would require for all packets travelling using the specified socket. For example, if there exists two raw Ethernet sockets, they could be both configured with different priorities using setsockopt() API discussed in Section 3.4.2 of this document. Further, a desired QoS scheme can be implemented in the Ethernet driver using this priority that is carried onto the packets. It can be also used by an application to map the priority to certain transmission properties like EMAC channel number on which the packets are to be transmitted etc. This section describes one such implementation of Socket Priority to implement Raw Ethernet Packet Prioritization over traditional IP traffic.

A.17.2.1 Socket Priority Configuration

In this specific use case, the application requires that:

- Raw Ethernet traffic and traditional IP traffic to be sent out on two separate EMAC channels.
- Further, it also requires that both on Transmit (Tx) and Receive (Rx) paths, the Raw ethernet data is always serviced before the IP data.

For the implementation to achieve this is two fold also:

For requirement 1, the application would have to create a Raw ethernet socket and configure the
socket priority to carry the EMAC channel number. The Raw Ethernet module in turn will ensure that all
packets travelling using this socket are tagged with the EMAC channel number in their "PktPriority"
field. The socket priority configuration is shown in the example below:

The following example creates a Raw Ethernet socket and configures the EMAC channel number to 3 using socket priority:

```
SOCKET sraw = INVALID_SOCKET;
UINT16 priority = 0;
int retVal, val;
/* Allocate the file environment for this task */
fdOpenSession( TaskSelf() );
/* Create the raw ethernet socket */
sraw = socket(AF_RAWETH, SOCK_RAWETH, 0x300);
if( sraw == INVALID SOCKET )
   printf("Fail socket, %d\n", fdError());
   fdCloseSession (TaskSelf());
   return;
/* Configure the transmit device */
val = 1;
retVal = setsockopt(sraw, SOL_SOCKET, SO_IFDEVICE, &val, sizeof(val));
if(retVal)
   printf("error in setsockopt \n");
```



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```
/* Configure the EMAC channel number */
val = 3;
retVal = setsockopt(sraw, SOL_SOCKET, SO_PRIORITY, &val, sizeof(val));
if(retVal)
    printf("error in setsockopt \n");
```

• Secondly, to implement the prioritization and also obtain the EMAC channel number on which the packet needs to be transmitted, the EMAC driver can inspect the "PktPriority" field of the packet and use it to enqueue the packet to the hardware accordingly. A code snippet from the ethernet driver is shown below for illustration purposes:

This is a code snippet from the "Send" routine of the ethernet driver.

```
/* Peek into the packet to check out if any prioritization is needed.

* All raw ethernet packets are tagged with the EMAC channel number onto
 * which they need to be sent outin the PktPriority field.
 */
if (((PBM_Pkt *)hPkt)->PktPriority != PRIORITY_UNDEFINED)
{
    /* Enqueue the packet in the Raw Tx Queue and send it for transmission.
    * Use the PktPriority field now as the EMAC channel number on which
    * packet needs to be Txed
    */
}
else
{
    /* This is just a normal IP packet. Enqueue the packet in the
    * Tx queue and send it for transmission.
    */
}
```

For more details on this use case implementation, please refer to the Ethernet driver code packaged in the NSP for TCI6488.

A.17.3 API Function Overview

The following APIs are exported by the Raw Ethernet module of the core NDK stack:

RawEthTxPacket API to send out Raw ethernet data using Raw ethernet sockets

copy

RawEthRxPacket API to handle raw ethernet packets received by the stack



A.17.4 API Functions

RawEthTxPacket Sends out Raw ethernet data, creates a copy of the data.

Syntax int RawEthTxPacket (HANDLE hRawEthSock, char* pBuffer, int len);

Parameters

hRawEthSock Handle to the raw ethernet socket

pBuffer Handle to the data buffer that needs to be sent len Length of data contained in the data buffer pBuffer.

Return Value

O Successfully sent out the packet

ENOBUFS Error allocating memory for the packet. Packet not sent out.

Description

This is the API called by the Raw Ethernet sockets module to transmit data sent by the application. This API allocates memory for the packet and the buffer according to the length specified, copies over the contents of the application buffer to the packet, and finally populates any socket priority configured on the socket to the *PktPriority* field of the packet for further use by the stack or the driver. It also increments the Raw ethernet success stats if the transmit succeeded. This API invokes the NIMUSendPacket API to send out the packet eventually.

RawEthTxPacketNC Sends out Raw ethernet data, without any copy of the data.

Syntax int RawEthTxPacketNC (HANDLE hRawEthSock, char* pBuffer, int len, HANDLE hPkt);

Parameters

hRawEthSock Handle to the raw ethernet socket

pBuffer Handle to the data buffer that needs to be sent len Length of data contained in the data buffer pBuffer

hPkt Handle to the packet that needs to be sent. The pBuffer is the data buffer

Return Value

O Successfully sent out the packet

EINVAL Bad Packet / Buffer Handles. Packet not sent out

Description

This is the API called by the Raw Ethernet sockets module to transmit data sent by the application without making any copy of it on the Tx path. This API is very useful for applications which have very definite performance requirements for their application. The buffers and packet handles passed here can be obtained in advance using the socket API *getsendncbuff()* by the application , then can be used to fill data and finally invoke the *sendnc()* API to transmit this data. The send no-copy API of the raw Ethernet socket module in turn invokes this API for finally transmitting the data. The raw Ethernet socket APIs are all discussed in detail in Section 3.4 of this document. This API validates the packet and buffer handles, and populates any socket priority configured on the socket to the *PktPriority* field of the packet for further use by the stack or the driver. It finally invokes the *NIMUSendPacket* API to send out the packet eventually. It also increments the Raw Ethernet success stats if the transmit succeeded. No memory allocations or copies are made by this API and hence is less intensive in terms of performance.



RawEthRxPacket Receive handler for Raw ethernet traffic in the stack.

int RawEthRxPacket (PBM_Handle hPkt); **Syntax**

Parameters

hPkt Handle to the packet which is passed up to the stack by the Ethernet

Return Value

0 Success 1 Error

Description This API is called by the NIMU layer when the Ethernet if a raw Ethernet socket object

> exists for the Ethernet type in the packet and if so enqueus in the socket buffer for the application to receive. No copies are made of the packet and the buffers further on the receive path by the Raw Ethernet socket layer and the packet is as is handed over for the application to use. This API also increments the Raw Ethernet receive stats

accordingly.

A.18 Obtaining Stack Statistics

Stack statistics are available from global structures or global arrays exported by the stack library. The declaration of these global identifiers appears in the interface specification for the individual protocols. The following protocols contain statistics information:

Protocol	Statistics Definition	
IP	IPIF.H	
ICMP	ICMPIF.H	
TCP	TCPIF.H	
UDP	UDPIF.H	
Raw Transport (non-TCP/UDP)	RAWIF.H	
Network Address Translation	NATIF.H	
Raw Ethernet	RAWETHIF.H	

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Network Address Translation

This section is required only for system programming that needs low level access to the Network Address Translation (NAT) layer. **This API does not apply to sockets application programming.**

This section describes functions that are callable from the kernel layer. You should be familiar with the operation of the operation of <code>//Exit()</code> functions before attempting to use the APIs described in this section (see Section A.1.2).

NAT has a unique status in the stack software because it can be an integral part of programming at both the user and kernel levels, or can be entirely redundant and even purged from the stack build.

This section describes the operation of the Network Address Translation software included in the NDK, how to configure it, how to install port mappings, and how to program proxy filter routines to support protocols like FTP.

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www.ti.com NAT Operation

B.1 NAT Operation

NAT is a translation of packet IP address. It is used by the stack when routing, to translate the IP address of a packet to/from a private LAN from/to a public WAN. NAT is required when the IP address paradigms on either side of the router are incompatible; for example, virtual addresses vs. physical addresses, or private vs. public. In the case of a home LAN, NAT allows multiple clients on the home LAN to use a single ISP account by sharing the router WAN IP address obtained from the ISP.

B.1.1 Typical Configuration

For the examples that follow, consider the typical configuration illustrated in Figure B-1. The NDK is executing as a home router (HR) and connects the home LAN subnet (192.168.0.x) to the Internet (WAN) via an ISP that has assigned HR an address of 128.1.2.12. The hosts on the home network (H1 and H2) have obtained their internet addresses from HR via DHCP. The IP of HR on the home LAN as well as the IP subnet used by the home LAN is pre-configured in HR. Figure B-1 also shows a host on the public internet (IH) to which the LAN hosts will connect. Lastly, it is assumed that the home LAN subnet is virtual, and NAT is required to allow H1 and H2 to share the WAN IP address assigned to HR by the ISP (128.1.2.12).

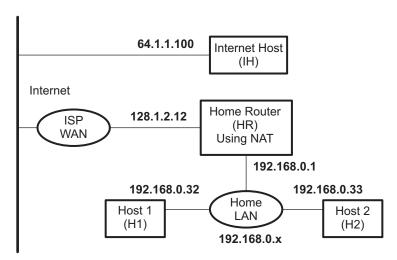


Figure B-1. Basic Home Network Configuration

B.1.2 Basic NAT

When sharing a single WAN IP address, the IP address obtained from the ISP is assigned to the router (the NDK in routing mode). Client machines that are to share the IP address are placed on the home LAN. The router routes traffic between the LAN and the WAN (internet via the ISP).

As packets traverse from the LAN to the WAN across the router, the source IP address of the packet (a LAN address) is replaced with the public IP address of the router. The result is that all packets sent to the WAN appear to have originated from the router with the public IP address obtained from the ISP.

As packets traverse from the WAN to the LAN across the router, the destination IP address of the packet (the router's WAN IP as obtained from the ISP) is replaced with the home LAN IP address of the physical client machine to which the packet is ultimately destined.

To perform this translation successfully, some details must be addressed. First, to allow multiple clients to share the public IP address in a non-ambiguous fashion, there must exist a deterministic method of mapping packets from the WAN to their correct destination on the LAN. This is done by keeping records of LAN IP clients that have initiated IP traffic, and by altering the TCP/UDP port (or ICMP Id field) as well as the IP address when performing the translation.

Every time a LAN client sends a packet to the WAN, the local IP address, port/id, and protocol is recorded for reverse mapping, as well as the destination IP address and port for security. When a packet is received from the WAN, the destination port/id is checked against the current database of NAT entries to see if the packet's destination address and port/id should be translated to a LAN client.



NAT Operation www.ti.com

For example, when accessing the Internet, all communication is normally initiated by the client. In this case, communication will be initiated by H1 or H2. Assume that H1 attempts to establish an HTTP connection with the Internet host (IH). It will send a connection request to the IP address assigned to IH, and a TCP port value of 80, which is HTTP. The request will be from its own IP address with an ephemeral port value that is picked from a pool (consider it random for these purposes- for example, 1001). So the request will be addressed as follows:

Packet 1

То	From	Protocol
64.1.1.100 : 80	192.168.0.32 : 1001	TCP

When the router HR receives this packet, it searches for a NAT entry that matches the *From* address of the packet. Because this is the first packet, assume the table is empty. When no entry is found, (skipping proxies for now) the router will create a new entry. It does this by recording information from packet 1, as well as picking a new port value from its own pool that has been specifically reserved for NAT (assume the range is 50000 to 55000, and that it chooses 50001). The new port is used as the packet's source port. The NAT entry record would look like the following:

NAT Entry Table

Foreign IP	Foreign Port	Local IP	Local Port	Mapped Port	IP Protocol	TCP State	Timeout
64.1.1.100	80	192.168.0.32	1001	50001	TCP	SYNSENT	00:01:00

The Local IP and Local Port values are those that are local to hosts on the home LAN. The Foreign IP value is the foreign side of the connection as viewed by hosts on the home LAN. The Mapped Port value is the source port when the packet is sent from HR. The source IP address used in the packet is that assigned to HR by the ISP. The IP protocol of the packet is recorded, and when using TCP, the state of the TCP connection is tracked to establish a reasonable timeout value. The SYNSENT value indicates that a connection request was sent. Before a full connection is established, the timeout is set fairly low for example, 1 minute.

As the packet is transmitted from HR to the ISP, it would look like the following:

Packet 1 (modified)

То	From	Protocol
64.1.1.100 : 80	128.1.2.12 : 50001	TCP

When IH receives the packet, it believes that the connection request came from HR. It thus sends the response packet to HR. The packet would be addressed as follows:

Packet 2 (response to packet 1)

То	From	Protocol
128.1.2.12 : 50001	64.1.1.100 : 80	TCP

When HR receives the packet, it checks the NAT entry table for an entry with a *Mapped Port* value equal to the destination port of the packet (in this case 50001). The value of *Protocol* and the source IP address/port values must also match the *Protocol*, *Foreign IP*, and *Foreign Port* fields of the NAT entry. This helps ensure that the reply is from the desired server.



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Here, HR finds the entry and proceeds to modify the packet. It replaces the destination address/port with the local address/port stored in the entry. It also resets the timeout of the entry. After modification, the packet would be addressed as follows:

Packet 2 (modified)

То	From	Protocol
192.168.0.32 : 1001	64.1.1.100 : 80	TCP

Once a connection is established, the timeout of the entry is set high (for example, five hours), because TCP connections can stay connected for an indefinite period of time without exchanging any packets.

If H2 attempts to connect to the same host simultaneously, it can share the public IP address assigned to HR. For example, H2 sends a connection request to IH addressed as follows:

Packet 3

То	From	Protocol
64.1.1.100 : 80	192.168.0.33 : 1024	TCP

HR would not find a NAT entry for 192.168.0.33:1024, so it would create one:

NAT Entry Table

	Foreign IP	Foreign Port	Local IP	Local Port	Mapped Port	IP Protocol	TCP State	Timeout
	64.1.1.100	80	192.168.0.33	1024	50002	TCP	SYNSENT	00:01:00
Ī	64.1.1.100	80	192.168.0.32	1001	50001	TCP	CONNECT	04:59:23

The modified packet and its reply would proceed similar to packets 1 and 2. Packets that pass from the LAN to the WAN are searched based on *Local IP* combined with *Local Port*. Packets that pass from the WAN to the LAN are searched based on *Mapped Port*. Note that for all entries on the NAT entry table, these values are unique.

B.1.3 NAT Port Mapping

So far, you have examined communication that has been initiated by hosts on the home LAN. Note that any unsolicited packets sent to HR from the WAN will not match any entry in the NAT table. These packets will be forwarded to the internal protocol stacks on HR, where they may or may not be used.

Now assume that a host on the home LAN (for example, H2) must place an HTTP server on the Internet. With what has been examined so far, it would be impossible to contact such a server from the WAN because no unsolicited traffic (like an HTTP connect request) can pass from the WAN to the LAN. However, H2 can acquire a portion of HR's WAN presence by mapping one of the well-known port values on the public WAN IP address to itself through port mapping.

In port mapping, a NAT entry is created to send all traffic destined for a specific port on the public IP address to an alternate destination. For well known ports like HTTP, the port value is not usually altered. Only the destination IP address changes. In this case, port 80 (HTTP) on the public IP address is mapped to port 80 of the LAN host H2. The entry would look as follows:

NAT Entry Table

Foreign IP	Foreign Port	Local IP	Local Port	Mapped Port	IP Protocol	TCP State	Timeout
wild	wild	192.168.0.32	80	80	TCP	_	STATIC



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When a connection request arrives from a remote host for the public IP address assigned to HR, as with the basic NAT discussion of the previous section, the destination port of the packet is matched with the *Mapped Port* value of the NAT entry. Normally, the *Foreign IP* and *Port* of the NAT entry must also match for source IP and port of the packet, but here the values are *wild*. This is because when the entry is created, the foreign peer is unknown. Because, every TCP connection state must be tracked in its own NAT entry, a second entry must be spawned. Any match of a wild NAT entry will spawn a fully qualified entry. For example, assume the following packet arrives:

Packet 4

То	From	Protocol
128.1.2.12 : 80	64.1.1.100 : 2006	TCP

The resulting NAT entry table would be:

NAT Entry Table

Foreign IP	Foreign Port	Local IP	Local Port	Mapped Port	IP Protocol	TCP State	Timeout
64.1.1.100	2006	192.168.0.32	80	80	TCP	SYNSENT	00:01:00
wild	wild	192.168.0.32	80	80	TCP	_	STATIC

The packet sent to the LAN by HR would be:

Packet 4 (modified)

То	From	Protocol
192.168.0.32 : 80	64.1.1.100 : 2006	TCP

Note that the wildcard entry's timeout is STATIC. This means that the entry will never expire. Note that when the new entry is spawned, it acquires a timeout.

One last point to note here is that the installation of a port map for port 80 does not prohibit HR from running its own HTTP server hosted on its private LAN IP address (192.168.0.1). This means that local hosts could get to a local HTTP server on 192.168.0.1, and the public HTTP server on 192.168.0.32, but outside hosts connecting to 128.1.2.12 could only get to the public HTTP server on 192.168.0.32.



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For example, assume the same topology as before, with the HR running both and HTTP and Telnet servers, H1 running an HTTP server, and H2 running a Telnet server. This is illustrated in Figure B-2.

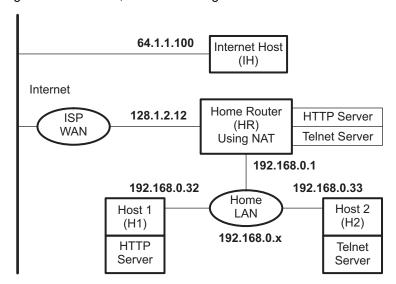


Figure B-2. Public Servers on the Home Network

To make the servers on H1 and H2 public, the following NAT port mapping entries are installed on HR:

NAT Entry Table

Foreign IP	Foreign Port	Local IP	Local Port	Mapped Port	IP Protocol	TCP State	Timeout
wild	wild	192.168.0.33	23	23	TCP	_	STATIC
wild	wild	192.168.0.32	90	90	TCP	_	STATIC

With these mappings, the externally available HTTP server and Telnet server publicly accessible on the WAN IP (128.1.2.12) are actually executing on H1 and H2. However, HR can have its own HTTP and Telnet servers and make them available to hosts on the LAN.

Also note that, regardless of how hosts on the LAN access HR (either through 192.168.0.1 or 128.1.2.12), their packets are not processed via NAT. Thus, they are never altered. The following are some connection examples:

Client	Protocol Used	Target Address	Resulting Server Connection
IH	HTTP	128.1.2.12	HTTP on H1
H2	HTTP	128.1.2.12	HTTP on HR
H2	HTTP	192.168.0.1	HTTP on HR
H2	HTTP	192.168.0.32	HTTP on H1
IH	Telnet	128.1.2.12	Telnet on H2
H1	Telnet	128.1.2.12	Telnet on HR
H1	Telnet	192.168.0.1	Telnet on HR
H1	Telnet	192.168.0.33	Telnet on H2



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B.1.4 NAT Proxy Filters

B.1.4.1 Problem Synopsis

Translating the IP destination address of a packet via NAT guarantees that all packets can be redirected to their correct physical destination, but it does not guarantee that the information will be understood by the recipient. Because one side of the connection always believes they are actually connected to a different IP address than their physical peer, there is a possibility that the application using the information will become confused. The confusion arises when there is information in the packet payload that is dependent on the IP address/port of the peer connection.

B.1.4.2 Problem Example - FTP Clients on the LAN

As a straightforward example of a situation that requires a proxy filter, consider FTP (file transfer protocol). FTP actually uses two ports to transmit a file. The first port establishes the control connection. Then, new ports establish the data connection to actually send the file. The FTP protocol allows an FTP client to specify its port for the data connection to the server. If no port is specified by the client, the client's control port value is used.

The above scenario presents a couple problems for standard NAT. First, if NAT creates an entry for the FTP control connection, the entry could not be used for the data connection. As an example, H1 sends an FTP connection request to IH. The packet would be addressed as follows:

Packet 1

То	From	Protocol
64.1.1.100 : 21	192.168.0.32 : 1137	TCP

HR would not find a NAT entry for 192.168.0.33:1137, so it would create one:

NAT Entry Table

Foreign IP	Foreign Port	Local IP	Local Port	Mapped Port	IP Protocol	TCP State	Timeout
64.1.1.100	21	192.168.0.32	1137	50003	TCP	SYNSENT	00:01:00

The modified packet and its reply would proceed as discussed in Section B.1.2. The modified packet would be:

Packet 1 (modified)

То	From	Protocol
64.1.1.100 : 21	128.1.2.12 : 50003	TCP

Now assume that eventually the FTP server on IH attempts to establish a data connection back to what it thinks is the FTP client's ephemeral port (50003). Note classic FTP uses port 20 to establish data connections. Its connection request packet would be:

Packet 2 (Data connection request)

То	From	Protocol
128.1.2.12 : 50003	64.1.1.100 : 20	TCP



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Because there is no NAT entry record that will match the address values in this packet (specifically port 20 in the *From* field), this packet will not be forwarded to the FTP client. For this to work, there must be a port mapping installed for 64.1.1.100 that has a wildcard port value (it is not certain that the connection request will arrive on port 20). The NAT entry table would be as follows:

NAT Entry Table

	Foreign IP	Foreign Port	Local IP	Local Port	Mapped Port	IP Protocol	TCP State	Timeout
Ī	64.1.1.100	wild	192.168.0.32	1137	50003	TCP	-	STATIC
Ī	64.1.1.100	21	192.168.0.32	1137	50003	TCP	CONNECT	04:58:39

With such a mapping, if a connection request from port 20 arrived, the wild card entry would be matched, and another entry spawned for port 20 on IH. The table would look as follows:

NAT Entry Table

Foreign IP	Foreign Port	Local IP	Local Port	Mapped Port	IP Protocol	TCP State	Timeout
64.1.1.100	20	192.168.0.32	1137	50003	TCP	SYNSENT	00:01:00
64.1.1.100	wild	192.168.0.32	1137	50003	TCP	-	STATIC
64.1.1.100	21	192.168.0.32	1137	50003	TCP	CONNECT	04:58:39

The second issue in dealing with an FTP client is that the client can change the port on which the FTP server attempts connection. This is done via a PORT command sent from the client to the server. The PORT command contains information about the client in the packet payload.

For example, assume the FTP client (H1) creates a new socket for the data connection, and its ephemeral port value is 1142. H1 would then send an FTP PORT command on the control connection to the server. The server would then attempt a connection. The following is an approximation of the operation (it is not the exact syntax of the port command).

Packet 3 (FTP Client H1 Sends Port Command for Port 1142)

То	From	Protocol	Packet Payload
64.1.1.100 : 21	192.168.0.32 : 1137	TCP	"PORT 192.168.0.32, 1142"

As a reminder, the FTP server would normally see the packet as:

Packet 3 (modified incorrectly)

То	From	Protocol	Packet Payload
64.1.1.100 : 21	128.1.2.12 : 50003	TCP	"PORT 192.168.0.32, 1142"

This packet creates a couple of problems. First, the IP address in the PORT command does not match the IP address of the FTP server's connected peer. This would produce an error. Plus, the IP address in the PORT command is not a real Internet address. Lastly, even if the FTP server tried to connect to 128.1.2.12:1142, there is no mapping for the port number in the NAT entry table.



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The correct procedure for modifying this packet is to solve all the above problems. First, a new NAT entry is created for 192.168.0.32:1142. The foreign IP address is left as a wildcard because as before, because it is not certain what port the FTP server will use. The NAT entry table would then look as follows:

NAT Entry Table

I	Foreign IP	Foreign Port	Local IP	Local Port	Mapped Port	IP Protocol	TCP State	Timeout
	64.1.1.100	wild	192.168.0.32	1142	50004	TCP		00:02:00
	64.1.1.100	wild	192.168.0.32	1137	50003	TCP	_	STATIC
	64.1.1.100	21	192.168.0.32	1137	50003	TCP	CONNECT	04:58:39

To review, note that you have the original NAT entry for the FTP control connection, and now two wildcard entries for possible FTP data connection requests.

The final step of the modification is to alter the payload of the packet so that the information in the PORT command matches the WAN IP address of HR (128.1.1.21) and the *Mapped Port* of the new NAT entry (50004). The correctly modified packet would be:

Packet 3 (modified correctly)

То	From	Protocol	Packet Payload
64.1.1.100 : 21	128.1.2.12 : 50003	TCP	"PORT 128.1.2.12, 50004"

It is also possible for a client to request the FTP server to create a new port (the PASV command), but that does not create any issues for FTP clients on the LAN. If the FTP server were on the LAN and the client on the WAN, the proxy process would key off the PASV command.

B.1.4.3 NDK Support for Proxy Filters

The modification procedure discussed above does have some multifaceted problems:

- 1. The creation of the first data connection wildcard entry depends on the knowledge by some entity that an FTP control connection has occurred, and what IP/PORT the connection occurred on.
- 2. The creation of the second data connection wildcard entry depends on the detection of a PORT command being passed from the client to the server.
- 3. The modification of the data payload of the packet containing the PORT command requires that some entity is examining packet payloads.
- 4. Modification of a TCP packet payload can permanently alter the values of the TCP sequence and acknowledge fields in the TCP header of all future packets on the control connection.

The first three problems are very specific to FTP, and the fourth problem (TCP sequence) is specific to any alteration of a TCP packet payload. Fortunately, the proxy filter support routines remove much of the burden of supporting these transformations.

The solution is twofold. First, the stack allows you to install proxy filter callback functions on specified TCP/UDP port values, either outgoing (for clients) or incoming (for servers). There are three callback functions involved.

The first callback function *Enable* is called when a new connection is attempted, or when the NAT entry expires. This function allows you to establish the basic connection state for the protocol in question. In the case of the FTP client example, the first wildcard data connection mapping would be installed here. Note that this function can also be used to filter connection requests. If this function returns zero, the connection request is ignored.

The second and third callback functions are mirrors of the other. They are the Tx and Rx functions. The Tx callback is called with the IP header of every packet that passes from the LAN to the WAN for the connection in question, while the Rx callback is called with the IP header of every packet that passes from the WAN to the LAN. While in these functions, the programmer can call a packet modify function to modify the payload of the packet. The system will automatically track and perform modifications to the TCP sequence values (when using TCP).



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In the case of the FTP client, there would be no Rx callback because only packets from the client need to be examined. The Tx callback would look for PORT commands from the client, and when one was detected, it would install the second wildcard port mapping as discussed in the previous section, and then modify the packet payload so that the PORT command reflected the WAN IP of HR, and the Mapped Port of the NAT entry.

B.1.4.4 FTP Proxy Filter Example Code

From the discussion in this section, it would be easy to draw the conclusion that developing proxy filter code would be horribly complicated. However, the actual implementation is straightforward. The code to implement the filter discussed in Section B.1.4.3 is shown below. The API for NAT and Proxy is discussed in the following sections.

```
// GetVal - Convert ASCII decimal string to integer
static uint GetVal( UINT8 **pData )
{
    uint v = 0;
    while(**pData >= '0' && **pData <= '9')</pre>
        v = v*10 + (*(*pData)++ - '0');
    (*pData)++; return(v);
}
11
// FTPCProxyEnable - Proxy for FTP Clients behind firewall
11
\ensuremath{//} NOTE: Proxy callback function operate at the kernel level. They
// may not make calls to user-level functions.
//
int FTPCProxyEnable( NATINFO *pin, uint Enable )
    HANDLE hNat;
    \ensuremath{//} Some implementations of FTP require the host to listen for
    // connections on the ephemeral port used to connect to the FTP
    // server. We create a STATIC mapping to handle this.
    if( Enable )
    {
        // Create it
        hNat = NatNew( pNI->IPLocal, pNI->PortLocal, pNI->IPForeign, 0,
                       IPPROTO_TCP, pNI->PortMapped, 0 );
        pNI->pUserData = hNat;
    }
    else
    {
        // Destroy it
        NatFree( pNI->pUserData );
    return(1);
}
// FTPCProxyTx - Proxy for FTP Clients behind firewall
// NOTE: Proxy callback function operate at the kernel level. They
// may not make calls to user-level functions.
//
int FTPCProxyTx( NATINFO *pNI, IPHDR *pIpHdr )
{
    UINT16
              Length, Offset;
    TCPHDR
              *pTcpHdr;
    UINT8
              *pData;
    HANDLE
              hNAT;
    NATINFO *pNINew;
    char
              tmpstr[32];
```



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```
UINT16
          PortNew;
IPN
          IPNew;
pData = (UINT8*)pIpHdr;
// Get pointer to TCP header
Offset = (pIpHdr->VerLen & 0xf) * 4;
pTcpHdr = (TCPHDR *)(pData + Offset);
// Get length of the IP payload
Length = HNC16(pIpHdr->TotalLen) - Offset;
// Get the offset into the TCP payload and payload size
Offset += pTcpHdr->HdrLen >> 2;
Length -= pTcpHdr->HdrLen >> 2;
// Get pointer to TCP payload
pData += Offset;
// For clients, we only care about sending PORT commands
//
// For example, if our client IP is 192.138.139.32, and it reports
// port 384, the form of the command sent to the FTP server would
// be: "PORT 192,138,139,32,1,128\r\n"
//
// We replace the Client IP with the router's IP, and the client
// port with a NAT port which is mapped to the client port.
11
if(!strncmp( pData, "PORT ", 5) )
{
    // Get the IP/Port declared by sender
    // Form is "i1,i2,i3,i4,p1,p2"
    pData += 5;
    IPNew = ((UINT32)GetVal (&pDada)) << 24;</pre>
    IPNew |= ((UINT32)GetVal (&pDada)) << 16;</pre>
    IPNew |= ((UINT32)GetVal (&pDada)) << 8;</pre>
    IPNew |= ((UINT32)GetVal (&pData));
    IPNew = htonl(IPNew);
    PortNew = GetVal(&pData);
    PortNew = (PortNew<<8) + GetVal (&pData);</pre>
    // Add a NAT mapping to client's IP and Port
    hNAT = NatNew(IPNew, PortNew, pNI->IPForeign, 0, IPPROTO_TCP,
                  0, NAT_IDLE_SECONDS);
    if(!hNAT)
        return(0);
    // Get Server IP and Mapped Port
    IPNew = htonl( NatIpServer );
    pNINew = NatGetPNI( hNAT );
    PortNew = pNINew->PortMapped;
    // Print a replacement string with IP and Port
    sprintf(tmpstr, "%u,%u,%u,%u,%u,%u\r\n",
            ((uint)(IPNew >> 24)), ((uint)(IPNew >> 16)&0xFF),
            ((uint)(IPNew >> 8)&0xFF), ((uint)(IPNew)&0xFF),
            PortNew>>8, PortNew&0xFF);
    // Replace the original string with ours
    ProxyPacketMod( Offset+5, Length-5, strlen(tmpstr), tmpstr );
return(1);
```

}



www.ti.com NAT Port Mapping

B.2 NAT Port Mapping

NAT port mapping allows a client machine on the LAN (or home network) to appear on a specific port of the router's public WAN IP address. This API (and NAT in general) is only used when the NDK is acting as an IP router, and when the IP network on one side of the router is using virtual IP addresses.

The functions described in this section illustrates how to install and remove port mappings. The functional operation of NAT and NAT Port Mapping is discussed in more detail in Section B.1.

B.2.1 Function Overview

The following functions create and destroy port mappings:

NatNew() Create a new NAT entry (for port mapping)

NatFree() Free a NAT entry

NatGetPNI() Get a pointer to a NAT entry's NATINFO structure

B.2.2 NAT Entry Information Structure

A port mapping is just a NAT entry. Each NAT entry has its own information structure. This NATINFO structure allows you to examine the status of a particular entry.

The specification of the NATINFO structure is as follows:

```
typedef struct _natinfo {
                                  // Current TCP State (Simplified)
         uint TcpState;
                                   // Closed or closing
#define NI_TCP_CLOSED 0
                                    // Connecting
#define NI_TCP_SYNSENT 1
         NI_TCP_ESTAB 2 // Established
IPN IPLocal; // Translated IP Address
#define NI_TCP_ESTAB 2
         UINT16 PortLocal; // Translated TCP/UDP Port
IPN IPForeign; // IP Address of Foreign Peer
UINT16 PortForeign; // Port of Foreign Peer
         UINT8 Protocol; // IP Potocol
UINT16 PortMapped; // Locally Mapped TCP/UDP Port (router)
         HANDLE hProxyEntry; // Handle to Proxy Entry (if any)
         UINT32 Timeout; // Expiration time in SECONDS
         void *pUserData;
                                  // Pointer to proxy callback data
} NATINFO;
```

The individual fields are defined as follows:

• uint TcpState;

This is a condensed version of the state of the TCP connection that is being translated by this entry. This field is only valid when the Protocol field is set to IPPROTO_TCP. The defined values are:

```
NI_TCP_CLOSED The connection is closed

NI_TCP_SYNSENT The peers are in the process of connecting

NI_TCP_ESTAB A connection has been established
```

IPN IPLocal;

This is the IP address (in network format) of the peer host on the local network (LAN). It is the entity that has been assigned a virtual IP address behind the firewall.

UINT16 PortLocal;

This is the port in use by the peer host on the local network (LAN). It is the entity that has been assigned a virtual IP address behind the firewall.

IPN IPForeign;

This is the IP address (in network format) of the peer host on the public network (WAN). It is the entity that is on the physical network outside the firewall.

• UINT16 PortForeign;



This is the port in use by the peer host on the public network (WAN). It is the entity that is on the physical network outside the firewall.

• UINT8 Protocol;

This is protocol in use by the NAT entry. It must be IPPROTO_TCP, IPPROTO_UDP, or IPPROTO ICMP.

UINT16 PortMapped;

This is the port in use by the router on its public (WAN) IP address. It is this port that maps back to a specific local IP/port on the LAN.

HANDLE hProxyEntry;

When a NAT entry is created as a result of a proxy filter being installed on a specific port, the HANDLE to the proxy filter that spawned the NAT entry is stored here.

UINT32 Timeout;

This is time in seconds when the proxy entry will expire. The system checks with a fairly large granularity, so the actual expiration can occur 10 to 20 seconds later. If this value is ZERO, the entry is static. A NAT entry must be specified as STATIC when it is created. Setting Timeout to ZERO will cause the entry to expire in 0 to 20 seconds.

void * pUserData;

This field is reserved for use by proxy filter callback functions. It is not used by the system software.

The NAT information structure is of little importance when only port mapping is required. It is mostly for use in NAT proxy filters.

B.2.3 NAT API Functions

NatNew	Create a NAT Entry (fo	or Port Mapping)
Hatitow	Orcate a NAT Littly (N	σι ι σιτινιαρριιίς)

Syntax HANDLE NatNew(IPN IPLocal, UINT16 PortLocal, IPN IPForeign, UINT16 PortForeign,

UINT8 Protocol, UINT16 PortMapped, UINT32 Timeout);

Parameters

IPLocal IP address (in network format) of host on the LAN to map

PortLocal TCP/UDP port value of host on the LAN to map

IPForeign IP address of WAN peer (usually NULL/wild for port mappings)

PortForeign TCP/UDP port of WAN peer (usually NULL/wild)
Protocol IPPROTO_TCP or IPPROTO_UDP)

Port Mapped Port on router's public WAN to map (usually a well-known port)

Timeout of entry in seconds (NULL for STATIC)

Return Value

Handle to NAT entry, or NULL on error.

Description

This function creates a NAT entry with the parameters as specified.

For example, to allow a host on a virtual IP address of 1.2.3.4 to run a Telnet server reachable via the router's public (physical) IP address, a mapping would be installed to map TCP port 23 (telnet) to 1.2.3.4:23. If the connection were to be open to all foreign hosts, then *IPForeign* and *PortForeign* would be left NULL. The value of *Timeout* would also be NULL to make the entry STATIC.

```
hNatTelnet = NatNew( htonl(0x01020304), 23, 0, 0, IPPROTO TCP, 23, 0);
```

The function returns a handle to the NAT entry created. This handle should be freed with NatFree() when the mapping is no longer desired.



NatFree Destroy a NAT Entry

Syntax void NatFree(HANDLE hNat);

Parameters

hNat Handle to NAT entry created with NatNew()

Return Value None.

This function frees the supplied NAT entry. It is called to remove a STATIC NAT entry Description

that is no longer required.

NatGetPNI Get a Pointer to a NAT Entry's NATINFO Structure

NATINFO NatGetPNI(HANDLE hNat); **Syntax**

Parameters

hNat Handle to NAT entry created with NatNew()

Return Value Pointer to NATINFO structure or NULL on error.

Description This function returns a pointer to the NATINFO structure defined in Section B.2.2. It is

used mainly by NAT proxy filter callback functions.

B.3 NAT Proxy Filters

NAT proxy filters allow NAT to operate correctly with network protocols that have addressing specific data in their packet payload data. This API (and NAT in general) is only used when the NDK is acting as an IP router, and when the IP network on one side of the router is using virtual IP addresses.

The functions described in this section illustrate how to install and remove port proxy filters and their associated callback functions. The functional operation of NAT and NAT Port Mapping, and NAT Proxy is discussed in more detail in Section B.2.2.

B.3.1 Function Overview

The following functions create and destroy proxy filters:

ProxyNew() Create Proxy Filter for NAT entries ProxyFree() Destroy a Proxy Filter declaration

The following function can be called from within a proxy filter callback function:

ProxyPacketMod() Modify a packet being processed by NAT



B.3.2 NAT Proxy Filter Callback Functions

The proxy filter callback functions allow the proxy programmer to examine NAT entry properties as the entries are created, plus the examination of packet data as packets pass between the LAN and WAN. This section describes the syntax of the callback functions that are supplied to the proxy filter when it is first installed in the system.

ProxyEnableCallback Proxy Enable Callback Function

Syntax int SampleProxyEnableCallback(NATINFO *pNI, uint EnableFlag);

Parameters

pNI Pointer to NATINFO structure of NAT entry created

EnableFlag Set to 1 for an enable request

Return Value 1 to allow normal operation, or NULL to abort new NAT entry.

Description This function is called when a NAT entry containing a proxy is created or destroyed.

When the entry is created, the value of *EnableFlag* is 1. When the entry is being

destroyed, the value of *EnableFlag* is zero.

When *EnableFlag* is set, the return value of this function determines if the NAT entry will be enabled. If this function returns NULL, the NAT entry is immediately destroyed (in this event, the callback is not called a second time for this destroy). This can be used to

restrict peer connections.

ProxyTx/RxCallback Proxy Tx/Rx Callback Functions

Syntax int SampleProxyTxCallback(NATINFO *pNI, IPHDR *plpHdr);

int SampleProxyRxCallback(NATINFO *pNI, IPHDR *plpHdr);

Parameters

pNI Pointer to NATINFO structure of NAT entry in use plpHdr Pointer to the IP header of the packet being translated

Return Value 1 to allow normal operation, or NULL to abort the supplied packet.

Description This function is called when a packet is crossing the router from the WAN to the LAN

(Rx callback) or from the LAN to the WAN (Tx callback). The NAT entry containing a proxy that matches the packet is described by the supplied NATINFO structure. This

structure was described in Section B.2.2.

The purpose of the callback is to examine the packet and take appropriate action based on its contents. The packet payload can be easily modified by the *ProxyPacketMod()* function described later in this section. The translation of the IP address and port information cannot be altered by this callback; however, the callback can act as a packet

filter and discard unwanted packets by returning a value of NULL.



B.3.3 NAT Proxy API Functions

ProxyNew Create a New Proxy Filter for NAT Entries

HANDLE ProxyNew(uint NatMode, UINT8 Protocol, UINT16 Port, IPN IPTarget, int **Syntax**

(*pfnEnableCb)(NATINFO *, uint), int (*pfnTxCb)(NATINFO *, IPHDR *), int

(*pfnRxCb)(NATINFO *, IPHDR *));

Parameters

NatMode Port direction to detect (NAT_MODE_RX or NAT_MODE_TX)

Protocol to use (IPPROTO TCP or IPPROTO UDP) Protocol

Port value for RX or TX packets to detect Port **IPTarget** New IP destination NAT_MODE_RX proxy

pfnEnableCb Pointer to proxy *Enable* callback function (NULL if none) pfnTxCb Pointer to proxy Tx callback function (NULL if none) pfnRxCb Pointer to proxy Rx callback function (NULL if none)

Return Value Handle to new proxy, or NULL on error.

Description This function creates a hook that is examined whenever a new NAT entry is created.

> The calling parameter NatMode specifies the direction of the proxy (NAT MODE RX for servers behind the firewall, and NAT MODE TX for clients behind the firewall).

The Protocol and Port values are the IP protocol and well known port of the protocol to

proxy.

For example, if setting up a FTP client proxy, set:

NatMode = NAT MODE TX, Protocol = IPPROTO TCP, and Port = 21.

IPTarget is used only in server proxies (when NatMode is set to NAT MODE RX). This specifies the machine behind the firewall that is actually providing the service.

The three pointers to callback functions correspond to the proxy filter callback functions described in the previous section.

The function returns a handle to the new proxy. Note that a proxy handle is not the same as (or compatible with) a NAT entry handle.

The proxy should be destroyed by calling ProxyFree() when it is no longer needed.

ProxyFree Destroy a Proxy Filter Declaration

void ProxyFree(HANDLE hProxy); **Syntax**

Parameters

hProxy Handle to Proxy Filter entry created with ProxyNew()

Return Value None.

This function frees the supplied Proxy Filter entry. It is called to remove an entry that is Description

no longer required.



ProxyPacketMod Modify the Contents of a Packet

Syntax IPHDR *ProxyPacketMod(uint Offset, uint OldSize, uint NewSize, UINT8 *pNewData);

Parameters

Offset Offset in bytes from start of IP header to first modified byte

OldSize Size of old data at Offset

NewSize Size of new data to replace old data at Offset

pNewData Pointer to new data to replace old data

Return Value Pointer to new IP header of packet. This pointer is used for further modifications (if

needed).

Description This function may only be called from a proxy filter callback function. Its purpose is to

modify the contents of a TCP or UDP packet, and perform the necessary adjustments for

packet size - including TCP sequencing adjustment.



Point-to-Point Protocol

Point to point protocol (PPP) was originally designed as a replacement for SLIP (serial line IP) in sending IP packets via a serial line. In addition to its massive popularity in performing this function, PPP has also been increasingly used for the transmission of packets over other media. This is due to PPP's inherent peer-to-peer nature, allowing for per-connection security and billing.

The NDK has built-in support for both PPP servers and clients. The PPP support API is designed to be shared by one or more physical devices. One obvious device that can be hooked to PPP is a serial line, but the stack also contains support for PPP over Ethernet (PPPoE). The low level PPP API as well as Serial HDLC and PPPoE are all discussed in this appendix.

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C.1 Low Level PPP Support

This section describes the operation of the PPP support API included in the NDK.

NOTE: Unlike the HDLC and PPPoE APIs that are application callable, the low level PPP support API is designed to be called from the kernel layer only. You should be thoroughly familiar with the operation of the kernel and the IIEnter()/IIExit() functions before attempting to use the APIs described in this section.

C.1.1 PPP Operation

PPP is very much like Ethernet in that there is a defined packet format. The basic PPP packet is shown below. It consists of flag delimiters, address and control bytes, protocol field (similar to ether-type under Ethernet), and a two byte checksum.

Figure C-1. Standard PPP Frame Over Serial Line

Flag (7E)	Addr (FF)	Control (03)	Protocol	Payload	CRC	Flag (7E)
<u> </u>	4	4	•	4500	_	4
1	1	1	2	1500	2	1

To abstract out the actual processing of the PPP data from the processing of the PPP frame encoding, the PPP support included in the NDK expects a smaller frame, consisting of the protocol and payload fields only. This format is shown in Figure C-2.

Figure C-2. PPP Frame Processed by PPP API

Protocol		Payload
2		Size specified by layer 2 (about 1500)

The abstraction of PPP from the layer 2 encoding allows PPP to be carried by a variety of physical devices. The programming interface to the PPP layer called by the application is actually exposed by the layer 2 encoder. This layer 2 encoder is referred to as a serial interface (SI), but does not have to be a serial port. This interoperation between PPP and the SI is shown in Figure C-3. The functions shown in the dotted rectangle are those provided by the serial interface software.

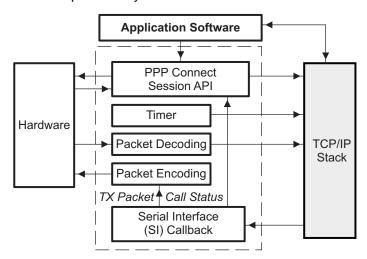


Figure C-3. Serial Interface (SI) Abstraction







As shown in Figure C-3, the SI interface has the responsibility of providing for connection control, a timer used by PPP for timeout, packet encoding and decoding, and a SI callback function for status messages and packet transmission. Note that the SI driver developer also defines the actual API used by the application software to establish and tear down PPP connection sessions. There is no specific requirements in specifying the session API for any particular PPP device, but the APIs defined for HDLC and PPPoE can be used as a guide.

C.1.2 Function Overview

The SI interface module is charged with communicating with both the hardware and the application program, but the PPP packets themselves are processed via the PPP support functions in the stack. The PPP support software provides the following functions for use by the SI module:

pppNew()	Create a new PPP connection instance
pppFree()	Destroy an existing PPP connection instance
pppTimer()	Inform PPP that a 1 second timer tick has expired
pppInput()	Pass in a received PPP packet for processing

The formal declaration of these functions appear later in this section (see Section C.1.6).

NOTE: These functions can only be called in kernel mode. See Appendix for programming in kernel mode.

C.1.3 Supported Protocols

In keeping with trying to maintain a small footprint, the PPP software supports a subset of the general PPP protocols. The following are supported:

- Link Control Protocol (LCP)
- Internet Protocol Control Protocol (IPCP)
- Password Authentication Protocol (PAP)
- Challenge Handshake Authentication Protocol (CHAP) using MD5
- Internet Protocol (IP)

C.1.4 SI Module Callback Function

The PPP support API is used for connection instance creation and destruction, and to pass received packets to the stack. To get information about PPP back from the stack, and to allow the stack to request the transmission of PPP packets, the SI module supplies a callback function. A pointer to this callback is passed to PPP as a parameter to pppNew().

NOTE: This function is called in kernel mode. See Appendix for programming in kernel mode.



C.1.4.1 Function Declaration

The SI callback function is provided in the SI code module using the following definition:

SIControl Notify the Serial Interface of a Change in Status, or when SI Needs to Transmit a

Packet

Syntax void SIControl(HANDLE hSI, uint Message, UINT32 Data, PBM_Handle hPkt);

Parameters

hSI Handle to SI private data

Message code describing the PPP event
Data Additional data concerning the message

hPkt Handle to a PBM packet when Message is SI_MSG_SENDPACKET

Return Value None.

Description This function is called when a PPP needs to notify the serial interface (SI) of a change in

status, or when it needs SI to transmit a packet.

The *hSI* parameter is a handle (pointer to a void) that is originally passed to PPP via *pppNew()*. This value allows the SI module to know which of its own connection instances is in use. The PPP instance handle in use is not supplied, but rather should be obtained by reference from the supplied SI handle. If the programmer of the SI module does not wish to track handles, then this parameter may be NULL (always as originally supplied to *pppNew()*). This is NOT the handle to the PPP instance that is passed to

other functions in the PPP API.

The purpose of the callback is determined by the value of the Message parameter. The

following message values are defined for this parameter:

SI_MSG_CALLSTATUS PPP connection status has changed

SI_MSG_SENDPACKET PPP is requesting a packet to be encoded and transmitted

SI_MSG_PEERCMAP LCP has received the peer's 32 bit asynchronous character map

C.1.4.2 SI_MSG_CALLSTATUS Message

When this message value is set, the callback function was called by PPP to update the status of the connection instance. When the callback is called with this message, the value of *Data* contains additional information about the call. *Data* can be set to any of the following values:

SI_CSTATUS_WAITING

SI_CSTATUS_NEGOTIATE

SI_CSTATUS_AUTHORIZE

SI_CSTATUS_CONFIGURE

Connection instance is idle

Instance in LCP negotiation stage

Instance in authorization stage

Instance in IP configuration stage

SI_CSTATUS_DISCONNECT Connection dropped

SI_CSTATUS_DISCONNECT_LCP Connection dropped in LCP stage

SI_CSTATUS_DISCONNECT_AUTH Connection dropped in authorization stage
SI_CSTATUS_DISCONNECT_IPCP Connection dropped in IP configuration stage



If Data is set to any of disconnect messages, pppFree() should be called to destroy the connection instance. For all other status values, no action is required.

NOTE: It is always safe to assume that when the value of Data >= SI_CSTATUS_DISCONNECT, the message is some type of disconnect.

C.1.4.3 SI MSG SENDPACKET Message

When this message value is set, the callback function was called by PPP to transmit a packet. The Data parameter is set to the 16 bit PPP protocol of the packet, and the hPkt parameter contains a handle to a packet (PKT) object that contains the packet payload. It is the job of the SI callback function to encode the packet and transmit it on the physical hardware.

C.1.4.4 SI MSG PEERCMAP Message

Serial interfaces to PPP require a translation map for the first 32 character values. This map informs the packet encoded which characters must be escaped and which do not. The default value of the peer CMAP should be 0xfffffff, and updated only when this message is received. Whether or not PPP will attempt to exchange CMAP information with its peer, is determined by passing flags to pppNew() when the connection instance is created.

C.1.4.5 Example Callback Function Implementation

The following is an example of a SI module callback function from the HDLC module code in the example applications. The code illustrates the basic processing that must be done for the various SI callback messages. The function calls made in this example are described in Appendix.

```
//-----
// SI Control Function
void hdlcSI( HANDLE hSI, uint Msq, UINT32 Aux, PBM Handle hPkt )
   HDLC_INSTANCE *pi = (HDLC_INSTANCE *)hSI;
   HANDLE hTmp;
   uint
               Offset,Size;
   UINT8
               *pBuf;
   switch(Msg)
   {
   case SI MSG CALLSTATUS:
       // Update Connection Status
       pi->Status = (uint)Aux;
       if( Aux >= SI_CSTATUS_DISCONNECT )
          // Close PPP
          if( pi->hPPP )
          {
              hTmp = pi->hPPP;
              pi->hPPP = 0;
              pppFree( hTmp );
       break;
   case SI_MSG_PEERCMAP:
       // Update Out CMAP for Transmit
       pi->cmap_out = Aux;
       llSerialHDLCPeerMap( pi->DevSerial, Aux );
      break;
   case SI_MSG_SENDPACKET:
       if(!hPkt)
```



```
DbgPrintf( DBG_ERROR, "hdlcSI: No packet" );
            break;
        }
        Offset = PBM_getDataOffset( hPkt );
        Size = PBM_getValidLen( hPkt );
        // Make sure packet is valid, with room for protocol, room for checksum
        if((Offset<4) | ((Offset+Size+2)>PBM_getBufferLen(hPkt)))
            DbgPrintf( DBG ERROR, "hdlcSI: Bad packet" );
            PBM_free( hPkt );
            break;
        }
        // Add in 2 byte Protocol and 2 byte header. Also add in size for
        // 2 byte checksum. Note that the outgoing checksum is corrected
        // (calculated) by the serial driver.
        Offset -= 4;
        Size += 6;
        PBM_setDataOffset(hPkt, Offset);
        PBM_setValidLen(hPkt, Size);
        pBuf = PBM_getDataBuffer(hPkt)+Offset;
        *pBuf++ = 0xFF;
        *pBuf++ = 0x03;
        *pBuf++ = (UINT8)(Aux/256);
        *pBuf = (UINT8)(Aux%256);
        // Send the buffer to the serial driver
        llSerialSendPkt(pi->DevSerial, hPkt);
        break;
    }
}
```

C.1.5 Tips for Implementing a PPP Serial Interface (SI) Module Instance

C.1.5.1 Multiple Instances

PPP supports multiple instances, but the SI module implementation tracks multiple instances of itself. This is done in two ways. One method is for the SI module to have a locally global head pointer to its first instance, and an array or linked list for additional instances. Or, the instance can be bound to the next layer down. In the case of the HDLC module, one PPP instance is bound to one serial port driver instance. So the HDLC module does not need to track instances independently.

When a new PPP connection is established, a new SI module instance should be allocated and a handle to the new SI instance is passed to the *pppNew()* function. The handle that *pppNew()* returns must be associated with the handle to the SI instance. The PPP handle must be passed to all other PPP API functions, and PPP will pass back the SI instance handle to the SI callback function.

When new data arrives from the hardware, it is the responsibility of the SI module to associate that data with a specific SI instance. The SI instance can then be accessed to retrieve the handle to the PPP instance to use with any PPP function calls. In the case of HDLC, the SI instance is known because it is associated with a particular serial device instance.

C.1.5.2 Using the Timer Object

PPP requires that its *pppTimer()* function be called once every second. This can be PRD driven if necessary, but the timer callback cannot be called from a PRD because it must be called from within kernel mode (an *llEnter()/llExit()*) pairing.



C.1.5.3 Registering Packet Padding Requirements

Although a serial interface will probably not have any special requirements for packets from the stack, it must at least be able to construct valid packets to send to the *pppInput()* function. To use the packet allocation function provided by the IF API (see Appendix), the SI module should declare its padding requirements via the *IFSetPad()* function. For a serial interface that does not use the packet buffer to physically send the packet, the size of the PPP header would be 4 bytes (2 byte HDLC header and 2 byte protocol field), and the padding would be 2 bytes (checksum).

C.1.6 PPP API Functions

The following is the full description of the PPP functions described in this section.

pppNew	Create a New PPP	Connection Instance

Syntax HANDLE pppNew(HANDLE hSI, uint pppFlags, uint mru, IPN IPServer, IPN IPMask, IPN

IPClient, char *Username, char *Password, UINT32 cmap, void (*pfnSICtrl)(HANDLE,

uint, UINT32, HANDLE));

Parameters

hSI Handle to SI module to be passed back to callback function

pppFlags Connection option flags

mru Maximum receive unit (maximum size of Payload)

IP address of server in server mode (NULL in client mode)
IPMask
IP subnet mask of client in server mode (NULL in client mode)
IPClient
IP address of client in server mode (NULL in client mode)
Username
Pointer to username in client mode (NULL in server mode)
Password
Pointer to password in client mode (NULL in server mode)

cmap 32-bit local CMAP to pass to peer pfnSICtrl Pointer to SI module callback function

Return Value

Handle to new PPP connection instance, or NULL on error.

Description

This function is called to create a new PPP connection instance. The type of connection created is determined by the calling parameters.

- hSI This is a private handle created by the caller that points back to the caller's
 instance data. It is passed back to the caller via the callback function pointed to by
 pfnSICtrl, and can be used to link back to caller's instance data when the callback is
 executed
- pppFlags The flags determine what type of connection instance to create, and what type of options to support in the connection instance. In the pppFlags parameter, one and only one of the following flags must be set:

PPPFLG_SERVER Create PPP server connection instance
PPPFLG_CLIENT Create PPP client connection instance



When operating in SERVER mode, any of the following flags can also be set:

PPPFLG_OPT_AUTH_PAP Require PAP authentication PPPFLG OPT AUTH CHAP Require CHAP authentication PPPFLG_OPT_USE_MSE Use MS extensions as server PPPFLG_OPT_LOCALDNS Claim Local IP as DNS server PPPFLG_SIOPT_SENDCMAP Send an async character map PPPFLG_SIOPT_RECVCMAP Accept an async character map PPPFLG CH1 Allow server channel/group 1 account users PPPFLG CH2 Allow server channel/group 2 account users PPPFLG CH3 Allow server channel/group 3 account users PPPFLG_CH4 Allow server channel/group 4 account users PPPFLG OPT ALLOW IP Allow client to declare its own IP address PPPFLG OPT ALLOW HC Allow peer to negotiate PFC/ACFP

When operating in CLIENT mode, any of the following flags can also be set:

PPPFLG_OPT_USE_MSE	Use MS extensions as client
PPPFLG_OPT_CLIENT_P2P	Treat the connection as a pure peer to peer (i.e., do not create a default route using the peer as a gateway)
PPPFLG_SIOPT_SENDCMAP	Send an async character map
DDDELO CIODE DECVOMAD	A count on course observation many

PPPFLG_SIOPT_RECVCMAP

PPPFLG_OPT_ALLOW_HC

Accept an async character map

Allow peer to negotiate PFC/ACFP

- mru The MRU is maximum receive unit, or the maximum size of the payload portion
 of a PPP packet. For a standard serial link, the MRU is typically 1500, but can be
 smaller.
- IPServer When creating the PPP instance in SERVER mode, this is the IP address
 in network format of the NDK reported to the peer. When operating in CLIENT mode,
 this value is NULL.
- IPMask When creating the PPP instance in SERVER mode, this is the IP subnet
 mask of the peer's IP network reported to the peer. When operating in CLIENT mode,
 this value is NULL.
- *IPClient* When creating the PPP instance in SERVER mode, this is the IP address in network format of the peer reported to the peer. When operating in CLIENT mode, this value is NULL.
- Username When creating the PPP instance in CLIENT mode, this is a pointer to a NULL terminated string containing the username to use in PAP or CHAP authentication. The maximum string length is defined by PPPNAMELEN. When operating in SERVER mode, this value is NULL.
- Password When creating the PPP instance in CLIENT mode, this is a pointer to a NULL terminated string containing the password to use in PAP or CHAP authentication. The maximum string length is defined by PPPNAMELEN. When operating in SERVER mode, this value is NULL.
- cmap When the PPPFLG_SIOPT_SENDCMAP flag is set in the pppFlags parameter, this is the CMAP value that is sent to the peer; otherwise it is NULL.
- pfnSICtrl This is a required pointer to the caller's callback function to handle status
 updates from the stack, and requests to transmit PPP packets. See Section C.1.4 for
 more detail.



When run in SERVER mode, the name of the PPP server defaults to DSPIP in CHAP authentication; however, this can be changed by using the

CFGITEM_SYSINFO_REALMPPP configuration tag. For example:

When successful, this function returns a handle to a new PPP instance. This handle is used by the caller when calling other functions in the PPP API.

pppFree Destroy PPP Connection Instance

Syntax void pppFree(HANDLE hPPP);

Parameters

hPPP Handle to PPP instance created with pppNew()

Return Value None.

Description This function is called to close and destroy a PPP connection instance created with

pppNew(). This function must be called to free the PPP handle, even if the PPP

connection itself is already disconnected.

pppInput Send a PPP Packet to PPP for Processing

Syntax void pppInput(HANDLE hPPP, PBM_Pkt *pPkt);

Parameters

hPPP Handle to PPP instance created with *pppNew()*

pPkt Pointer to a PBM packet

Return Value None.

Description This function is called when a PPP packet is received on a active serial interface. The

packet is data decoded into the PPP protocol and payload fields, and given to PPP as a packet object. The handle *hPPP* is the PPP connection instance returned from *pppNew()* for this connection, and *pPkt* is a packet object created by the packet buffer manager

(PBM).

pppTimer Notify PPP of One Second Tick

Syntax void pppTimer(HANDLE hPPP);

Parameters

hPPP Handle to PPP instance created with pppNew()

Return Value None.

Description This function is called on an active PPP instance to notify PPP that one second has

elapsed. Because the PPP API is entirely stateless, it relies on the serial interface for

time tick notification.



C.2 Serial HDLC Client and Server Support

This implementation of HDLC for the NDK library is included in the example applications. It interfaces to the serial port driver described in the HAL.

NOTE: The HDLC API is user-callable. Unlike the low level PPP support API, you should not use the IIEnter()/IIExit() functions when calling the functions described in this section.

C.2.1 Function Overview

Called by Application:

Create a Serial HDLC Client Session hdlcNew() Destroy a Serial HDLC Client Session hdlcFree()

hdlcGetStatus() Get the Call Status of a Serial HDLC Client Session

Create a Serial HDLC Server Session hdlcsNew() hdlcsFree() Destroy a Serial HDLC Server Session

Get the Call Status of a Server HDLC Client Session hdlcsGetStatus()

Called by Serial Port Driver:

hdlcInput() Send HDLC input buffer for processing

C.2.2 HDLC API Functions

hdlcNew Create a Serial HDLC Client Session

HANDLE hdlcNew(uint Dev, uint pppFlags, UINT32 cmap, char *Username, char **Syntax**

*Password);

Parameters

Dev Physical index of serial port to use

Connection option flags pppFlags Async control character map cmap Pointer to client account username Username Password Pointer to client account password

Return Value If it succeeds, the function returns a handle to a HDLC client instance. Otherwise, it

returns NULL.

Description This function is called to create a new serial HDLC client instance on the physical serial

interface specified by the index Dev.

pppFlags - The flags determine what type of connection instance to create, and what type of options to support in the connection instance. In the pppFlags parameter, the following flag must be set:

Create PPP client connection instance PPPFLG_CLIENT

In addition, any of the following flags can also be set:

PPPFLG OPT USE MSE Use MS extensions as client

PPPFLG OPT CLIENT P2P Treat the connection as a pure peer to peer (i.e.,

don't create a default route using the peer as a

gateway).



PPPFLG_SIOPT_SENDCMAP Send an async character map (strongly

recommended)

PPPFLG_SIOPT_RECVCMAP Accept an async character map (strongly

recommended)

PPPFLG_OPT_ALLOW_HC Allow peer to negotiate PFC/ACFP

- cmap This is the desired value of the async character control map that is sent to the
 peer to allow frame compression by skipping the escape coding of characters when it
 is not required. The mask contains a set bit for each character (0 to 31) that must be
 escaped when sent by the peer. If the PPPFLG_SIOPT_SENDCMAP option is not
 set, it is assumed that all 32 characters must be sent via the escape sequence.
- Username This is a pointer to a NULL terminated string containing the username to use in PAP or CHAP authentication. The maximum string length is defined by PPPNAMELEN.
- Password This is a pointer to a NULL terminated string containing the password to
 use in PAP or CHAP authentication. The maximum string length is defined by
 PPPNAMELEN.

When successful, this function returns a handle to a new serial HDLC instance. The current status of the connection can be queried at any time by calling hdlcGetStatus().

hdlcFree Destroy a Serial HDLC Client Session

Syntax void hdlcFree(HANDLE hHDLC);

Parameters

hHDLC Handle to HDLC Client Session

Return Value None.

Description This function is called to close and destroy a serial HDLC client session that was created

with *hdlcNew()*. This function is always called once for every HDLC instance handle. If the connection is no longer active, it frees the instance memory. If the connection is still

active, it disconnects the call first.

hdlcGetStatus Get the Status of a Serial HDLC Client Session

Syntax uint hdlcGetStatus(HANDLE hHDLC);

Parameters

hHDLC Handle to HDLC Client Session

Return Value This function returns a uint that will be set to one of the following values:

SI_CSTATUS_WAITING Connection is idle (HDLC session opening)
SI_CSTATUS_NEGOTIATE Connection in LCP negotiation stage
SI_CSTATUS_AUTHORIZE Connection in authorization stage

SI_CSTATUS_CONFIGURE Connection in IP configuration stage

SI_CSTATUS_CONNECTED Connection is fully connected and operational

SI CSTATUS DISCONNECT Connection dropped

SI_CSTATUS_DISCONNECT_LCP Connection dropped in LCP stage

SI_CSTATUS_DISCONNECT_AUTH Connection dropped in authorization stage
SI_CSTATUS_DISCONNECT_IPCP Connection dropped in IP configuration stage



Description This function is called to get the connection status of a serial HDLC client session using

the HDLC instance handle returned from *hdlcNew()*. This function can be called anytime after the handle is created with *hdlcNew()*, and before it is destroyed with *hdlcFree()*.

hdlcsNew Create a Serial HDLC Server Session

Syntax HANDLE hdlcsNew(uint Dev, uint pppFlags, UINT32 cmap, IPN IPServer, IPN IPMask,

IPN IPClient);

Parameters

Dev Physical index of serial port to use

pppFlags Connection option flags cmap Async control character map

IPServer IP address of server in network format

IP subnet mask in network format of the peer's network

IPClient IP address in network format of the client

Return Value If it succeeds, the function returns a handle to a serial HDLC server instance. Otherwise,

it returns NULL.

DescriptionThis function is called to create a new serial HDLC server instance on the physical serial

interface specified by the index Dev.

 pppFlags - The flags determine what type of connection instance to create, and what type of options to support in the connection instance. In the pppFlags parameter, the

following flag must be set:

PPPFLG SERVER Create PPP server connection instance

In addition, any of the following flags can also be set:

PPPFLG_OPT_AUTH_PAP Require PAP authentication

PPPFLG_OPT_AUTH_CHAP Require CHAP authentication (PAP is fallback when

specified)

PPPFLG OPT USE MSE Use MS extensions as server

PPPFLG_SIOPT_SENDCMAP Send an async character map (strongly

recommended)

PPPFLG_SIOPT_RECVCMAP Accept an async character map (strongly

recommended)

PPPFLG_CH1 Allow server channel/group 1 account users
PPPFLG_CH2 Allow server channel/group 2 account users
PPPFLG_CH3 Allow server channel/group 3 account users
PPPFLG_CH4 Allow server channel/group 4 account users
PPPFLG_OPT_ALLOW_IP Allow client to declare its own IP address
PPPFLG_OPT_ALLOW_HC Allow peer to negotiate PFC/ACFP

- cmap This is the desired value of the async character control map that is sent to the
 peer to allow frame compression by skipping the escape coding of characters when it
 is not required. The mask contains a set bit for each character (0 to 31) that must be
 escaped when sent by the peer. If the PPPFLG_SIOPT_SENDCMAP option is not
 set, it is assumed that all 32 characters must be sent via the escape sequence.
- IPServer This is the IP address in network format of the NDK reported to the peer.
- IPMask This is the IP subnet mask of the peer's IP network reported to the peer.



 IPClient - This is the IP base address in network format of the IP address to be assigned to the client.

When successful, this function returns a handle to a new serial HDLC server instance. The current status of the connection can be queried at any time by calling *hdlcsGetStatus()*.

The name of the PPP server defaults to DSPIP in CHAP authentication; however, this can be changed by using the CFGITEM_SYSINFO_REALMPPP configuration tag. For example:

hdlcsFree Destroy a Serial HDLC Server Session

Syntax void hdlcsFree(HANDLE hHDLC);

Parameters

hHDLC Handle to HDLC Server Session

Return Value None.

Description This function is called to close and destroy a serial HDLC server session that was

created with *hdlcsNew()*. This function is always called once for every HDLC instance handle. If the connection is no longer active, it frees the instance memory. If the

connection is still active, it disconnects the call first.

hdlcsGetStatus Get the Status of a Serial HDLC Server Session

Syntax uint hdlcsGetStatus(HANDLE hHDLC);

Parameters

hHDLC HDLC Server Session

Return Value This function returns a uint that will be set to one of the following values:

SI_CSTATUS_WAITING Connection is idle (PPPoE session opening)
SI_CSTATUS_NEGOTIATE Connection in LCP negotiation stage
SI_CSTATUS_AUTHORIZE Connection in authorization stage

SI_CSTATUS_CONFIGURE Connection in IP configuration stage
SI_CSTATUS_CONNECTED Connection is fully connected and operational

SI CSTATUS DISCONNECT Connection dropped

SI_CSTATUS_DISCONNECT_LCP Connection dropped in LCP stage

SI_CSTATUS_DISCONNECT_AUTH Connection dropped in authorization stage SI_CSTATUS_DISCONNECT_IPCP Connection dropped in IP configuration stage



Description

This function is called to get the connection status of a serial HDLC server session using the HDLC instance handle returned from hdlcsNew(). This function can be called anytime after the handle is created with hdlcsNew(), and before it is destroyed with hdlcsFree().

C.3 PPPoE Client and Server Support

The PPPoE (PPP over Ethernet) specification allows for PPP packets to be transmitted in a peer to peer method over an Ethernet tunnel. The standard has gained in popularity because it allows for the use of multiple user accounts on a single Ethernet network.

The implementation of PPPoE supplied in the NDK library is built into the stack library code, and linked to the Ether object that handles packets from all Ethernet devices in the HAL layer. Thus, is it not necessary to access or alter the HAL to use PPPoE.

The software can be used as a PPP server or PPP client, but not both simultaneously. In both cases, PPPoE uses the the PPP programming interfaces described earlier in this section. Thus, for server mode, the PPP server will use the same user account information as a serial based server.

NOTE: The PPPoE API is user callable. Unlike the low level PPP support API, you should not use the *llEnter()/llExit()* functions when calling the functions described in this section.

C.3.1 Function Overview

The PPPoE function API is short:

Create a PPPoE Client Session pppoeNew() Destroy a PPPoE Client Session pppoeFree()

pppoeGetStatus() Get the Call Status of a PPPoE Client Session

pppoesNew() Create a PPPoE Server Session Terminate a PPPoE Server Session pppoesFree()

C.3.2 PPPoE API Functions

pppoeNew	Create a PPPoE Client Session
----------	-------------------------------

HANDLE pppoeNew(HANDLE hEther, uint pppFlags, INT8 *Username, INT8 **Syntax**

*Password);

Parameters

Handle to Ether device on which to look for a PPPoE server hEther

Connection option flags pppFlags

Username Pointer to client account username Password Pointer to client account password

If it succeeds, the function returns a handle to a PPPoE client instance. Otherwise, it Return Value

returns NULL.

Description This function is called to create a new PPPoE client instance on the Ether type interface specified by the handle hEther.

> pppFlags - The flags determine what type of connection instance to create, and what type of options to support in the connection instance. In the pppFlags parameter, the following flag must be set:



PPPFLG_CLIENT Create PPP client connection instance

In addition, any of the following flags can also be set:

PPPFLG OPT CLIENT P2P Treat the connection as a pure peer to peer (i.e., do not

create a default route using the peer as a gateway)

PPPFLG_OPT_ALLOW_HC Allow peer to negotiate PFC/ACFP

 Username - This is a pointer to a NULL terminated string containing the username to use in PAP or CHAP authentication. The maximum string length is defined by PPPNAMELEN.

Password - This is a pointer to a NULL terminated string containing the password to
use in PAP or CHAP authentication. The maximum string length is defined by
PPPNAMELEN.

When successful, this function returns a handle to a new PPPoE instance The current status of the PPPoE connection can be queried at any time by calling pppoeGetStatus().

pppoeFree Destroy a PPPoE Client Session

Syntax void pppoeFree(HANDLE hPPPOE);

Parameters

hPPPOE Handle to PPPoE Client Session

Return Value None.

DescriptionThis function is called to close and destroy a PPPoE client session that was created with

pppoeNew(). This function is always called once for every PPPoE instance handle. If the connection is no longer active, it frees the instance memory. If the connection is still

active, it first disconnects the call.

pppoeGetStatus Get the Status of a PPPoE Client Session

Syntax uint pppoeGetStatus(HANDLE hPPPOE);

Parameters

hPPPOE Handle to PPPoE Client Session

Return ValueThis function returns a uint that will be set to one of the following values:

SI CSTATUS WAITING Connection is idle (PPPoE session opening)

SI_CSTATUS_NEGOTIATE Connection in LCP negotiation stage
SI_CSTATUS_AUTHORIZE Connection in authorization stage
SI_CSTATUS_CONFIGURE Connection in IP configuration stage

SI_CSTATUS_CONNECTED Connection is fully connected and operational

SI_CSTATUS_DISCONNECT Connection dropped

SI_CSTATUS_DISCONNECT_LCP Connection dropped in LCP stage

SI_CSTATUS_DISCONNECT_AUTH Connection dropped in authorization stage SI_CSTATUS_DISCONNECT_IPCP Connection dropped in IP configuration stage



Description

This function is called to get the connection status of a PPPoE client session using the PPPoE instance handle returned from *pppoeNew()*. This function can be called anytime after the handle is created with *pppoeNew()*, and before it is destroyed with *pppoeFree()*.

pppoesNew

Create a PPPoE Server Session

Syntax

HANDLE pppoesNew(HANDLE hEther, uint pppFlags, uint SessionMax, IPN IPServer, IPN IPMask, IPN IPClientBase, INT8 *ServerName, INT8 *ServiceName);

Parameters

hEther Handle to Ether device on which to invoke the PPPoE server

pppFlags Connection option flags

SessionMax Maximum number of client connections allowed

IPServer IP address of server in network format

IPMask IP subnet mask in network format of the client address pool IPClientBase IP base address in network format of the client address pool

ServerName Server name reported via PPPoE protocol ServiceName Service name reported via PPPoE protocol

Return Value

If it succeeds, the function returns a handle to a PPPoE server instance. Otherwise, it returns NULL.

Description

This function is called to create a new PPPoE server instance on the Ether type interface specified by the handle *hEther*.

- SessionMax This value is the maximum number of simultaneous peer connections
 to be allowed at any given time. Thus, it is also the minimum size of the client IP
 address pool.
- pppFlags The flags determine what type of connection instance to create, and what type of options to support in the connection instance. In the pppFlags parameter, the following flag must be set:

PPPFLG SERVER

Create PPP server connection instance

In addition, any of the following flags can also be set:

PPPFLG_OPT_AUTH_PAP	Require PAP authentication
PPPFLG_OPT_AUTH_CHAP	Require CHAP authentication
PPPFLG_OPT_USE_MSE	Use MS extensions as server
PPPFLG_OPT_LOCALDNS	Claim Local IP as DNS server
PPPFLG_CH1	Allow server channel/group 1 ac

PPPFLG_CH1 Allow server channel/group 1 account users
PPPFLG_CH2 Allow server channel/group 2 account users
PPPFLG_CH3 Allow server channel/group 3 account users
PPPFLG_CH4 Allow server channel/group 4 account users
PPPFLG_OPT_ALLOW_IP Allow client to declare its own IP address
PPPFLG_OPT_ALLOW_HC Allow peer to negotiate PFC/ACFP

- IPServer This is the IP address in network format of the NDK reported to the peer.
- *IPMask* This is the IP subnet mask of the peer's IP network reported to the peer.
- IPClientBase This is the IP base address in network format of the IP address pool
 to be assigned to and reported to peer connections. The size of the address pool is
 determined by the value of SessionMax.
- ServerName This is a required pointer to a NULL terminated string containing the



server name that is reported to PPPoE clients. The maximum length of this name including the NULL terminator is defined by PPPOE_NAMESIZE. If a longer name is supplied, this function will fail.

 ServiceName - This is a required pointer to a NULL terminated string containing the service name that is reported to PPPoE clients. The maximum length of this name, including the NULL terminator, is defined by PPPOE_NAMESIZE. If a longer name is supplied, this function will fail.

The name of the PPP server defaults to DSPIP in CHAP authentication. This is independent of the PPPoE server name. However, the name can be changed by using the CFGITEM_SYSINFO_REALMPPP configuration tag. For example:

When successful, this function returns a handle to a new PPPoE server instance. The status of individual connections is not available to the caller, but tracked automatically by PPPoE. When sessions are added or destroyed, the IP address callback supplied to NC_NetStart() is called and connections can be tracked by the applications programmer via this function callback.

pppoesFree Destroy a PPPoE Server Session

Syntax void pppoesFree(HANDLE hPPPOES);

Parameters

hPPPOES Handle to PPPoE Server Session

Return Value None.

Description This function is called to close and destroy a PPPoE server session that was created with papers New(). This function is always called once to shut down the PPPoE server

with pppoesNew(). This function is always called once to shut down the PPPoE server.

Any external client currently connected to the server is disconnected.

C.4 Creating PPP Server User Accounts

To use the PPP or PPPoE protocol in server mode, it advisable to protect access to the system through the use of a PPP authentication protocol. The PPP supplied in the stack library allows for the use of either PAP or CHAP in user authentication. The database of authorized users (name and password) is stored in the configuration system.

C.4.1 Adding and Reviewing User Accounts

The definition of the user account entry in the configuration system is defined in Section G.3.6. Note in that section that the server channel flags PPPFLG_CH1 through PPPFLG_CH4 are duplicated in both the server flags and the client account flags. This allows the system programmer to allow different classes of services for different channels.

The methodology of adding, querying, and removing user accounts is the same for any other tag in the configuration system. Some simple examples follow. More example code can be found in the sample console program.



C.4.1.1 Adding a PPP User Account

The following code adds a PPP user account for the user supplied in *name* with a password supplied in *password*. Note that it also uses the *AcctFind()* function to verify that the account does not already exist.

```
void AcctAdd(char *name, char *password)
    CI_ACCT CA;
    HANDLE hAcct;
    int rc;
    // Check string lengths for name and password
    if(strlen(name) >= CFG_ACCTSTR_MAX | |
        strlen(password) >= CFG_ACCTSTR_MAX)
        printf("Name or password too long, %d character max\n\n",
                CFG_ACCTSTR_MAX-1);
    // See if the account already exists
    hAcct = AcctFind(tok2);
    if(hAcct)
    {
        printf("Account exits - remove old account first\n\n");
        // We must de-reference the account we found
        CfgEntryDeRef(hAcct);
        return;
    // Fill in the CA record
    strcpy(CA.Username, name);
    strcpy(CA.Password, password);
    // Give user access to all channels
    CA.Flags =
        CFG_ACCTFLG_CH1 | CFG_ACCTFLG_CH2 | CFG_ACCTFLG_CH3 | CFG_ACCTFLG_CH4;
    // Add it to the configuration
    rc = CfgAddEntry(0, CFGTAG_ACCT, CFGITEM_ACCT_PPP,
                     CFG_ADDMODE_NOSAVE, sizeof(CI_ACCT), (UINT8 *)&CA, 0);
    if(rc < 0)
       printf("Error adding account\n");
       printf("Account added\n");
    return;
}
```

C.4.1.2 Searching for a PPP User Account

The following code implements the AcctFind() function called in the previous example. Note that the same method could be used to print out a list of all accounts.

```
HANDLE AcctFind(char *name)
{
    HANDLE hAcct;
    CI_ACCT CA;
    int rc;
    int size;

    // Get the first user account
    rc = CfgGetEntry(0, CFGTAG_ACCT, CFGITEM_ACCT_PPP, 1, &hAcct);

    // If there are no accounts, then we did not find it
    if(rc <= 0)</pre>
```



```
return(0);
    // Search until we run out of accounts or have a match
    while(1)
        // Get the data for this entry into CA
        size = sizeof(CA);
        rc = CfgEntryGetData(hAcct, &size, (UINT8 *)&CA);
        if(rc <= 0)
            // This is an unexpected error - deref the handle and abort
            CfgEntryDeRef(hAcct);
            return(0);
        }
    // See if the username matches the search name. If so, return
    // the referenced handle
    if(!strcmp(name, CA.Username))
       return(hAcct);
    \ensuremath{//} Since we did not match, get the next entry. If there is no
    // next entry, we are done searching.
    rc = CfgGetNextEntry(0, hAcct, &hAcct);
    if(rc <= 0)
        return(0);
}
```

C.4.1.3 Removing a PPP User Account

Removing a specific user account is done by finding the account and removing the entry handle.

The following uses the AcctFind() function to find the target account.

```
void AcctDelete(char *name)
{
    HANDLE hAcct;

    // Find the account to delete
    hAcct = AcctFind(name);

    // If we found the account, remove it
    if(hAcct)
    {
        CfgRemoveEntry(0, hAcct);
        printf("Account removed\n");
    }
}
```



Hardware Adaptation Layer (HAL)

As discussed in the introduction, hardware devices are supported through a Hardware Adaptation Layer. This section describes the HAL API.

This section is required only for system programming that needs low level access to the hardware for configuration and monitoring. This API does not apply to sockets application programming.

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D.1 Overview

The function of the HAL is to provide resources to the stack library functions and allow them to operate independently of the current run-time environment. The HAL contains the functionality required by the stack that depends directly on the hardware in a particular environment.

D.1.1 HAL Function Types

The HAL is interspersed with two different types of functions; those that are called at kernel level (inside an <code>//Enter()/I/Exit()</code> pairing), and those that are not. (For more information on the <code>//Enter()</code> and <code>//Exit()</code> functions, see Section A.1.)

To distinguish kernel level functions from application support functions, both have been given a different naming conventions. Kernel level functions are named with an II prefix, without a leading underscore, for example: IPacketSend(), while application functions have an underscore, for example: IPacketInit().

D.1.2 External Calls from HAL Functions

Because HAL functions are called from the stack kernel, they are executing within an *IIEnter()/IIExit()* pair. These HAL functions can call the stack API directly, but should not call normal application functions.

If a HAL function must call an external application function, or if it is going to call a potentially blocking function, then it should first call <code>//Exit()</code>. Then, when it has completed, it should call <code>//Enter()</code> before returning to the stack. It is important not to block while in an <code>//Enter() / //Exit()</code> pair.

D.2 Low-Level LED Driver (IIUserLed)

The User LED driver is not really a driver at all. It is a collection of functions to control (ON|OFF|TOGGLE) LED lights on a given hardware platform.

D.2.1 Function Overview

Application Functions:

IIUserLedInit() Initialize the LED displays to their default state

IlUserLedShutdown() Shut down the LED environment

LED_ON() Turn on a LED LED OFF() Turn off a LED

LED_TOGGLE() Toggle the state of a LED



D.2.2 Low-Level LED API Functions

The following functions are required.

_IIUserLedInit Initialize the LED Displays to their Default State

Syntax void _ IlUserLedInit();

Return Value None.

Description This function initializes anything necessary to get the LED displays to their default state.

_IIUserLedShutdown Shutdown the LED Environment

Syntax void _IIUserLedShutdown();

Return Value None.

Description This function is called when shutting down the system to shut down and clean up the

LED environment. Typically, this is an empty function.

LED_ON Turn On an LED

Syntax void LED_ON(UINT32 ledId);

Description This function turns on the specified LED in the calling argument.

LED_OFF Turn Off an LED

Syntax void LED_OFF(UINT32 ledId);

Description This function turns off the LED specified in the calling argument.

LED_TOGGLE Toggle the State of an LED

Syntax void LED_TOGGLE(UINT32 ledId);

Description This function toggles the on/off state of an LED specified in the calling argument.



D.3 Low-Level Timer Driver (IITimer)

The stack code requires a very basic simple time function. It consists of two parts: a function API, which can be called from the stack to get the current time, and a scheduler that sends timer event notifications every 100ms using the STKEVENT event object.

D.3.1 Function Overview

Application Functions:

_IlTimerInit() Initialize Timer Environment
_IlTimerShutdown() Shutdown Timer Environment

Kernel Layer Functions:

IlTimerGetTime() Get the Current Time
IlTimerGetStartTime() Get the Initial Startup Time

D.3.2 Low-Level Timer API Functions

The following functions are required.

IITimerInit Initialize Timer Environment

Syntax void IITimerInit(STKEVENT Handle hEvent, UINT32 ctime);

Return Value None.

Description This function is called to initialize the timer environment, and to set the initial time. The

value of *ctime* is the number of seconds elapsed from a known reference. An initial value of zero is also acceptable. The stack software is only tracks relative time. Take care when setting this value because the stack does not manage the timer value wrapping.

This occurs every 136 years, or in 2116 if time is based off of Jan 1, 1980.

Every 100mS, the timer driver will indicate a timer event to the event object specified by

hEvent. This STKEVENT object is discussed in Section A.4.

IITimerShutdown Shutdown Timer Environment

Syntax void _IITimerShutdown();

Return Value None.

Description This function is called when shutting down the system, to shut down and clean up the

timer environment.



IlTimerGetTime Get Current Time in Seconds and Milliseconds

Syntax UINT32 IITimerGetTime(UINT32 *pMSFrac);

Description Returns the number of seconds that have elapsed since the timer driver was started. If

the pointer *pMSFrac* is non-zero, the function writes the fractional seconds (in

milliseconds) to this location (0 to 999).

NOTE: Although the stack does not require real time, do not simply use a

millisecond timer and divide by 1000, as the value will wrap every 50 days. Device drivers should attempt to provide a time value accurate

down to millisecond granularity.

IlTimerGetStartTime Get the Initial Startup Time

Syntax UINT32 IITimerGetStartTime();

Return Value Initial start time in seconds.

Description Returns the initial start time that was passed to _*IITimerOpen()*.

D.4 Low-Level Packet Driver (IIPacket)

The stack code requires a very basic packet function library. Note that although the high level packet API is documented here, the HAL contains a generic packet driver that implements this API. It is more efficient to use the standard IIPacket driver and provide a hardware specific mini-driver than to implement the IIPacket API from scratch. The IIPacket mini-driver is described in the support package documentation for your hardware platform (TMS320C6000 Network Developer's Kit (NDK) Support Package for DSK6455 User's Guide (SPRUES4) or TMS320C6000 Network Developer's Kit (NDK) Support Package for EVMDM642 User's Guide (SPRUES5)).

D.4.1 Function Overview

Application Functions:

_IIPacketInit() Initialize Driver Environment and Enumerate Devices

_IIPacketShutdown () Shutdown Driver Environment IIPacketServiceCheck() Check for Packet Activity

Kernel Layer Functions:

IlPacketOpen()
Open Driver and Bind Logical Ether Object to Device Id
IlPacketClose()
Close Driver and Unbind Logical Ether Object from Device Id

IIPacketSetRxFilter() Set Packet Receive Filter

IIPacketGetMacAddr() Get MAC address

IIPacketGetMCastMax() Get the Maximum Number of Multicast Addresses

IIPacketGetMCast()Get Multicast Address ListIIPacketSetMCast()Set Multicast Address ListIIPacketService()Service a Queued Packet

IIPacketSend() Send a Packet

IIPacketloctI() Execute Driver Specific IOCTL command.



D.4.2 Low-Level Packet API Functions

The low-level support layer must provide the following functions:

_IIPacketInit Initialize Driver Environment and Enumerate Devices

uint IIPacketInit(STKEVENT Handle hEvent); **Syntax**

Return Value Returns the number of physical packet devices.

Description This function is called by NETCTRL to initialize the packet driver environment. This

> function also enumerates all the physical packet devices in the system, and returns a device count. The stack will then call the IIPacketOpen() function once for each physical

device indicated.

The hEvent calling parameter is a handle to a STKEVENT object that must be signaled whenever a packet is received. This STKEVENT object is discussed in Section A.4.

IIPacketShutdown Shutdown Driver Environment

Syntax void IIPacketShutdown();

Return Value None.

This function is called by NETCTRL to indicate a final shutdown of the packet driver Description

environment. When called, there should be no currently open packet drivers, and

_IIPacketInit() will be called again before any call to IIPacketOpen().

_IIPacketServiceCheck Check for Ethernet Packet Activity

void _IIPacketServiceCheck(uint fTimerTick); **Syntax**

None. Return Value

This function is called by NETCTRL to check if packets are available from the Ethernet Description

device. In a polling system, this function is called continuously. In an interrupt driven semaphore system, it is called when packet activity is indicated via the STKEVENT object, and also by the scheduler at 100ms timer intervals for dead man polling checks.

In both polling and interrupt environments, the fTimerTick flag will be set whenever a

100ms timer tick has occurred.

If any new packets are detected from within this function, the packet driver should signal the STKEVENT object in the passive mode (do not set the fHwAsynch flag in the STKEVENT signal() function). This only applies to new packet events detected from within this function. The STKEVENT object is discussed in Section A.4.

IIPacketOpen Open Driver and Bind Logical Ether Object to Device ID

uint IIPacketOpen(uint dev, HANDLE hEther); **Syntax**

This function should return 1 on success, and 0 on failure. Return Value

Opens the low level packet driver specified by the one's based index dev. The maximum Description

value of dev is the number of devices returned from the IIPacketInit() function. When opening the device, the packet driver should bind the physical index with the logical Ether object handle specified in hEther. This handle is used in receive indications to the

stack.



IIPacketClose Close Driver and Unbind Logical Ether Object from Device ID

Syntax void IIPacketClose(uint dev);

Return Value None.

Description Closes the low level packet driver specified by the one's based index *dev*. The maximum

value of *dev* is the number of devices returned from the _*llPacketInit()* function. After this call, the packet driver should no longer attempt to indicate received packets to the stack.

IIPacketSetRxFilter Set Packet Receive Filter

Syntax void IIPacketSetRxFilter(uint dev, uint filter);

Return Value None.

Description Called to set the types of packets that should be received via the receive indication

function. Each level of filter is inclusive of the previous level. They are:

ETH_PKTFLT_NOTHING No Packets

ETH_PKTFLT_DIRECT Only directed Ethernet

ETH_PKTFLT_BROADCAST Directed plus Ethernet Broadcast

ETH PKTFLT MULTICAST Directed, Broadcast, and selected Ethernet Multicast

ETH PKTFLT ALLMULTICAST Directed, Broadcast, and all Multicast

ETH_PKTFLT_ALL All packets

IIPacketGetMacAddr Get MAC Address

Syntax void IIPacketGetMacAddr(uint dev, UINT8 *pbData);

Return Value None.

Description Copies the 6 byte MAC address of the physical device index *dev* into the supplied data

buffer.

IIPacketGetMCastMax Get the Maximum Number of Multicast Addresses

Syntax uint IIPacketGetMCastMax(uint dev);

Return Value The maximum number of 6 byte MAC addresses that can be supplied for

IIPacketSetMCast().

DescriptionCalled to get the maximum number of multicast addresses that can be supported on the

physical packet device.

IIPacketGetMCast Get Multicast Address List

Syntax uint IIPacketGetMCast(uint dev, uint maxaddr, UINT8 *pbAddr);

Return Value The number of 6 byte MAC addresses written to *pbAddr*.

Description Called to get the current list of multicast addresses installed on the physical device. The

maximum size of the list (supplied as an address count) is in *maxaddr*. The list is a contiguous stream of 6 byte addresses pointed to by *pbAddr*. The function returns the

number of addresses in the list supplied.



IIPacketSetMCast Set Multicast Address List

Syntax void IIPacketSetMCast(uint dev, uint addrcnt, UINT8 *pbAddr);

Return Value None.

Description Called to install a list of multicast addresses on the physical device. The size of the list

(supplied as an address count) is in *addrcnt*. The list is a contiguous stream of 6 byte addresses pointed to by *pbAddr*. The new list preempts any previously installed list, and

thus an address count of ZERO removes all multicast addresses.

IIPacketService Service a Queued Packet

Syntax void IIPacketService();

Description This function is called to inform the driver that it may now indicate any queued packet

buffers to the Ether object corresponding to the physical ingress device. Packet drivers must internally queue their own packets. Queued packets cause events to be sent to the

scheduler that will in turn call this function.

Packets are passed to the Ether object via EtherRxPacket().

IIPacketSend Send a Packet

Syntax void IIPacketSend(uint dev, PBM Handle hPkt);

Description Called to send a packet out the physical packet device indicated by *dev*. The information

about the packet (size and location) is contained in the PBM packet buffer specified by the handle *hPkt*. Once the packet has been sent, the packet buffer must be freed by

calling PBM_free().

The PBM packet buffer object is described in detail in Section A.3.

IIPacketloctl Execute Driver Specific IOCTL Command

Syntax uint IIPacketloctl(uint dev, uint cmd, void *arg);

Return Value This function returns 1 for success.

DescriptionCalled to execute the driver specific IOCTL command. For detailed information about the

set of commands specific to your device, check the NDK Support Package document of

your hardware platform.



D.5 Low-Level Serial Port Driver (IISerial)

In the current directory structure, the serial port driver (IISerial) may or may not be part of the HAL directory (as it is an optional component). However, it is part of the HAL architecture, and should be programmed using the same guidelines used for the IITimer and IIPacket drivers..

D.5.1 Function Overview

Application Functions:

IlSerialInit() Initialize Driver Environment and Enumerate Devices

_llSerialShutdown() Shutdown Driver Environment llSerialServiceCheck() Check for packet activity

IlSerialSend() Send Raw Data to the Serial Port

Kernel Layer Functions:

IISerialHDLCPeerMap() Update the HDLC encoding peer CMAP

IlSerialService() Service HDLC Packets
IlSerialSendPkt() Send a Serial Data Packet

D.5.2 Low-Level Serial API Functions

The low level support layer must provide the following functions:

llSerialInit	Initialize Driver Environment and Enumerate Devices	

Syntax uint _IISerialInit(STKEVENT_Handle hEvent);

Return Value Returns the number of physical serial devices.

Description This function is called by NETCTRL to initialize the system to use the serial port. It also

enumerates all the physical devices in the system, and returns a device count. The stack will then call the <code>IlSerialOpen()</code> function and/or the <code>IlSerialOpenHDLC()</code> function for each

physical device it requires.

The hEvent calling parameter is a handle to a STKEVENT object that must be signaled whenever a serial packet (or raw data) is received. This STKEVENT object is discussed

in Section A.4.

_IISerialShutdown Shutdown Driver Environment

Syntax void _llSerialShutdown();

Return Value None.

Description This function is called by NETCTRL to indicate a final shutdown of the serial driver

environment. When called, there should be no currently open serial drivers, and

_IISerialInit() will be called again before any call to IISerialOpen() or IISerialOpenHDLC().



_IISerialServiceCheck Check for Serial Port Activity

Syntax uint _IISerialServiceCheck(uint fTimerTick);

Return Value None.

Description T

This function is called by NETCTRL to check if serial packets (or data) are available from the serial device. In a polling system, this function is called continuously. In an interrupt driven semaphore system, it is called when packet activity is indicated via the STKEVENT object, and also by the scheduler at 100mS timer intervals for dead man polling checks.

In both polling and interrupt environments, the *fTimerTick* flag will be set whenever a 100mS timer tick has occurred.

If any *new* serial packets are detected from within this function, the packet driver should signal the STKEVENT object in the passive mode (do not set the *fHwAsynch* flag in the *STKEVENT_signal()* function). This only applies to new packet events detected from within this function. The STKEVENT object is discussed in Section A.4.

Finally, if the driver is only open in character mode (not HDLC), and there are characters for the character mode device waiting, they are passed into the user application from this function by calling character mode input callback function passed to <code>IlSerialOpen()</code>.

IISerialSend

Send Raw Data to the Serial Port

Syntax uint _IISerialSend(uint dev, UINT8 *pBuf, uint len);

Return Value The number of bytes sent to the serial port.

Description

This function is called by the application to send raw unpacketized serial data to the serial port. This function may only be called when the serial driver is not open for HDLC mode. The function returns the number of bytes sent, which will always be either the number of bytes it was told to send specified by the *len* parameter, or NULL on an error.

Note that this function is provided mainly for convenience to the application programmer. The implementation of this function is to packetize the data specified in the *pBuf* and *len* parameters into a PBM buffer, and then call *SerialSendPkt()*.

IISerialOpen

Open Driver in Character Mode

Syntax

uint IISerialOpenCharmode(uint dev, void (*pCharmodeRxCb)(char c));

Return Value

This function should return 1 on success, and 0 on failure.

Description

Opens the low level serial driver specified by the one's based index *dev* in character mode. The maximum value of *dev* is the number of devices returned from the _*IISerialInit()* function.

Character mode input simply passes all characters received at the port to the character mode receiver.

When opening the device, the driver should save the callback function pointer *pCharmodeRxCb*. This function is called for each character received while in character mode when the *_IlSerialServiceCheck()* function is called. Serial drivers queue up serial data, signaling an event to the STKEVENT object passed to *_IlSerialInit()*, and then pass the serial data to the application callback function from within the *_IlSerialServiceCheck()* function.

When the driver is opened in HDLC mode, no character mode input is received. When the HDLC mode is closed, the character mode becomes active again.



IISerialClose Close Driver Character Mode

Syntax void IISerialClose(uint dev);

Return Value None.

Description Closes the character mode of the low level serial driver specified by the one's based

index dev. Once called, the serial driver should not attempt to call any character mode

callback function.

IISerialOpenHDLC Open Driver HDLC Session

Syntax uint IISerialOpenHDLC(uint dev, HANDLE hHDLC, void (*cbTimer)(HANDLE h), void

(*cbHDLCInput)(PBM_Handle hPkt));

Return Value This function should return 1 on success, and 0 on failure.

Description Opens the low level serial driver specified by the one's based index *dev* in HDLC mode.

The maximum value of *dev* is the number of devices returned from the _*IISerialInit()*

function.

The hHDLC parameter is a handle to the HDLC device. Any HDLC packet received has

its Rx interface in the PBM packet buffer set to this device handle.

The callback function *cbTimer* is called by the driver every second to drive any timeouts

required by the caller. Note the serial driver calls *cbTimer* from kernel mode.

Serial drivers queue up HDLC packets. When a complete HDLC packet is ready, the driver signals an event to the STKEVENT object passed to _IlSerialInit(), and then passes the HDLC packet (as a PBM packet buffer) to the application callback function

cbHDLCInput from within the IISerialService() function.

This is similar to character mode operation, but different because the entire packet is passed over at one time, and it is done from the *IlSerialService()* function, not from *_IlSerialServiceCheck()* as with character mode data. The *cbHDLCInput* function is called from kernel mode while the character mode application callback is not.

When the driver is in HDLC mode, the driver receives serial data as HDLC packets, and creates a PBM packet buffer object to hold each HDLC frame. Note that the HDLC flag character (0x7E) is always removed from the HDLC packets. The HDLC packet passed to the *cbHDLCInput* function is formatted as follows:

Addr (FF)	Control (03)	Protocol	Payload	CRC
1	1	2	1500	2

The serial driver processes the HDLC packet data as it arrives to remove any escaped characters and to verify the CRC. When a HDLC packet is ready, the driver signals an event to the STKEVENT object.

IISerialCloseHDLC Close Driver HDLC Session

Syntax void IISerialCloseHDLC(uint dev);

Return Value None.

Description Closes the HDLC mode of the low level serial driver specified by the one's based index

dev. Once called, the serial driver should not attempt to indicate HDLC frame buffers to

the scheduler or stack. Any queued buffers should be flushed.



IISerialConfig Configure Serial Port

Syntax void IlSerialConfig(uint dev, uint baud, uint mode, uint flowctrl);

Return Value None.

Description This function is called to configure the serial port attributes for the indicated device.

The value of *baud* is the baud rate, and must be an even denominator of 230400, up to a maximum baud rate of 230400. For example: 230400, 115200, 57600, 38400, 28800,

and 19200 are all legal values, while 56000 is not.

The value of mode indicates the mode of the device including data bits, parity, and stop

bits. Only the two most commonly used modes are defined:

HAL_SERIAL_MODE_8N1 8 Data Bits, No Parity, 1 Stop Bit HAL_SERIAL_MODE_7E1 7 Data Bits, Even Parity, 1 Stop Bit

The value of flowctrl indicates the desired flow control operation. Legal values for this

parameter are:

HAL_SERIAL_FLOWCTRL_NONE No Flow Control

HAL_SERIAL_FLOWCTRL_HARDWARE Hardware Flow Control

This function can be called before or after the device is opened.

IISerialHDLCPeerMap Update the HDLC Encoding Peer CMAP

Syntax void IISerialHDLCPeerMap(uint dev, UINT32 peerMap);

Return Value None.

Description When in HDLC mode, the serial driver sends all serial data as HDLC frames. This

requires it to add the frame flag characters, and do any character escaping necessary to encode the frame for transmission over the serial link. This includes escaping characters

that appear in the peer's character map (CMAP).

By default, the CMAP is set to 0xFFFFFFF. For character codes 0 to 31, if the bit (1<<charval) is set in the CMAP, then the serial driver performs an HDLC escape

sequence when sending the character in an HDLC frame.

This function allows the application to update the peer's CMAP as it gets information

from the peer allowing it to do so.

IISerialService Service HDLC Packets

Syntax void IISerialService();

Return Value None.

Description This function is called to inform the driver that it may now indicate any queued HDLC

buffers to the HDLC callback function corresponding to the serial port. Serial drivers internally queue a PBM packet buffer for each HDLC frame received. When a new packet is received, the driver signals the STKEVENT object, which will cause this

function to be called by the network scheduler.



IISerialSendPkt Send a Serial Data Packet

Syntax void IISerialSendPkt(uint dev, PBM_Handle hPkt);

Return Value None.

Description Called to send a serial data packet out the physical serial device indicated by *dev*. The

information about the packet (size and location) is contained in the PBM packet buffer specified by the handle hPkt. Once the packet has been sent, the packet buffer must be

freed by calling PBM_free().

The data is treated as raw bytes when the driver is not open in HDLC mode. When in

HDLC mode, the data packet is an HDLC frame with the following format:

Addr (FF)	Control (03)	Protocol	Payload	CRC	
1	1	2	1500	2	

Note that the CRC on the packet does not need to be valid. The serial port driver will validate the CRC when the packet is sent. However, the 2 byte space-holder for the CRC must be present in the packet.



Web Programming with the HTTP Server

The easiest way to get information from an embedded network device is through the web server. The HTTP server pulls files from the embedded file system (EFS) that is included in the NDK software package's OS adaptation layer. These files can be compiled into the application, located on a network file system, a memory-based file system, or on a physical disk interfaced to the DSP. The NDK HTTP server accesses files through the EFS application interface, which can be ported to any file system desired. The server currently supports the HTTP/1.0 protocol.

Common Gateway Interface (CGI) programs execute on a web server and process input from a user. They are useful as interfaces to services running on the device. Writing CGI programs for the NDK is relatively simple and only requires a few specific functions. A single CGI interface function can be written to support both HTTP POST requests and GET requests.

The CGI program is built from a single C callable entry-point (or CGI function). Each CGI function is called on its own independent task thread. The task threads are created with a priority of OS_TASKPRINORM and a stack size of OS_TASKSTKHIGH. Note that consecutive calls to the same CGI function will not be on the same task thread. Thus, CGI functions cannot share sockets from one call to the next. In general, there is no persistent data in a CGI function.

Also, file detection of CGI functions is done purely on the file extension. If the file ends with .cfg (case insensitive), then a POST or a GET of the file will result in a call to the CGI function mapped to that filename. A POST call to a non-CGI file is not allowed.

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Adding Web Content www.ti.com

E.1 Adding Web Content

E.1.1 Operation

As previously mentioned, the HTTP server allows access to files using the embedded file system (EFS) API. The default installation of this API is a RAM based file system that resides in the OS adaptation layer. This OS adaptation layer allows the HTTP server to work on any file storage device contained in the system.

The default RAM based file system is built up mainly from a standard file I/O API, with the addition of some private functions. These private functions allow files to be created and destroyed by passing in memory pointers to where they are stored. These functions are fully documented in Section 2.6.

E.1.2 Converting Standard HTML Files

The example code supplied with the NDK adds Web pages by converting them from binary HTML files into data arrays declared in C. An MS-DOS utility **binsrc** is supplied to allow conversion of files to a C array.

The calling format for binsrc is:

binsrc <input file name> <output file name> <identifier>

Parameters:

input file name File to be converted

identifier C name for data

For example, to convert an HTML file default.htm for use by EFS, the following command could be executed from the Windows command window:

```
binsrc default.htm default.c DEFAULT
```

The file default.c would contain the following:

E.1.3 Declaring HTML Files to EFS

Once the HTML file is converted to a memory image, the file is declared to the EFS file system by calling the function <code>efs_createfile()</code>. All the HTML files are typically created at the same time, during initialization, and before the HTTP server is actually invoked. In the example code, there are two functions used, <code>AddWebFiles()</code> and <code>RemoveWebFiles()</code>. These functions include all the code necessary to initialize and clean up the EFS file environment.

An example implementation of *AddWebFiles()* is shown below. Note the addition of two file creation calls. The first call to *efs_createfile()* creates the file declared in default.c as converted from the file default.htm. The second call creates a CGI file that is a C function entry-point. When a post is attempted to <code>sample.cqi</code>, the function *cqiSample()* is called.

```
// Include our externally converted pages
#pragma DATA_SECTION(DEFAULT, "HTMLDATA");
#include "default.c"

// Declare our CGI function entry point
static int cgiSample(SOCKET htmlSock, int ContentLength);

// Our function to initialize EFS with our Web files
void AddWebFiles(void)
{
    efs_createfile("index.html", DEFAULT_SIZE, DEFAULT);
    efs_createfile("sample.cgi", 0, (UINT8 *)cgiSample);
}
```



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Once the above code is run, the EFS system is ready for the HTTP server to serve up the content. Note the inclusion of the #pragma to place the converted Web page into a memory section named HTMLDATA. This allows the page to be placed out of the way by specifying the section's location in the linker command file.

E.1.4 Cleaning up HTML Files

Because the EFS system uses memory records to simulate file content from static data, the system should be flushed or cleaned when shutting down or rebooting. In the example code, the function *RemoveWebFiles()* is called when the EFS files are no longer required.

An implementation of RemoveWebFiles() that corresponds to the AddWebFiles() function shown above would be as follows:

```
void RemoveWebFiles(void)
{
    efs_destroyfile("sample.cgi");
    efs_destroyfile("index.html");
}
```

E.2 Writing CGI Functions

E.2.1 Adding Functions to the EFS

CGI programs must be in the EFS for the HTTP server to see them. An example of this was shown in the previous section by adding an entry for the file sample.cgi that translated into the C function *cgiSample()*. Whenever a POST is made to the file sample.cgi, the *cgiSample()* function is called.

E.2.2 CGI Function Declaration

The standard declaration for a CGI function in C is:

Function	CCI Eupotion Declaration
Function	CGI Function Declaration

Syntax static int cgiSample(SOCKET htmlSock, int ContentLength, char *pArgs);

Parameters

htmlSock The network socket on which the HTTP POST was issued ContentLength pArgs The size of the POST content waiting on socket htmlSock Pointer to NULL terminated arguments from a CGI 'GET'

Return Value All CGI functions return 1 if the input socket is left open, and 0 if it is closed or

transferred to another thread.

Description This function reads in the HTTP POST content from the socket *htmlSock*, and writes out

an HTML reply based on the function and the form content read. The size of the form

content is specified by ContentLength.

The CGI function must decide whether or not to close the socket on which the POST arrived. By default, the socket is normally left open, but in some cases may need to be closed. It is also possible that the CGI function may wish to take control of the socket

and close it at a later point in time.



The function must return either 0 or 1 to indicate the status of the socket *htmlSock*. If the socket is closed or passed on to another task, the function returns 0. If the socket is still active, the function returns 1.

When there is any doubt whether or not to close the socket, the socket is typically left open for the HTTP server to close when appropriate.

The *ContentLength* argument is the size of the CGI argument still to be read from the socket. On a CGI GET operation, the arguments have already been read from the socket and are passed as a NULL terminated string in the *pArgs* parameter. Note that in any given CGI call, either one or both of these parameters can be NULL. It is also possible for *pArgs* to point to a zero length string.

E.2.3 Parsing CGI Form Data

The first task a CGI function will most likely perform is to read the POST form data from the socket. This can be done easily because two of the calling arguments to the function are the socket to read and the size of the data. To remain reentrant, the CGI function should allocate its memory buffer to hold the form data.

After reading in the data from the socket, each form entry can be parsed from the from by using the supplied example function: *cgiParseVars()*. This function can be used to parse the NULL terminated option string that may also be passed to the CGI function. The formal definition of the function is shown below.

Note that this function replaces *parsePostVars()*,a similar function that was included in earlier versions of the NDK. The *parsePostVars()* function was not reentrant, and has been purged from the NDK release. The source code to *cgiParseVars()* is included in the example application code shipped with the stack.

cgiParseVars	Parse CGI Form POST Input
cyll alac vala	i ai se coi i oilli i os i lliput

Syntax char *cgiParseVars(char PostInput[], int *pParseIndex);

Parameters

PostInput[] Pointer to the form data read in from the HTTP request socket pParseIndex Pointer to an int holding the current parse position (initially zero)

Return Value

A pointer to a NULL terminated string within *PostInput[]*, signifying the name or value of a form entry. Also updates the value pointed to by *pParseIndex*.

Description

Reads input from a CGI POST operation pointed to by *PostInput[]* at an offset pointed to by *pParseIndex* and returns in sequence a pointer to the name and then the value of each post entry. This function modifies the data in *PostInput[]*. It also updates the current parsing position in the variable *pParseIndex*. The parse index must be set to 0 on initial call.

On the initial call to this function, the integer value pointed to by *pParseIndex* should contain zero.

On reaching the end of the input, the function sets *pParseIndex* to -1. If called again, the function will return a NULL pointer and leave the value of *pParseIndex* unchanged.

E.2.4 Parsing CGI Multi-Part Form Data

In some cases, it is preferable to use a multi-part form when posting CGI data. The multi-part form is specified in the HTML code by adding the tag **ENCTYPE="multipart/form-data"** to the form type. When this form type is used, form entries are sent in a slightly different format than with the standard form, thus an alternate CGI parsing function is required.

After reading in the data from the socket, each form entry can be parsed from the multi-part form by using the supplied example function: cgiParseMultiVars(). This function parses the post data into individual records. The formal definition of the function is shown below.



cgiParseMultiVars Parse CGI Form Multi-Part POST Input

Syntax int cgiParseMultiVars(char *buffer, int buflen, CGIPARSEREC *recs, int maxrecs);

Parameters

buffer Buffer holding the entire post content

buflen Length of the post content

recs Pointer to an array of records of type CGIPARSEREC maxrecs The maximum number of records that can be written to *recs*

Return Value The number of valid records parsed, or -1 on a parsing error.

Description Reads input from a CGI POST operation pointed to by *buffer*, with length *buflen*, and

returns a collection of CGIPARSEREC records to recs. The caller must provide buffer space to hold recs, and indicate the maximum number of records that can be written to

the buffer in maxrecs.

The CGIPARSEREC record is defined as follows:

This function modifies the data in *buffer* to add string delimiters. This function should only be called once to parse all entries from the form data.

E.2.5 Sending HTTP/HTML Replies

After parsing the CGI POST form data, the CGI function should send some sort of reply to the requesting client. The reply takes the form of an HTTP message signifying success or error, potentially followed by HTML data.

The HTTP server supplies several functions to aid in building and sending HTTP data over the socket. In addition, the example applications contain various MACROS than can also help in initially developing a CGI function. The HTTP functions are fully described at the end of this section, but the main reply functions are usually one of the following:

httpSendFullResponse() Send full HTTP response, including a status code and an HTML file httpSendErrorResponse() Send full HTTP error response, including an HTML message

or

httpSendStatusLine() Send HTTP status response, including a status code and content

type

httpSendEntityLength() Send HTTP content length and terminate HTTP header (optional)

httpSendClientStr() Used after httpSendStatusLine() to send content data



As an example of using these functions, consider the two response MACROS included in inc\nettools\httpif.h.

```
//
// Common error responses
//
#define http404(Sock) httpSendErrorResponse(Sock, HTTP_NOT_FOUND)
#define http501(Sock) httpSendErrorResponse(Sock, HTTP_NOT_IMPLEMENTED)
```

These MACROS use the error response function to send a full error message to the client. Alternately, the <code>httpSendStatusLine()</code> function can be used to start a message that is completed by the application. Under normal circumstances, a CGI function will use the <code>httpSendStatusLine()</code> function to send an OK message to the client, followed by the <code>httpSendClientStr()</code> function to send client data in the form of a NULL terminated string. Note that an additional carriage return and line feed are required to separate the header from the HTML data.

For example, the following code sends a quick Success message.

```
// Send response status
httpSendStatusLine(Sock, HTTP_OK, CONTENT_TYPE_HTML);

// Terminate the response header
httpSendClientStr(Sock, CRLF);

// Send the Success Message
httpSendClientStr(Sock, "<html><h1>Success!</h1><br/>br></html>");
```

Note that the *httpSendClientStr()* function replaces the *httpSendClientData()* function from earlier releases of the NDK. For data sizes that can be represented by an integer, client data can also be sent simply by calling the sockets *send()* function.

E.2.6 HTML Error Response

The HTTP server generates a generic error response message for several possible HTTP errors. The function *httpSendErrorResponse()* is part of this function. The error response consists of two parts, the HTTP header and the HTML response message. It is the HTML message that is displayed to the web browser when an error occurs.

The default HTML message used by the HTTP server is quite plain. For example, on the error 404, it generates:

```
<html><body><h1>HTTP/1.0 404 - File Not Found</h1></body></html>
```

Some application developers may wish to enhance the HTML generation of errors. This is done by hooking a callback function into the HTTP server error processing. The callback hook is defined as:

```
_extern int (*httpErrorResponseHook)(SOCKET Sock, int StatusCode);
```

Any function using the callback must generate the content length tag, and then the entire HTML response page. (The content length is the length of the HTML response.) It can be written using the httpSendEntityLength() function.

If the application does not wish to handle the error, it can return NULL indicating that it did not handle the error. In this case, the HTTP server will use the default HTML. If the application returns 1, this tells the HTTP server that the HTTP response was completed by the callback function.

The httpErrorResponseHook function pointer is NULL by default. If an application needs to install a callback to this pointer, the value should be set before the HTTP server is initialized.

As an example of how the callback function may look, here is the default error response function. Any substitute function provided by the application would be quite similar:

```
typedef struct _codestr {
   int code;
   char *string;
} CODESTR;

// Note MAX string length is 30 (since Data[] is 80 bytes)
CODESTR codestr[] = {
```



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```
{ HTTP_OK, " OK" },
     HTTP NO CONTENT, " No Content" },
     HTTP_AUTH_REQUIRED, " Authorization Required" },
    { HTTP_NOT_FOUND, " File Not Found" },
    { HTTP_NOT_IMPLEMENTED, " Not Implemented" },
    { HTTP_NOT_ALLOWED, " Not Allowed" },
    { 0, " Unknown" }
};
int httpSendErrorHTML(SOCKET Sock, int StatusCode)
    char Data[80];
    int I;
    // Build the HTML response into Data[]
    sprintf(Data, "<html><body><h1>HTTP/1.0 %3d -", StatusCode);
    for(i=0;codestr[i].code && codestr[i].code!=StatusCode;i++);
    strcat(Data, codestr[i].string);
   strcat(Data,"</hl></body></html>");
    // Send the length of the HTML response
    // (this also terminates the HTTP header)
   httpSendEntityLength(Sock, strlen(Data));
    // Send the respone data
   httpSendClientStr(Sock, Data);
   return(1);
```

E.3 HTTP Authentication

The HTTP server included in the NDK supports the Basic method of HTTP authentication, which is MIME encoding of the username and password.

As with other HTTP functionality, the HTTP server calls an EFS function to perform file access authentication. The EFS function used is *efs_filecheck()*. The function is passed the filename of the file to be authenticated, and the username and password of the user attempting to access the file.

The exact method used to designate a file as protected and to authorize individual access, is determined by the implementation of the *efs_filecheck()* function. This section describes the operation of the example implementation of *efs_filecheck()* provided in the NDK.

E.3.1 Authorization Realms

Regardless of implementation of the authentication scheme at the EFS layer, the HTTP server understands the authority system to be based on four authorization realms. The realms are enumerated 1 to 4, and the authorization realm index (when required) is returned to the HTTP server by the efs filecheck() function.

When the HTTP server indicates to the client that authorization is required, it supplies the name of the authorization realm to the client. The application programmer can specify the name of each authorization realm by using the configuration system. The configuration tag CFGTAG_SYSINFO is used for storing authorization realm names. The item numbers used for the four realms are CFGITEM_SYSINFO_REALM1 through CFGITEM_SYSINFO_REALM4.

For example, to set the name of authorization realm 1, while building the configuration, the programmer could write:

If no realm name is supplied in the configuration, then a default realm name is used by the HTTP server.



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E.3.2 User Accounts

How and whether user accounts are stored in the system is entirely up to the system programmer. The user account is only accessed directly in the *efs_filecheck()* function.

However, the default implementation of *efs_filecheck()* uses the configuration system to access usernames and passwords. These user accounts can be added to the configuration system at any time. As an example, the following code adds a sample account to access authorization realm 1. The username and password are simply *username* and *password* respectively:

E.3.3 Designating Protected Files

As with the authorization user accounts, the method of how a file is designated as protected depends on the implementation of the *efs_filecheck()* function.

In the default implementation, files are grouped for authorization by their first level directory. For example, the files index.html and banner.gif would both carry the same authorization requirements, while the files mydir/sample.cgi and mydir/sample.htm would carry a different authorization. The file group is marked for authorization by placing a special file in the directory, named %R%. This file is exactly 4 bytes long, and contains an integer value, being the realm index 1 to 4. If there is no %R% file in the directory, then no authorization is required.

For example, the following code sets up a small web page in an unprotected space (the root directory), and then sets up sample.cgi and sample.htm in a protected directory, requiring authentication on authorization realm 1.

```
// The authentication scheme works by looking for files named %R% in the subdirectory
// of any given filename, or in the root directory if no subdirectory exits. The file
// contains a single 4 byte int that is the authentication realm index. If there is
// no file, there is no authentication.
//
// Note for this implementation, only the first subdirectory level is validated.
// The int "OurRealm" will be our "%R%" realm file, forcing any file
// located in the same directory to be authenticated on realm 1. The
// system supports realms 1 to 4.
// Note that we are only going to protect the "protected/" subdir,
// but it is also possible to protect the entire web site by putting
// a %R% file in the root. Also, you can have the root protected
// on (say) realm 1, and a subdir on (say) realm 2, allowing for
// "users" (members of realm 1) and "superusers" (members of both
// realm 1 and realm 2).
static int OurRealm = 1;
void AddWebFiles(void)
   efs_createfile("index.html", DEFAULT_SIZE, DEFAULT);
   efs_createfile("logobar.gif", LOGOBAR_SIZE, LOGOBAR);
   efs_createfile("dspchip.gif", DSPCHIP_SIZE, DSPCHIP);
    efs_createfile("inform.cgi", 0, (UINT8 *)cgiInform);
   efs_createfile("protected/%R%", 4, (UINT8 *)&OurRealm);
   efs_createfile("protected/sample.htm", SAMPLE_SIZE, SAMPLE);
   efs_createfile("protected/sample.cgi", 0, (UINT8*)cgiSample);
}
```



www.ti.com CGI Function Example

E.4 CGI Function Example

As an example of using all the concepts described so far, consider a simple example. Assume an applications programmer wishes to create a Web form that inputs and processes user data.

E.4.1 Create the HTML Page

The HTML page can be created with an HTML editor, or by hand. For this example, there is an HTML page that contains a simple CGI form. The contents of the example page, default.htm are shown below.

```
<html>
<head><title>CGI Sample</title></head>
<body>
    <h1>CGI Sample Form</h1>
    <hr WIDTH="100%">
   Fill in the form fields and hit 'Submit'.
    <form name="my_form" method="POST" action="sample.cgi">
        Name: <input type="text" name="name"><br>
        I dislike spam: <input type="checkbox" name="spam" value="no!"><br>
        Favorite Pizza:
            <input type="radio" name="pizza" value="pepperoni"> Pepperoni
            <input type="radio" name="pizza" value="sausage"> Sausage
            <input type="radio" name="pizza" value="cheese" checked> Cheese
            <input type="radio" name="pizza" value="other"> Other
            <hr>>
        Favorite Color: <select name="color">
            <option value="red"> Red
            <option value="green"> Green
            <option value="blue"> Blue
            <option value="yellow"> Yellow
            <option value="cyan"> Cyan
            <option value="magenta"> Magenta
            <option value="black"> Black
            <option value="white"> White
            </select>
        <input type="submit"> <input type="reset">
    </form>
</body> </html>
```

The next step performed is to convert this HTML file to C source file, as seen in Section E.1.2. Once the page is in C source code form, it can be added to the program.

E.4.2 Create the Base WEBPAGE Source File

Once the HTML pages are ready in source form, the main WEBPAGE.C source file is created. This file will perform all the necessary Web processing in the example. The basic source code declares the HTML pages as files to the EFS file system. To do this, it exports two functions called from the main network initialization routine, *AddWebFiles()* and *RemoveWebFiles()*. Note that a CGI function is also declared to handle processing of the CGI form contained on the Web page, called **sample.cgi**.



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The source code as defined so far is shown below.

```
static int cgiSample(SOCKET htmlSock, int ContentLength, char *pArgs )
    char *name = 0, *spam = 0, *pizza = 0, *color = 0;
   char *buffer, *key, *value;
   int len;
   int parseIndex;
   char htmlbuf[MAX_RESPONSE_SIZE];
    // The pArgs parameter is used for passing arguments
    // on the address line using the '?' operator. It is
    // typcially not used on a CGI POST
   // 1. Read in the request data
    // First, allocate a buffer for the request
   buffer = (char*) mmBulkAlloc( ContentLength + 1 );
   if (!buffer)
       goto ERROR;
    // Now read the data from the client
    len = recv( htmlSock, buffer, ContentLength, MSG_WAITALL );
   if (len < 1)
       goto ERROR;
    // 2. Parse request using cgiParseVars(), or a similar function
    // Setup to parse the post data
   parseIndex = 0;
    buffer[ContentLength] = '\0';
    // Process request variables until there are none left to do
    {
       key = cgiParseVars( buffer, &parseIndex );
       value = cgiParseVars( buffer, &parseIndex );
        if( !strcmp("name", key) )
           name = value;
        else if( !strcmp("pizza", key) )
           pizza = value;
        else if( !strcmp("spam", key) )
           spam = value;
        else if( !strcmp("color", key) )
           color = value;
        } while ( parseIndex != -1 );
    // 3. Process request in some meaningful way . . .
    // (OK, we really don't do this here.)
    // 4. Send a response. Keep in mind the first line of the
    \//\ response should indicate whether the request was
    // successful or not.
   httpSendStatusLine(htmlSock, HTTP_OK, CONTENT_TYPE_HTML);
    // 5. Send appropriate headers
    // No more header data to send - CRLF terminates header
   html( CRLF );
    // 6. Send the response data
    // Build our HTML response
    // Here we'll just echo back the input we received
    // to an HTML table.
    //
```



```
html("<h1>Form Information</h1>");
  html(divider);
  html("\r\n");
  if( name )
     sprintf( htmlbuf, tablefmt, "Name:", name );
     html( htmlbuf );
  }
  if( spam )
     sprintf( htmlbuf, tablefmt, "Likes Spam:", spam );
     html( htmlbuf );
  }
  if( pizza )
     sprintf( htmlbuf, tablefmt, "Favorite Pizza:", pizza );
  html( htmlbuf );
  if( color )
     sprintf( htmlbuf, tablefmt, "Favorite Color:", color );
     html( htmlbuf );
  html("<br>\r\n");
  html(divider);
  ERROR:
  if( buffer )
     mmBulkFree( buffer );
  return(1);
}
```

E.5 HTTP Server Exported Functions

The HTTP server module exports several functions and strings to aid in the creation of a CGI function. This section contains the formal specification for these functions. The first part of this appendix describes how to use these functions in creating a HTTP CGI function in C.

E.5.1 Commonly Used Strings

To aid in the creation of the response data, some commonly used HTML strings can be defined. Some of these are already defined in the HTTPIF.H file. These include the following (note that all entries, except the first three, include a trailing space character.):

Global Name	String Value	
DEFAULT_NAME	"index.html"	
CRLF	"\r\n"	
SPACE	п п	
HTTP_VER	"HTTP/1.0 "	
CONTENT_LENGTH	"Content-length: "	
CONTENT_TYPE	"Content-type: "	
CONTENT TYPE APPLET	"application/octet-stream '	•



Global Name	String Value
CONTENT_TYPE_AU	"audio/au"
CONTENT_TYPE_DOC	"application/msword "
CONTENT_TYPE_GIF	"image/gif "
CONTENT_TYPE_HTML	"text/html "
CONTENT_TYPE_JPG	"image/jpeg "
CONTENT_TYPE_MPEG	"video/mpeg "
CONTENT_TYPE_PDF	"application/pdf "
CONTENT_TYPE_WAV	"audio/wav "
CONTENT_TYPE_ZIP	"application/zip "

E.5.2 Function Overview

The basic HTTP Server exported functions are as follows:

httpSendStatusLine() Send the status of this request to the client httpSendClientStr() Send NULL terminated string data to client httpSendFullResponse() Send a full formatted response to the client

httpSendEntityLength() Send the content length and terminate HTTP header

httpSendErrorResponse() Send a full formatted response to the client

E.5.3 HTTP Server Exported API Functions

httpSendStatusLine Send the Status of this Request to the Client

Syntax void httpSendStatusL	e(SOCKET So	ock, int StatusCode, char	*ContentType);
-----------------------------	-------------	---------------------------	-----------------

Parameters

Sock Socket on which to send

StatusCode HTTP status code of the request ContentType HTTP type string of the response

Return Value None.

Description Sends a formatted response message to *Sock* with the given status code and content

type. The value of *ContentType* can be NULL if no ContentType is required.

The status code and content type should match HTTP standard definitions. Some content type strings are listed in Section E.5.1. The pre-defined status codes include:

HTTP_OK	(200)
HTTP_NO_CONTENT	(204)
HTTP_AUTH_REQUIRED	(401)
HTTP_NOT_FOUND	(404)
HTTP_NOT_ALLOWED	(405)
HTTP_NOT_IMPLEMENTED	(501)



httpSendClientStr Send NULL Terminated String Data to Client

Syntax void httpSendClientStr(SOCKET Sock, char *Response);

Parameters

Socket on which to send

Response Pointer to NULL terminated string

Return Value None.

DescriptionThis function sends the indicated NULL terminated response string to the indicated client

socket. In other words, it calls strlen() and send().

httpSendFullResponse Send a Full Formatted Response to the Client

Syntax void httpSendFullResponse(SOCKET Sock, int StatusCode, char *RequestedFile);

Parameters

Sock Socket on which to send

StatusCode HTTP status code of the request

RequestedFile Pointer to filename of file to include in body

Return Value None.

Description Sends a full formatted response message to *Sock*, including the file indicated by the

filename pointed to by RequestedFile. The status code for this call is usually HTTP_OK.

httpEntityLength Send the Content Length and Terminate HTTP Header

Syntax void httpSendEntityLength(SOCKET Sock, INT32 EntityLength);

Parameters

Socket on which to send

EntityLength Length of the entity (usually HTML page) to follow the HTTP header

Return Value None.

Description Writes out the entity length tag, and terminates the HTTP header with an additional

CRLF. Because the header is terminated, this must be the last tag written. Entity data

should follow immediately.



httpSendErrorResponse Send a Full Formatted Error Response to the Client

Syntax void httpSendErrorResponse(SOCKET Sock, int StatusCode);

Parameters

Sock Socket on which to send

StatusCode HTTP status code of the request

Return Value None.

Description Sends a full formatted error response message to *Sock*, including a small HTML file

displaying the status code. For example, HTTP_NOT_FOUND would generate:

/html></body></html>



IP Version 6 (IPv6) Stack API

This section discusses use of the API for the IPv6 stack.

Topic		Page
	Synopsis	



Synopsis www.ti.com

F.1 Synopsis

The IPv6 stack is designed to be modular and coexist with the traditional IPv4 stack. The IPv6 stack can be easily built in or out of an application using the "_INLCUDE_IPv6_CODE" compilation flag. IPv6 stack is available only with NIMU enabled architectures. Default stack builds are provided with IPv6 stack enabled. The *TMS320C6000 Network Developer's Kit (NDK) User's Guide* (SPRU523) has details on the various IPv6 stack builds packaged in the NDK.

The IPv6 stack is similar in its architecture to the IPv4 stack with respect to the components it is made of. Figure F-1 shows the main building blocks of IPv6.

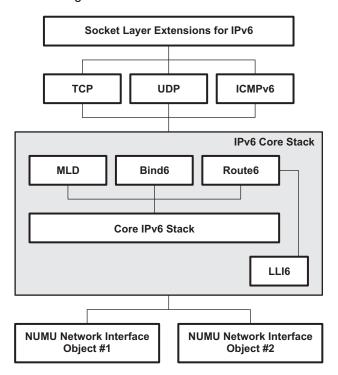


Figure F-1. NDK IPv6 Architectural Block Diagram

The IPv6 stack components and the RFCs it supports are as follows:

- IPv6 Core Stack
 - Neighbor Cache Support
 - Routing Table Support
 - Extension Header Support
 - Fragmentation/Reassembly
 - Binding Lifetime Management
 - Routing Table Lifetime Management
 - RFCs
- RFC 3596 DNS Extensions to Support IPv6
- RFC 2460 Internet Protocol Version 6 Only support for processing of extension headers
- RFC 2461 Neighbor Discovery for IPv6
- RFC 2462 IPv6 Stateless Address Autoconfiguration
- RFC 2463 IPv6 Internet Control Message Protocol (ICMPv6) for IPv6
- RFC 2464 Transmission of IPv6 Packets over Ethernet Networks
- RFC 3484 Default Address Selection for IPv6 Implemented partially
- RFC 3587 IPv6 Global Unicast Address Format
- RFC 3493 Basic Socket Interface Extensions for IPv6 Implemented but not fully. No compatibility with



IPv4 nodes, multicast, getaddrinfo/freeaddrinfo.

- RFC 2373 IPv6 Addressing Architecture No support for IPv6 addresses embedded with IPv4.
- Layer4 Support
 - ICMPv6
 - RAW
 - UDP
 - TCP
- Socket Layer Extensions for IPv6
- Application Support
 - TFTP
 - Telnet
 - Web Server
 - DNS

F.2 API Functions and Data Structures

The IP Version 6 (IPv6) Stack API and data structures can be downloaded from the following URL: http://www-s.ti.com/sc/techlit/spru524.zip

F.2.1 Socket Support for IPv6

The following is a list of Socket API that is supported:

- socket
- bind
- listen
- connect
- getpeername
- getsockname
- send
- sendto
- recv
- recvfrom
- setsockopt (limited IPv6 options supported)
- getsockopt (limited IPv6 options supported)
- close
- shutdown

The No-Copy variants for receive are not currently supported for IPv6 sockets.



F.2.2 Architecture

Figure F-2 illustrates the internal architecture block diagram for the socket layer:

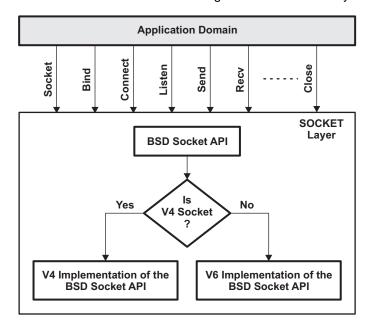


Figure F-2. Internal Architecture Block Diagram for Socket Layer

When a socket is created, it is marked as either an IPv4 socket or an IPv6 socket, i.e., in the socket creation the socket family selected is either AF_INET (IPv4) or AF_INET6 (IPv6). This is then used as a de-multiplexing field to differentiate which socket implementation needs to be selected. This architecture reduces the impact on the existing IPv4 implementation of sockets.

F.2.3 Socket Options

The IPv6 socket layer supports all the standard socket properties except the following:

SO IFDEVICE

The option binds the socket to an interface and ensures that packets are transmitted on the specified interface.

SO TXTIMESTAMP

This is a Texas Instruments specific option that was used for time stamping the path through the IPv6 Stack.

Of all the IPv6 specific options, the only one currently supported is the IPV6_UNICAST_HOPS, which allows the configuration of the Hop Limit in the packet. Remaining options will be added in future releases.

F.2.4 Daemon6

NDK supports a module called *Daemon*, which is a single network task that monitors the socket status of multiple network servers. When activity is detected, the daemon creates a task thread specifically to handle the new activity. This is more efficient than having multiple servers, each with their own listening thread.

Since the Daemon operates on sockets, a new module called Daemon6 has been created that does the same functionality as Daemon except that it operates on V6 sockets.



The following snippet of code indicates how Echo Servers on UDP can be made to operate on both IPV4 and IPV6

```
hEchoUdp = DaemonNew( SOCK_DGRAM, 0, 7, dtask_udp_echo, OS_TASKPRINORM, OS_TASKSTKNORM, 0, 1);

#ifdef _INCLUDE_IPv6_CODE
hEchoUdp6 = Daemon6New (SOCK_DGRAM, IPv6_UNSPECIFIED_ADDRESS, 7, dtask_udp_echo6, OS_TASKPRINORM, OS_TASKSTKNORM, 0, 1);

#endif
```

F.2.5 Nettools Applications

The Net-Tools module in the NDK stack has multiple applications that are provided to System developers. These applications provide basic services such as Telnet, TFTP etc. This section documents the modifications in these applications to support IPv6.

F.2.5.1 Telnet

Telnet is implemented as a server daemon that resides on port 23 and waits for incoming connections. The Telnet protocol by itself is agnostic to the Layer3 implementation i.e. IPv4 or IPv6. To be able to support IPv6 the following code needs to be added in the application startup code:

The code uses the Daemon6 API described above and starts the Telnet Daemon that opens an IPv6 socket on port 23. There is no conflict since the IPv4 Telnet daemon has also opened port 23 since the socket library for IPv4 and IPv6 are different.

With these modifications the Telnet daemon works over IPv6. There is one minor change in the Telnet code base that needs to be addressed. This is a display issue; after performing the telnet the server displays the Peer IP Address and Port Information.

For example, on IPv4 the display is as follows:

```
TCP/IP Stack Example Client
Welcome connection: 192.168.1.2:3881
Welcome to the console program.
Enter '?' or 'help' for a list of commands.
```

On IPv6, the display code needs to be modified as follows to display the IPv6 address of the peer:

```
TCP/IP Stack Example Client
Welcome connection : fe80::a00:9ff:fedc:fbdc:1061
Welcome to the console program.
Enter '?' or 'help' for a list of commands.
```

Submit Documentation Feedback



F.2.5.2 Web Server

The Web Server is implemented as a server daemon that resides on port 80 and waits for incoming connections. Much like Telnet; the web server is agnostic to the layer3 protocol.

The following snippet of code needs to be added to the application startup code to start the web server as a daemon:

Besides this, there are no additional modifications required in the HTTP code.

F.2.5.3 TFTP

The TFTP is an IPv6 client that implements the Trivial File Transfer Protocol over IPv6. The TFTP protocol uses the IP Address and Port information to ensure that data packets being received match the peer server and port information; this is typically implemented by most TFTP implementations for a more secure file transfer.

To achieve modularity, a new module TFTP6 has been created, which was based on the TFTP module. Modifications have been done to ensure that the TFTP6 module uses the AF_INET6 family for socket creation and the security checks are done with respect to the IPv6 addresses.

The following new API has been published to be able to retrieve a file over an IPv6 network through TFTP:

F.2.5.4 DNS Client

The existent DNS Client in NDK is capable of doing IPv4 forward and reverse name resolutions [2]. This has now been extended to do IPv6 forward and reverse AAAA (Quad-A) type DNS lookups as described in RFC 3596 [2] over IPv4 network. Currently, there is no support for the DNS client to communicate with an IPv6 DNS server; i.e., the DNS client is only capable of doing name resolutions by communicating with an IPv4 DNS server. DNS over IPv6 network is left for a future release.

To be able to support IPv6 name resolution, the following changes have been made to the existing implementation of DNS:

- A new Record type T_AAAA specific to the Internet class has been defined that can store a single IPv6 address. The IANA assigned value of the type is 28 (decimal) [2].
- The basic HOSTENT data structure has been modified (as shown below) such that it can hold both IPv4 and IPv6 addresses.

```
* @brief
  The structure describes the Host Name - IP Address record
* @details
 * The HOSTENT structure holds information such as IPv4/v6
 * address, host name mappings for a given host. It is used
* by the DNS resolver in conveying such HostName - IP Address
* mappings to a user application.
* /
struct _hostent {
   /**
              This is the official name / Fully Qualified Domain Name
     * (FQDN) of the host.
     * /
   char *h name;
    /**
     * @brief
                This indicates the address family of the IP address that
     * maps to the given hostname. The values it takes are AF_INET (v4) /
     * AF INET6 (v6).
```



```
* /
    int h_addrtype;
    * @brief
                This indicates the length (in bytes) of the IP address that follows.
     * For IPv4 address it is set to 4, and for IPv6 address set to 16 bytes.
     * /
    int h_length;
    /**
     * @brief
                 This is the number of IP addresses returned for the given
     * hostname.
    int h_addrcnt;
#ifndef _INCLUDE_IPv6_CODE
     * @brief
                 List of upto MAXIPADDR IPv4 addresses (Network format) that map
     * to the given hostname.
    IPN h_addr[MAXIPADDR];
#else
     * @brief
                List of upto MAXIPADDR IPv4/IPv6 addresses that map to given hostname.
    char* h_addr_list[MAXIPADDR];
#endif
```

NOTE: The field *h_addr* was an array of IPv4 addresses in IPN format. To make it generic enough to hold both IPv4 and IPv6 addresses, this field is now replaced with *h_addr_list*. The field *h_addr_list* in the current implementation is an array of strings and it holds the IPv4/v6 addresses as pointers to IPN/IP6N, respectively. The following is an example illustration of how one could use the h_addr_list field to access IPv4/IPv6 address from the new HOSTENT structure.

IPv4 Illustration:

IPN IPTmp;

```
retcode = DNSGetHostByXXX( arg1, ... argn );

for( retcode = 0; retcode < phe->h_addrcnt; retcode++ )
{
    IPTmp = (IPN)RdNet32(phe->h_addr_list[0]);
    ConPrintf("IPAddr = ");
    ConPrintIPN(IPTmp);
    ConPrintf("\n");
}

IPv6 Illustration:

IP6N IPv6Tmp;
retcode = DNSGetHostByXXX( arg1, ... argn );

for( retcode = 0; retcode < phe->h_addrcnt; retcode++ )
{
    IPv6Tmp = *(IP6N *)phe->h_addr_list[0];
    ConPrintf("IPv6 Addr = ");
    ConIPv6DisplayIPAddress(IPv6Tmp);
    ConPrintf("\n");
}
```

 Two new APIs have been added for hostname to IPv6 address and IPv6 address to hostname resolution. The following are the two new APIs:



IPv6 Address to Hostname Resolution API (reverse DNS lookup for IPv6):

```
* @b Description
     * @n
           This function does reverse DNS lookup on the supplied
           IPv6 Address. On a successful return, pScrapBuf can be
            treated as a HOSTENT structure. The size of the scrap
           buffer (size) must be greater than the size of the structure
            as the structure will contain pointers into the scrap
            buffer, and the scrp buffer is also used for temporary
            name storage. 512 bytes of scrap buffer memory should be
            sufficient for most requests.
      @param[in] IPAddr
            The IPv6 address that needs to be resolved in IP6N format.
     * @param[out] pScrapBuf
           Scrap buffer area to hold the results on a successful
            DNS resolution.
      @param[in] size
           Size of the scrap buffer available.
      @retval
            Success - 0
     * @retval
            Error - >0, error code to determine the error.
int DNSGetHostByAddr2( IP6N IPAddr, void *pScrapBuf, int size );
```



Hostname to IPv6 Address Resolution API (forward DNS lookup for IPv6):

```
* @b Description
     * @n
            This function does DNS lookup on the supplied hostname.
            On a successful return, the pScrapBuf can be treated as a
            HOSTENT structure. The size of the scrap buffer (size)
            must be greater than the size of the structure as the
            structure will contain pointers into the scrap buffer, and
            the scrap buffer is also used for temporary name storage.
            512 bytes should be sufficient for most DNS requests.
            If the host name "Name" is terminated with a dot ('.'), the
            dot is removed. If the name contains a dot anywhere, it is
            used unmodified for an initial lookup. If the lookup fails -
            the appropriate DNS error code is returned. No default
            domain lookups are performed for IPv6, so if the hostname
            provided by user doesnt contain a dot, implying no
            domain name is provided, this function returns a foramt error.
      @param[in] Name
            The hostname to be resolved supplied by the user.
      @param[in] af_family
            The family (AF_INET/AF_INET6) of the IP address to which the
            query needs to be resolved to. If AF_INET is provided as the
            argument, then DNSGetHostByName is called in turn for IPv4
            lookup.
       @param[out] pScrapBuf
            Scrap buffer area to hold the results on a successful
            DNS resolution.
      @param[in] size
            Size of the scrap buffer available.
      @retval
            Success - 0
      @retval
            Error - >0, error code to determine the error.
int DNSGetHostByName2( char *Name, UINT8 af_family, void *pScrapBuf, int size );
```



F.2.6 Configuring the IPv6 Stack

One of the key differences between IPv6 and IPv4 is that the IPv6 stack needs to be instantiated at run time. This is because all IPv6 enabled interfaces automatically get a link local address, which is identified by the unique MAC address. Once an IPv6 address is assigned, it is mandatory that the IPv6 stack perform the Duplicate Address Detection process to ensure address uniqueness.

This implies that unlike IPv4 addresses cannot be assigned to the interface before the Ethernet Link is up because this will imply that the DAD packets never get transmitted out hence defeating the overall purpose.

RFC 2462, Section 5.3, states the following:

A node forms a link-local address whenever an interface becomes enabled. An interface may become enabled after any of the following events:

- The interface is initialized at system startup time.
- The interface is reinitialized after a temporary interface failure or after being temporarily disabled by system management.
- The interface attaches to a link for the first time.
- The interface becomes enabled by system management after having been administratively disabled.

In order to support IPv6 all Platform Support Packages should be modified such that the above mentioned API's are added in the Ethernet Link Change code. This is outside the context of the document and should be addressed in the NDK Support Package documentation.

Initialization and de-Initialization of the IPv6 stack is the responsibility of the system application and should be used in conjunction with the Link change events described above. Figure F-3 showcases the various entities in the system:

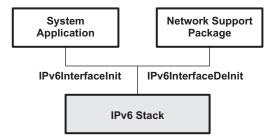


Figure F-3. IPv6 Stack Instantiation Placement

The IPv6 stack provides the necessary API's, which are responsible for the initialization and cleanup of the IPv6 stack instance on the interface.

For user convenience, a sample command prompt demonstration has been provided with the IPv6 stack to initialize and attach the IPv6 stack to a desired interface, and to demonstrate the use of various IPv6 utilities. For more details, see the IPv6 Stack Testing section of the *TI Network Developer's Kit (NDK)* v2.21 User's Guide (SPRU523) document.



Legacy Configuration Manager API

To simplify the configuration process, the NDK now recommends that you use the XGCONF configuration tool within CCS to configure an application's use of NDK modules. Use of that tool is described in the *TI Network Developer's Kit (NDK) User's Guide* (SPRU523). XGCONF is the same configuration tool used to configure SYS/BIOS.

This appendix provides legacy documentation for the configuration API used for configuration in previous versions of the NDK.

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Configuration Methods www.ti.com

Configuration Methods

Internally, the XGCONF configuration tool generates C code that calls into and updates the configuration database used in previous versions of the NDK. In fact, you can still choose to use the configuration API if you have legacy code. However, you must choose one method or the other to configure your application.

NOTE: You should not mix configuration methods. If you have legacy NDK applications that use the old C-based configuration method, you should either continue to use that method or convert the configuration entirely to an *.cfg file configuration. If a project uses both methods, there will be conflicts between the two configurations.

This appendix describes the C APIs that legacy NDK applications use to create and manage a system configuration.

G.2 Configuration Manager

The configuration manager is a collection of API functions to help you create and manipulate a configuration. The manager API is independent of the configuration specification.

The configuration is arranged as a database with a master key (called Tag) that defines the class of configuration item. A second key (called *Item*) determines the sub-item type in the tag class. For each tag and item, there can be multiple instances. Items can be further distinguished by their instance value.

The configuration is based on an active database. That is, any change to the database can cause an immediate reaction in the system. For example, if a route is added to the configuration, it is added to the system route table. If the route is then removed from the configuration, it is removed from the system route table.

To facilitate the active procession of configuration changes in a generic fashion, the configuration API allows the installation of service provider callback functions that are called to handle specific tag values in the configuration.

Configurations can be set active or inactive. When a configuration is active, any change to the configuration results in a change in the system. When a configuration is inactive, it behaves like a standard database. Part of the main initialization sequence is to make the system configuration active, and then inactive when shutting down.

Both the configurations and configuration entries are referenced by a generic handle. Configuration functions (named as CfgXxx()) take a configuration handle parameter, while configuration entry functions (name as CfgEntryXxx()) take a configuration entry handle parameter. These handles are not interchangeable.

Configuration entry handles are referenced. This means that each handle contains an internal reference count so that the handle is not destroyed by one task while another task expects it to stay valid. Functions that return a configuration entry handle supply a referenced handle in that its reference count has already been incremented for the caller. The caller can hold this handle indefinitely, but should dereference it when it is through. There are three calls that dereference a configuration entry handle. These are: CfgRemoveEntry(), CfgGetNextEntry(), and most simply CfgEntryDeRef(). See individual function descriptions for more information.

The PPP module in the stack library and several modules in the NETTOOLS library make use of a default configuration to store and search for data. The default configuration is accessed by passing in a NULL configuration handle to any function that takes the hCfg parameter (except CfgFree()). The default configuration is specified by calling CfgSetDefault().



www.ti.com Configuration Manager

G.2.1 Function Overview

The configuration access functions (in functional order) are as follows:

Configuration Functions:

CfgNew() Create a new configuration
CfgFree() Destroy a configuration
CfgSetDefault() Set default configuration
CfgGetDefault() Get default configuration

CfgLoad() Load configuration from a linear memory buffer CfgSave() Save configuration to a linear memory buffer

CfgSetExecuteOrder() Set the tag initialization and shutdown order on execute

CfgExecute() Make the configuration active or inactive

CfgSetService() Sets service callback function for a particular tag
CfgAddEntry() Add a configuration entry to a configuration

CfgRemoveEntry() Remove entry from configuration

CfgGetEntryCnt() Get the number of item instances for a tag/item pair CfgGetEntry() Get a referenced handle to a configuration entry

CfgGetNextEntry() Return supplied entry handle and get next entry handle
CfgGetImmediate() Get configuration entry data without getting an entry handle

Configuration Entry Functions:

CfgEntryRef()

Add a reference to a configuration entry handle

CfgEntryDeRef()

CfgEntryGetData()

CfgEntrySetData()

CfgEntrySetData()

CfgEntryInfo()

Add a reference to a configuration entry handle

Remove a reference to a configuration entry handle

Get configuration entry data from entry handle

Replace data block of entry data using entry handle

Get information on a configuration entry handle



G.2.2 Configuration API Functions

CfgAddEntry Add Configuration Entry to Configuration

int CfgAddEntry(HANDLE hCfg, uint Tag, uint Item, uint Mode, uint Size, UINT8 *pData, **Syntax**

HANDLE *phCfgEntry);

Parameters

hCfg Handle to configuration Tag Tag value of new entry Item value of new entry Item

Mode Mode flags for how to add entry Size Size of entry data pointed to by pData

pData Pointer to entry data

phCfgEntry Pointer to where to write handle of new configuration entry

Return Value

Returns 1 on success with successful processing by a service callback function (see CfgSetService())

Returns 0 on success with no processing performed by a service callback function Returns less than 0 but greater than CFGERROR_SERVICE on a configuration error

The possible configuration errors are:

CFGERROR_BADHANDLE Invalid hCfg handle

CFGERROR_BADPARAM Invalid function parameter

CFGERROR RESOURCES Memory allocation error while adding entry

> Returns less than or equal to CFGERROR_SERVICE when the service callback function returns an error. Service errors are specific to the service callback functions installed and are thus implementation dependent. The original error return from the service callback can be retrieved by using the CFG GET SERVICE ERROR() macro:

ServiceErrorCode = CFG GET SERVICE ERROR(CfqAddEntryReturnValue);

NOTE: On a service error, the configuration entry is still added to the configuration, and an entry handle is written to phCfgEntry when the pointer is supplied.

Description

This function creates a new configuration entry and adds it to the configuration.

The phCfgEntry parameter is an optional pointer that can return a handle to the newly added configuration entry. When the phCfqEntry parameter is valid, the function writes the referenced handle of the new configuration entry to the location specified by this parameter. It is then the caller's responsibility to dereference this handle when it is finished with it. When the parameter phCfqEntry is NULL, no entry handle is returned, but the function return value is still valid.

Configuration entry handles are dereferenced by calling one of the following:

CfgEntryDeRef() Stop using the entry

CfgRemoveEntry() Stop using entry and remove it from the configuration

CfgGetNextEntry() Stop using entry and get next entry



If the execution state of the configuration is active (see *CfgExecute()*), the addition of the configuration entry is immediately reflected in the operating state of the system.

Multiple configuration entries can exist with the same Tag and Item key values. The system creates a third key (Instance) to track these duplicate keyed entries. However, by default, the configuration system does not allow for fully duplicate entries. Entries are full duplicates if there exists another entry with the same Tag and Item key values and an exact duplicate data section (size and content). When a full duplicate entry is detected, the new (duplicate) entry is not created.

There are some options that determine how the entry is added to the configuration by using flags that can be set in the Mode parameter. The default behavior when adding an object is as follows:

- Multiple instances with the same Tag and Item values are allowed.
- However, duplicate instances with the same Tag, Item, Size, and pData contents are ignored.
- New entries are saved to the linear buffer if or when CfgSave() is used.

To modify the default behavior, one or more of the following flags can be set:

CFG_ADDMODE_UNIQUE CFG_ADDMODE_DUPLICATE Replace all previous entry instances with this single entry. Allow full duplicate entry (duplicate Tag, Item, and entry data).

CFG ADDMODE NOSAVE

Do not include this entry in the linear buffer in CfgSave().

Requests to add duplicates are normally ignored.

NOTE: Setting both the CFG_ADDMODE_UNIQUE and

CFG_ADDMODE_DUPLICATE flags is the same as only setting

CFG_ADDMODE_UNIQUE.



CfgExecute Set the Execution State (Active/Inactive) of the Configuration

Syntax int CfgExecute(HANDLE hCfg, int fExecute);

Parameters

hCfg Handle to configuration

fExecute Desired execute state (1 = active)

Return Value Returns 0 on success, or less than 0 on an operation error. The possible errors are:

CFGERROR_BADHANDLE Invalid hCfg handle
CFGERROR_BADPARAM Invalid function parameter

CFGERROR_ALREADY Configuration is already in desired state

Description When a configuration is first created, it is in an inactive state, so changes to the

configuration are not reflected by changes to the system.

Executing the configuration (setting *fExecute* to 1) causes all current entries in the configuration to be loaded, and any further changes in the configuration to be

immediately reflected in the system.

Disabling execution of the configuration (setting *fExecute* to 0) causes all configuration entries to be unloaded from the system (note that they are not removed from the configuration). Any further changes to the configuration are not reflected by changes to

the system.

CfgFree Destroy a Configuration Handle

Syntax void CfgFree(HANDLE hCfg);

Parameters

hCfg Handle to configuration

Return Value None.

Description Destroys a configuration. Unloads and frees all configuration entries and frees the

configuration handle. After this call, the configuration handle *hCfg* is invalid.

CfgGetDefault Get Default Configuration Handle

Syntax HANDLE CfgGetDefault();

Parameters None.

Return Value Returns a handle to the current default configuration, or NULL if None.

Description This function returns the current default configuration handle. The default handle is used

in any function that takes a *hCfg* parameter, when the specified parameter is NULL. At initialization, there is no default configuration. It must be allocated by CfgNew() and then specified via *CfgSetDefault()*. Normally, the default configuration is reserved for system

use.



CfgGetEntry Get Configuration Entry from Configuration

int CfgGetEntry(HANDLE hCfg, uint Tag, uint Item, uint Index, HANDLE *phCfgEntry); **Syntax**

Parameters

hCfg Handle to configuration Tag Tag value of entry Item value of entry Item

Index Instance index to get (1 to n)

phCfgEntry Pointer to where to write configuration entry handle

Return Value Returns 1 if a matching entry was found

Returns 0 if a matching entry was not found

Returns less than 0 on error

The possible configuration errors are:

CFGERROR BADHANDLE Invalid *hCfg* handle

CFGERROR BADPARAM Invalid function parameter

Description

This function searches the configuration for an entry matching the supplied *Tag* and *Item* parameters and an index matching the supplied *Index* parameter. For example, when Index is 1, the first instance is returned, when Index is 2, the second instance is returned. The total number of instances can be found by calling CfgGetEntryCnt().

The phCfgEntry parameter is an optional pointer that can return the handle of the configuration entry found by this function. When the phCfqEntry parameter is valid, the function writes the referenced handle of the configuration entry found to this pointer. It is the caller's responsibility to dereference the handle when it is no longer needed. When the parameter phCfgEntry is NULL, no entry handle is returned, but the function return value is still valid (found or not found).

Configuration entry handles are dereferenced by the calling one of the following:

CfgEntryDeRef() Stop using the entry

CfgRemoveEntry() Stop using entry and remove it from the configuration

CfgGetNextEntry() Stop using entry and get next entry

NOTE: Do not attempt to use the Index value to enumerate all entry instances in the configuration. The index of an entry handle is valid only at the time of the call as an item can move up and down in the list as configuration changes are made. To enumerate every entry for a Tag/Item pair, start with Index 1, and then use CfgGetNextEntry() to get additional entries.



CfgGetEntryCnt Get the Number of Entry Instances for the Supplied Tag/Item Pair

Syntax int CfgGetEntryCnt(HANDLE hCfg, uint Tag, uint Item);

Parameters

hCfg Handle to configuration
Tag Tag value of query
Item Item value of query

Return Value Returns 0 or greater on success (number if instances found) or less than 0 on error.

The possible errors are:

CFGERROR_BADHANDLE Invalid hCfg handle

CFGERROR_BADPARAM Invalid function parameter

Description This function searches the configuration for all instances matching the supplied Tag and

Item parameters and returns the number of instances found.

CfgGetImmediate Get Configuration Entry Data Directly from Configuration

Syntax int CfgGetImmediate(HANDLE hCfg, uint Tag, uint Item, uint Index, int Size, UINT8

*pData);

Parameters

Description

hCfg Handle to configuration
Tag Tag value of entry
Item Item value of entry

Index Instance index to get (1 to *n*)
Size Size of buffer to receive data

pData Pointer to data buffer to receive data

Return Value Number of bytes copied

This function is a useful shortcut when searching the configuration for well known entries. It searches the configuration for entries matching the supplied *Tag* and *Item* parameters and uses the item matching the supplied Index parameter. For example, if *Index* is 1, the first instance is used, if *Index* is 2, the second instance is used. The total

number of instances can be found by calling CfgGetEntryCnt().

Instead of returning a referenced handle to the configuration entry (as with the more generic CfgGetEntry() function), this function immediately gets the entry data for this

entry and copies it to the data buffer pointed to by pData.

The increased simplicity does decrease the function's flexibility. This function returns the number of bytes copied, so it will return 0 for any of the following reasons:

- A supplied parameter is incorrect
- The item was not found
- The supplied buffer size (specified by Size) was not large enough to hold the data



CfgGetNextEntry Get the Next Entry Instance Matching the Supplied Entry Handle

Syntax int CfgGetNextEntry(HANDLE hCfg, HANDLE hCfgEntry, HANDLE *phCfgEntryNext);

Parameters

hCfg Handle to configuration

hCfgEntry Handle to last configuration entry

phCfgEntryNext Pointer to receive handle of next configuration entry

Return Value Returns 1 if a next entry was found

Returns 0 if a next entry was not found

Returns less than 0 on error

The possible configuration errors are:

CFGERROR_BADHANDLE Invalid hCfg handle

CFGERROR_BADPARAM Invalid function parameter

NOTE: The handle *hCfgEntry* is not dereferenced on the event of an error.

Description

This function serves two purposes. First, it dereferences the configuration entry handle supplied in *hCfgEntry*. After this call, the handle is invalid (unless there was more than one reference to it). Secondly, this function returns a referenced configuration entry handle to the next instance (if any) of an entry that matches the Tag and Item values of the supplied entry.

When the parameter *phCfgEntryNext* is NULL, no entry handle is returned, but the function always returns 1 if such an entry was found and 0 when not.

When the *phCfgEntryNext* parameter is not NULL, the function writes a referenced handle to the configuration entry to the location specified by this parameter. It is then the caller's responsibility to dereference this handle when it is finished with it.

Configuration entry handles are dereferenced by the calling one of the following:

CfgEntryDeRef() Stop using the entry

CfgRemoveEntry() Stop using entry and remove it from the configuration

CfgGetNextEntry() Stop using entry and get next entry



CfgLoad Load a Configuration from a Linear Memory Block

Syntax int CfgLoad(HANDLE hCfg, int Size, UINT8 *pData);

Parameters

hCfg Handle to configuration
Size Size of memory block to load
pData Pointer to memory block to load

Return Value Returns the number of bytes loaded, or less than 0 on an error. The possible errors are:

CFGERROR_BADHANDLE Invalid hCfg handle

CFGERROR_BADPARAM Invalid function parameter

Description The configuration system features the ability for the manager to convert a configuration

database to a linear block of memory for storage in non-volatile memory. The

configuration can then be converted back on reboot.

This function converts a linear block of memory to a configuration by loading each configuration entry it finds in the coded data block. Note that CfgLoad() can be used to load entries into a configuration that already has pre-existing entries, but the method of entry is not preserved (see Mode parameter of CfgAddEntry()). To ensure that the resulting configuration exactly matches the one converted with CfgSave(), this function

should only be called on an empty configuration handle.

CfgNew Create a New Configuration

Syntax HANDLE CfgNew();

Parameters None.

Return Value Returns handle to a new configuration or NULL on memory allocation error.

Description Creates a configuration handle that can be used with other configuration functions. The

new handle defaults to the inactive state (see CfgExecute()).



CfgRemoveEntry Remove Configuration Entry from Configuration by Handle

Syntax int CfgRemoveEntry(HANDLE hCfg, HANDLE hCfgEntry);

Parameters

hCfg Handle to configuration

hCfgEntry Configuration entry to remove

Return Value Returns 0 on success or less than 0 on error.

The possible errors are:

CFGERROR_BADHANDLE Invalid hCfg handle

CFGERROR_BADPARAM Invalid function parameter

NOTE: The handle *hCfgEntry* is not dereferenced on the event of an error.

Description This function removes a configuration entry from a configuration.

If the execution state of the configuration is active (see *CfgExecute()*), then the removal of the configuration entry is immediately reflected in the operating state of the system.

This function also performs a single dereference operation on the configuration entry handle, so the handle is invalid after the call (unless there was more than one reference made). Although the entry handle is not freed until all handle references have been removed, it is always removed from the configuration immediately.



CfgSave Save a Configuration to a Linear Memory Block

Syntax int CfgSave(HANDLE hCfg, int *pSize, UINT8 *pData);

Parameters

hCfg Handle to configuration

pSize Pointer to size of memory block pData Pointer to memory block to load

Return Value Returns the number of bytes written, 0 on a size error (value at pSize set to required

size), or less than 0 on an operation error. The possible errors are:

CFGERROR_BADHANDLE Invalid hCfg handle

CFGERROR_BADPARAM Invalid function parameter

Description

One of the features of the configuration system is the ability for the manager to convert a configuration database to a linear block of memory for storage in non-volatile memory. The configuration can then be converted back on reboot.

This function saves the contents of the configuration specified by hCfg into the linear block of memory pointed to by *pData*.

The size of the data buffer is initially pointed to by the pSize parameter. If this size value pointed to by this pointer is zero (pSize cannot itself be NULL), the function does not attempt to save the configuration but rather calculates the size required and writes this value to the location specified by pSize. In fact, any time the value at pSize is less than the size required to store the configuration, the function returns 0 and the value at pSize is set to the size required to store the data.

The *pData* parameter points to the data buffer to receive the configuration information. This pointer can be null if *pSize is zero. Note that the pointer pSize must always be valid.

CfgSetDefault Set Default Configuration Handle

Syntax HANDLE CfgSetDefault(HANDLE hCfg);

Parameters

hCfg Handle to configuration to set as default, or NULL to clear default

Return Value None.

Description

This function sets the current default configuration handle to that specified in *hCfg*. The default handle is used in any function that takes a hCfg parameter, when the specified parameter is NULL. At initialization, there is no default configuration. It must be allocated by *CfgNew()* and then specified via *CfgSetDefault()*. Normally, the default configuration is reserved for system use. The default configuration handle should not be freed until it is cleared by calling *CfgSetDefault(0)*.



CfgSetService Set Service Callback Function for Configuration Tag

int CfgSetService(HANDLE hCfg, uint Tag, int (*pCb) (HANDLE, uint, uint, uint, **Syntax**

HANDLE));

Parameters

hCfg Handle to configuration Tag Tag value to change

pCb Pointer to service callback function

Return Value Returns 0 on success, or less than 0 on error. The possible errors are:

CFGERROR BADHANDLE Invalid *hCfq* handle

CFGERROR_BADPARAM Invalid function parameter

Description

To give the configuration the ability to be active - i.e., to make real-time changes to the system as the configuration changes, the configuration manager must have the ability to make changes to the system. To enable this in a generic fashion, the configuration manager allows for the installation of service callback functions for each configuration tag value.

This function sets the service function for a particular configuration tag. Service function pointers default to NULL, and when they are NULL, no service is performed for the configuration entry (it becomes information data only).

When invoked, the service callback function is passed back information about the affected entry. The callback function is defined as:

int CbSrv(HANDLE hCfg, uint Tag, uint Item, uint Op, HANDLE hCfgEntry),

hCfg HANDLE to Config

Tag Tag value of entry changed Item Item value of entry changed

Op Operation (CFGOP_ADD or CFGOP_REMOVE) Non-Referenced HANDLE to entry added or removed hCfgEntry

The callback should return 1 on success, 0 on pass, and <0 on error.

NOTE: The configuration entry handle passed to the callback function is not referenced, as its scope expires when the callback function returns.



CfgSetExecuteOrder Set the Tag Initialization and Shutdown Order on Execute

Syntax int CfgSetExecuteOrder(HANDLE hCfg, uint Tags, uint *pOpenOrder, uint

*pCloseOrder);

Parameters

hCfg Handle to configuration

Tags Number of tag values in pOpenOrder and pCloseOrder

pOpenOrder Pointer to array of tag values in initialization order

pCloseOrder Pointer to array of tag values in shutdown order

Return Value Returns zero on success, or less than 0 on an operation error. The possible errors are:

CFGERROR_BADHANDLE Invalid hCfg handle

CFGERROR_BADPARAM Invalid function parameter

Description

The configuration API has no knowledge of the configuration database specification. Thus, it has no concept of a priority in loading and unloading configuration entries. The default order for both loading and unloading is by ascending tag value.

You may require that the application specify the exact order in which entries should be initialized (specified in *pOpenOrder*) and shut down (specified in *pCloseOder*). Both arrays must be provided - even if they are identical pointers. The number of elements in each array is specified by the Tags parameter. This must exactly match the maximum number of tags in the system defined by CFGTAG_MAX. An entry of 0 in either order array is used as a placeholder for tags that have not yet been defined.

G.2.3 Configuration Entry API Functions

CfgEntryDeRef Remove a Reference to a Configuration Entry Handle

Syntax int CfgEntryDeRef(HANDLE hCfgEntry);

Parameters

hCfgEntry Handle to configuration entry

Return Value Returns 0 on success, or less than 0 on an operation error. The possible errors are:

CFGERROR BADHANDLE Invalid hCfgEntry handle

Description This function removes a reference to the configuration entry handle supplied in

hCfgEntry. It is called by an application when it wishes to discard a referenced

configuration entry handle. Once this function is called, the handle should no longer be

used.



CfgEntryGetData Get Configuration Entry Data

Syntax int CfgEntryGetData(HANDLE hCfgEntry, int *pSize, UINT8 *pData);

Parameters

hCfgEntry Handle to configuration entry pSize Pointer to size of data buffer Pointer to data buffer

pData

Return Value Returns the number of bytes written, 0 on a size error (value at pSize set to required

size), or less than 0 on an operation error. The possible errors are

CFGERROR BADHANDLE Invalid *hCfqEntry* handle CFGERROR_BADPARAM Invalid function parameter

Description This function acquires the entry data of the configuration entry specified by the entry

handle in hCfgEntry.

The value pointed to by pSize is set to the size of the supplied buffer, or zero to get the required size (the pointer pSize must be valid, but the value at the pointer can be zero). If the value at pSize is zero, or less than the number of bytes required to hold the entry data, this function returns 0, and the number of bytes required to hold the data is stored at pSize.

The pData parameter points to the data buffer to receive the configuration entry data.

This pointer can be null if *pSize is zero.

CfgEntryInfo Get Information on a Configuration Entry

Syntax int CfgEntryInfo(HANDLE hCfgEntry, int *pSize, UINT8 **ppData);

Parameters

hCfgEntry Handle to configuration entry

pSize Location to receive the size of the configuration entry data buffer ppData Location to receive the pointer to the configuration entry data buffer

Return Value Returns 0 on success, or less than 0 on an operation error. The possible errors are:

CFGERROR_BADHANDLE Invalid hCfgEntry handle

This function acquires the size and pointer to a configuration entry's data buffer. Description

> The entry handle is supplied hCfqEntry. A pointer to receive the size of the entry's data buffer is supplied in pSize, and a pointer to receive a pointer to the entry's data buffer is supplied in ppData. Either pointer parameter can be left NULL if the information is not required.

> This function should be used with great care. Direct manipulation of the configuration entry data should only be attempted on informational tags, and only when the caller holds a referenced handle to the configuration entry. This function is used in configuration service callback functions, which are called only when the configuration is

in a protected state.



CfgEntryRef Add a Reference to a Configuration Entry Handle

Syntax int CfgEntryRef(HANDLE hCfgEntry);

Parameters

hCfgEntry Handle to configuration entry

Return Value Returns 0 on success, or less than 0 on an operation error. The possible errors are:

CFGERROR_BADHANDLE Invalid hCfgEntry handle

Description This function adds a reference to the configuration entry handle supplied in *hCfgEntry*. It

is called by an application when it intends to use a configuration entry handle beyond the scope of the function that obtained it from the configuration. This normally occurs when

one user function calls another and passes it a handle.

The handle should be dereferenced when no longer needed. Configuration entry handles

are dereferenced by calling one of the following:

CfgEntryDeRef() Stop using the entry

CfgRemoveEntry() Stop using entry and remove it from the configuration

CfgGetNextEntry() Stop using entry and get next entry

CfgEntrySetData (Re)Set Configuration Entry Data

Syntax int CfgEntrySetData(HANDLE hCfgEntry, int Size, UINT8 *pData);

Parameters

hCfgEntry Handle to configuration entry

Size Size of data buffer pData Pointer to data buffer

Return Value Returns the number of bytes written, 0 on a size error (new size does not match old

size), or less than 0 on an operation error. The possible errors are:

CFGERROR_BADHANDLE Invalid hCfgEntry handle CFGERROR_BADPARAM Invalid function parameter

Description This function replaces the entry data of the configuration entry specified by the entry

handle in hCfgEntry.

The new entry data is pointed to by the *pData* parameter, with a size indicated by *Size*. Note that the new data must be an exact replacement for the old. The size of the new

buffer must exactly match the old size.

This function should be used for configuration entries that are for information purposes only. Note that if a service provider callback is associated with the Tag value of this entry, the processing function is not called as a result of this data update. This function only updates the data stored for this configuration entry.



G.3 Configuration Specification

Specifying all the available configuration options for the stack would require a separate document. This section details that part of the configuration that is relied upon by the Network Control (NC) initialization functions, or the services contained in the NETTOOLS library. The stack itself does not reference the configuration system. It has its own simpler method that is detailed in Appendix A, but it is redundant when using the configuration API. In fact, they conflict, as the Network Control functions assume full control of it.

G.3.1 Organization

As already mentioned, the configuration is arranged as a database with the value Tag as a major key, and the value Item as a minor key. Every major stack configuration component has a major key (Tag) value, including: network services (protocol servers), connected IP networks, gateway routes, connected client entities, global system information, and low-level stack configuration.

Most of these tags require service callback functions to implement the system functionality. For example, when an IP network is added using the CFGTAG_IPNET tag, there must be a function that makes the corresponding system calls that adds the network to the system route table. All these server callback functions are contained in the NETCTRL directory. Although source code to these functions is provided. many of the system calls they make can only be understood by reading the attached appendices.

The tag values currently defined are:

CFGTAG SERVICE Network Service

CFGTAG IPNET IP Network (Address, subnet mask, etc.)

CFGTAG ROUTE **IP Gateway Route**

IP Client (Client IP, Hostname, etc) CFGTAG_CLIENT

CFGTAG ACCT Client user account (name, password, etc.)

CFGTAG_SYSINFO Global System Information

CFGTAG OS Operating System Configuration entry

CFGTAG IP IP Stack Configuration entry

NOTE: The configuration support is currently not available for IPv6 stack management. IPv6 stack management can be done only using the APIs and data structure exported by it. IPv6 stack APIs and data structures are discussed in Appendix F of this document.

G.3.2 Network Service Specification (CFGTAG SERVICE)

The network services tag is perhaps the most time saving feature of the configuration. It allows you to instruct the system of what tasks to execute, and how they should be executed. It is also the most complicated configuration entry.

Network services are identified by a configuration Tag parameter value of CFGTAG_SERVICE.

Note that all these services are obtained directly from the NETTOOLS services API. The configuration system adds a level of abstraction so that a list of services can be added to a configuration, and then the service provider callback functions contained in the Network Control initialization routines can automatically load the services at runtime without having to call the NETTOOLS API directly.



G.3.2.1 Service Types

The type of service is indicated by the value of the *Item* parameter supplied to the *CfgAddEntry()* function. The defined service types include (by *Item*):

CFGITEM_SERVICE_TELNET Telnet Server
CFGITEM_SERVICE_HTTP HTTP Server

CFGITEM_SERVICE_NAT Network Address Translation

System

CFGITEM_SERVICE_DHCPSERVER

CFGITEM_SERVICE_DHCPCLIENT

CFGITEM_SERVICE_DNSSERVER

DHCP Client

DNS Server

G.3.2.2 Common Argument Structure

Each individual service has its own specific configuration instance structure, but they all share a generic argument structure. This is defined as follows:

The individual fields are defined as follows:

uint Item;

This is a copy of the Item value used when the entry is added to the configuration. Its initial value should be NULL, but it is overwritten by the service provider callback. It is used so that the status callback function can be provided with the original Item value.

• HANDLE hService;

This is the handle to the service as returned by the NETTOOLS function corresponding to the type of service requested. Its initial value should be NULL, and it is initialized by the service callback function when the service is started. The value is needed to shut down the service when the configuration is unloaded.

uint Mode;

The mode parameter is a collection of flags representing the desired execution behavior of the service. One or more of the following flags can be set:

CIS_FLG_IFIDXVALID Specifies the IfIdx field is valid.

CIS_FLG_RESOLVEIP Requests that IfIdx be resolved to an IP address before service execution is initiated.

CIS_FLG_CALLBYIP Specifies that the service should be invoked by IP address. (This is the default behavior when IFIDXVALID is not set, but this flag can be set with IFIDXVALID when RESOLVEIP is also

IFIDXVALID is not set, but this flag can be set with IFIDXVALID when RESOLVEIP is also set. If IFIDXVALID is set and this bit is not set, the service is invoked by physical device.)

CIS_FLG_RESTARTIPTERM A service that is dependent on a valid IP address (as determined by the RESOLVEIP flag) is shut down if the IP address becomes invalid. When this flag is set, the service will be

shut down if the IP address becomes invalid. When this flag is set, the service will be restarted when a new address becomes available. Otherwise; the service will not be

restarted.



uint Status;

The status parameter contains the service status as detected by the Net Control service callback function that initiates the service with NETTOOLS. The value of status should be initialized to NULL. Its defined values are:

CIS_SRV_STATUS_DISABLED Service not active (NULL state)

CIS_SRV_STATUS_WAIT

Net Control is waiting on IP resolution to start service

CIS_SRV_STATUS_IPTERM

Service was terminated because it lost its IP address

CIS_SRV_STATUS_FAILED

Service failed to initialize via its NETTOOLS open function

CIS_SRV_STATUS_ENABLED Service enabled and initialized properly

uint ReportCode;

All the services available via the configuration can also be launched directly via a NETTOOLS API. The NETTOOLS service API has a standard service reporting callback function that is mirrored by the configuration system via the Net Control service provider callback. This variable holds the last report code reported by the NETTOOLS service invoked by this configuration entry.

• uint IfIdx;

This is the physical device Index (1 to n) on which the service is to be executed. For example, when launching a DHCP server service, the physical interface is that connected to the home network. For more generic services (like Telnet), the service can be launched by a pre-defined IP address (or INADDR_ANY as a wildcard). When launching by IP address only, this field is left NULL. If the field is valid, the CIS_FLG_IFIDXVALID flag should be set in *Mode*.

• IPN IPAddr;

This is the IP address (in network format) on which to initiate the service. This IP address can specify the wildcard INADDR_ANY, in which case the service will accept connections to any valid IP address on any device. Note that some services (like DHCP server) do not support being launched by an IP address and require a device Index (supplied in *Ifldx*) on which to execute.

 void(*pCbSrv)(uint, uint, uint, HANDLE);

The pCbSrv parameter contains a callback function that is called when the status of the service changes. It can be set to NULL if a callback is not required. The specification of the callback function is as follows:

void StatusCallback(uint Item, uint

Status, uint Code, HANDLE hCfgEntry)

Item value of entry changed

Status New status

Code Report code (if any)

hCfgEntry Non-Referenced HANDLE to entry with status change

Note that the *Status* parameter is the same as the *Status* field described in the CISARGS structure. The Code parameter is that returned by the NETTOOLS service callback, which is a lower-level status callback function used by Net Control.



G.3.2.3 Individual Configuration Entry Instance Structures

The following code defines the instance structures used for each of the defined configuration entries using the configuration service tag. Note that all structures contain the previously mentioned CISARGS structure. Some services require more information and their configuration entry structure contains an additional parameter structure as defined in the service's NETTOOLS API. Others do not require a parameter structure.

```
// Telnet Entry Data
typedef struct _ci_service_telnet {
    CISARGS cisargs; // Common arguments
    NTPARAM_TELNET param; // Telnet parameters
} CI_SERVICE_TELNET;
// HTTP Server Entry Data
typedef struct _ci_service_http {
    CISARGS cisargs; // Common arguments
   NTPARAM_HTTP param; // HTTP parameters
} CI_SERVICE_HTTP;
// NAT Service Entry Data
typedef struct _ci_service_nat {
   CISARGS cisargs; // Common arguments NTPARAM_NAT param; // NAT parameters
} CI_SERVICE_NAT;
// DHCP Server Entry Data
typedef struct _ci_service_dhcps {
    CISARGS cisargs; // Common arguments
   NTPARAM_DHCPS param; // DHCPS parameters
} CI_SERVICE_DHCPS;
// DHCP Client Service
typedef struct _ci_service_dhcpc {
    CISARGS cisargs; // Common arguments
   NTPARAM_DHCP param; // DHCP parameters
} CI_SERVICE_DHCPC;
// DNS Server Service
typedef struct _ci_service_dnss {
   CISARGS cisargs; // Common arguments
} CI_SERVICE_DNSSERVER;
```



G.3.2.4 Specifying Network Services

G.3.2.4.1 Specifying Telnet Service Using the Configuration

The Telnet service can be specified as public because it can connect using any IP address, or an IP address of a specific interface. When accepting connections to any system IP address, the service is specified with the CALLBYIP flag and an IP address of INADDR_ANY. When a private connection is desired, the service is specified by the physical interface on which connections are allowed to occur. Because an IP address is required to initialize the service, the RESOLVEIP flag should also be set in the latter case. For example, the following code specifies that the telnet server should run using the IP address INADDR_ANY.

The above code is all that is required when using the configuration system to invoke this service.

G.3.2.4.2 Specifying DHCP Server Service Using the Configuration

Because the DHCP server service executes on a specific interface, it is never executed based on an IP address. Thus, it cannot be used with the CALLBYIP flag in the standard configuration service structure. However, because an IP host address is required to initialize the service on a specific interface, the RESOLVEIP flag should be set in cases where the IP address is not pre-assigned. For example, the following code specifies that the DHCP server should run on the interface specified by the physical index *dhcpsldx*. Here, the home networks have already been written to the configuration, so the RESOLVEIP flag is not necessary. The address pool being used is already stored in *IPPoolBase* and *PoolSize*. The DHCPS is requested to report the local server address as a DNS server to DHCP clients.

The above code is all that is required when using the configuration system to invoke this service.



G.3.2.4.3 Specifying DHCP Client Service Using the Configuration

Because the DHCP client service executes on a specific interface, it is never executed based on an IP address. Thus, it cannot be used with the CALLBYIP flag in the standard configuration service structure. Also, because the service runs without an IP host address, the RESOLVEIP flag should never be set. For example, the following code specifies that the DHCP client should run on the interface specified by the physical Index *dhcpldx*.

The above code is all that is required when using the configuration system to invoke this service.

G.3.2.4.4 Specifying HTTP Service Using the Configuration

The service can be specified as public as it can connect using any IP address, or an IP address of a specific interface. When accepting connections to any system IP address, the service is specified with the CALLBYIP flag and an IP address of INADDR_ANY. When a private connection is desired, the service is specified by the physical interface on which connections are allowed to occur. Because an IP address is required to initialize the service, the RESOLVEIP flag should also be set in the latter case.

For example, the following code specifies that the HTTP server should run using the IP address INADDR ANY.

The above code is all that is required when using the configuration system to invoke this service.

G.3.2.4.5 Specifying DNS Service Using the Configuration

The service can be specified as public because it can connect using any IP address, or an IP address of a specific interface. When accepting connections to any system IP address, the service is specified with the CALLBYIP flag and an IP address of INADDR_ANY. When a private connection is desired, the service is specified by the physical interface on which connections are allowed to occur. Because an IP address is required to initialize the service, the RESOLVEIP flag should also be set in the latter case.

For example, the following code specifies that the server should run using the IP address INADDR_ANY.

The above code is all that is required when using the configuration system to invoke this service.



G.3.2.4.6 Specifying NAT Service Using the Configuration

Because the NAT service executes on a specified *public* interface, it is never executed based on an IP address. Thus, it cannot be used with the CALLBYIP flag in the standard configuration service structure. In addition, because the public IP host address is required to initialize the service, the RESOLVEIP flag should be set when the IP address is not pre-assigned.

For example, the following code specifies that the NAT service should run on the interface specified by the physical index *natldx*. Here, the DHCP client service is used to obtain the public IP address (the address assigned to *natldx*), so at this point the IP address is unknown. Thus, the RESOLVEIP flag is set in the execution mode parameter. This informs the configuration service manager not to invoke NAT until it has resolved an IP address for the target interface. The RESTART flag is also set to tell the service to restart NAT if a public IP address is lost and regained. In this example, it is assumed that all networks in the 192.168.x.x/255.255.0.0 subnet are part of the NAT group to be translated.

The MTU parameter to the NAT configuration allows the programmer to set a limit on the MTU negotiated during a TCP connection. This prevents TCP packet traffic from being unnecessarily fragmented. For example, when routing between Ethernet and PPPoE over NAT, the MTU should be set to the smaller MTU of the two, which is PPPoE's limit of 1492. In the example below, it is assumed that the system is Ethernet to Ethernet, and thus, it uses the full 1500.

The above code is all that is required when using the configuration system to invoke this service.

To use NAT, it must be configured via the following function. Also, by default, the NAT code is not called by the stack. This increases stack efficiency when NAT is not in use. To enable the NAT module, the *IpNatEnable* element of the stack configuration structure must be set.

Note that when using the NAT service feature in NETTOOLS or when using the configuration system, this low-level configuration is not required.



NatSetConfig Configure the Network Address Translation Module

Syntax void NatSetConfig(IPN IPAddr, IPN IPMask, IPN IPServer, uint MTU);

Parameters

IPAddr IP address of the Virtual Network IPMask IP mask of the Virtual Network

IPServer Physical IP address of the server that will host the NAT translation

MTU IP Packet MTU (1500 for Ethernet, 1492 for PPPoE, etc.)

Description

This function configures NAT with a virtual network and a physical server. Note that both the virtual and physical addresses must also be contained in the stack's route table. NAT should only be used when the stack is acting as a router, and when there are more than one Ethernet devices present.

The MTU parameter must be in the range of 64 to 1500. When set less than 1500, TCP connection negotiation will be altered so that TCP sessions through NAT will be limited to the MTU specified. This prevents unnecessary fragmentation when using NAT over dissimilar packet devices. (Note this MTU is the IP packet MTU, not the TCP MTU.)

G.3.3 IP Network Specification (CFGTAG_IPNET)

The IPNET entry specifies what IP networks are to appear on which physical interfaces. When specifying an IPNET entry to the configuration, the Tag parameter is set to CFGTAG_IPNET, and the Item parameter is set to the Index (1 to n) of the physical interface on which the network is to appear.

The IPNET entry instance structure is defined as follows:

```
// IPNet Instance
typedef struct _ci_ipnet {
    uint NetType; // Network address type flags
    IPN IPAddr; // IP Address
    IPN IPMask; // Subnet Mask
    HANDLE hBind; // Binding handle (initially NULL)
    char Domain[CFG_DOMAIN_MAX]; // IPNet Domain Name
} CI_IPNET;
```

The individual fields are defined as follows:

• uint NetType;

CFG_NETTYPE_DYNAMIC

CFG_NETTYPE_VIRTUAL

CFG_NETTYPE_DHCPS

Address created by DHCP CLIENT

Virtual Network used by DNS resolver

Virtual Net Server reported by DHCP SERVER

This is type of network that appears on the interface. The network type determines how the network is treated by some services like NAT, DHCP, and DNS. The value is a collection of one or more of the following flags.

Most of the flags deal with the virtual network (or home network). If none of these flags are set, the network is a normal physical network. Note that virtual and non-virtual networks should not appear on the same interface. Also, only one network entry on each interface can have any of these flags set, although more than one of these flags can be set in that one entry.

• IPN IPAddr;

This is the IP address of the stack on the designated interface. When the NetType flag DHCPS is set, this address is also the gateway address reported to DHCP clients served by the DHCP server service.

IPN IPMask;

This is the IP network subnet mask.

HANDLE hBind;



This is the stack's internal binding handle for the network. Each connected network is represented as a binding internally to the stack. This is discussed further in the appendices at the end of this document. The value should be initialized to NULL.

• char Domain[CFG DOMAIN MAX];

This is the domain name of the network. It should be a full domain like home1.net, not just home1.

G.3.4 IP Gateway Route Specification (CFGTAG_ROUTE)

The ROUTE entry specifies a route from one network to another via a specified IP gateway. When specifying a ROUTE entry to the configuration, the *Tag* parameter is set to CFGTAG_ROUTE, and the *Item* parameter is not used (set to zero).

The ROUTE entry instance structure is defined as follows:

The individual fields are defined as follows:

• IPN IPDestAddr;

This is the IP base address of the IP network of the network that is made accessible via the IP gateway. This value should be pre-masked with the IPDestMask so that:

(IPDestAddr & IPDestMask) = IPDestMask

This is used as a sanity check by the system. For a default route, the value is zero.

IPN IPDestMask;

This is the mask of the IP network accessible by the IP gateway. For a host route, the value is 0xFFFFFFF, while for a default route, the value is zero.

IPN IPGateAddr;

This the IP address of the gateway through which the specified IP network is accessible. It must be an IP address that is available on a locally connected network, i.e., one gateway cannot point to another.

• HANDLE hRoute;

This is a handle to the route created by this configuration entry. All routes are represented as route handles internally to the stack. This is discussed further in the appendices at the end of this document. The value should be initialized to NULL.

G.3.5 Client Record Specification (CFGTAG_CLIENT)

The CLIENT entry specifies a record of a client that appears on the indicated physical interface. When specifying a CLIENT entry to the configuration, the *Tag* parameter is set to CFGTAG_CLIENT, and the *Item* parameter is set to the index (1 to n) of the physical interface on which the client appears.

Client records exist for two purposes:

- 1. They are used to resolve DNS queries on virtual networks.
- 2. They are used by the DHCP server service to track DHCP clients on the serviced virtual network.

Client records are created automatically in some DHCP server configurations (when using an address pool), but they can also be added manually. This allows an application to build a pre-defined fixed list of clients and their designated IP addresses on a virtual (home) network.

The CLIENT entry instance structure is defined as follows:



```
char Hostname[CFG_HOSTNAME_MAX]; // Client Hostname
UINT32 TimeStatus; // Time of last status change
UINT32 TimeExpire; // Expiration Time from TimeStatus
} CI_CLIENT;
```

The individual fields are defined as follows:

• uint ClientType;

This is type of client record. There are only two types - those created by DHCP server from an address pool, and those created manually by an application.

```
CFG_CLIENTTYPE_DYNAMIC Entry created via DHCPS
CFG_CLIENTTYPE_STATIC Entry created manually
```

• uint Status;

This is status of the client record. It is used by the DHCP server to track the state of the client and its lease to its IP address. The status can also be NULL for STATIC entries.

```
CFG_CLIENTSTATUS_PENDING

CFG_CLIENTSTATUS_VALID

CFG_CLIENTSTATUS_STATIC

CFG_CLIENTSTATUS_INVALID

Supplied via DHCP OFFER

Validated by DHCP REQUEST

Reported via DHCP INFORM or non-DHCP application

Invalidated by DHCP DECLINE
```

• IPN IPAddr;

This is IP address of the client.

char MacAddr[6];

This is physical Ethernet address of the client.

• char

```
Hostname[CFG HOSTNAME MAX];
```

This is the hostname of the client. It is recorded by the DHCP server service, even if the record is STATIC. Thus, when running DHCP server, even with a fixed client list, DHCP clients can specify their own host names, and these names will be available to the DNS resolver, i.e., DNS server and DNS client.

UINT32 TimeStatus;

This is the last time that the *Status* parameter was validated. It is thus the start time of a DHCP client lease.

UINT32 TimeExpire;

This is the total time in seconds of a DHCP client lease reported by the DHCP server to its clients. When using an address pool for the DHCP server, the server chooses this value.

G.3.6 Client User Account (CFGTAG_ACCT)

The ACCT entry specifies an account record of a client that has access to the system. When specifying a ACCT entry to the configuration, the Tag parameter is set to CFGTAG_ACCT, and the Item parameter is set to the account type. Currently, the NDK has only one generic account type. Both PPP authentication and EFS authorization realms use this type. Valid types values are:

```
CFGITEM_ACCT_SYSTEM System user account (PPP and EFS)
CFGITEM_ACCT_PPP PP user account (SYSTEM)
CFGITEM_ACCT_REALM EFS Authorization Realm user account (SYSTEM)
```

The ACCT entry instance structure is defined as follows:



The individual fields are defined as follows:

• uint Flags;

The flags determine the access granted by channel or group. The channels or groups that any given PPP server will allow is determined when the PPP server is invoked. The same is true of the HTTP authentication realms. A single client account can be a member of one or more groups, therefore, one or more of the following flags can be set:

CFG_ACCTFLG_CH1	Allow access to channel/group/realm 1
CFG_ACCTFLG_CH2	Allow access to channel/group/realm 2
CFG_ACCTFLG_CH3	Allow access to channel/group/realm 3
CFG_ACCTFLG_CH4	Allow access to channel/group/realm 4

char

```
Username[CFG ACCTSTR MAX];
```

This is the username of the client.

char

```
Password[CFG_ACCTSTR_MAX];
```

This is the password corresponding to the supplied client username.

G.3.7 System Information Specification (CFGTAG_SYSINFO)

The SYSINFO entry contains various types of global system information. There is no service callback function associated with these entries, as they are static information only. When specifying a SYSINFO entry to the configuration, the *Tag* parameter is set to CFGTAG_SYSINFO, and the *Item* parameter is set to the system information item in question.

Note that the first 256 values for *Item* are reserved for items that exactly match the corresponding DHCP protocol information tag value. For example:

```
#define CFGITEM_DHCP_DOMAINNAMESERVER 6 // Stack's DNS servers
#define CFGITEM_DHCP_HOSTNAME 12 // Stack's host name
```

These values are read by various network services, and are written in one of two ways.

First, when the standard DHCP client is executing, it will take full control over the first 256 *Item* values. It fills in the entries when it obtains its address lease, and purges them when the lease expires. There is a set of default entries that the DHCP client will always request. Additional information requests can be made by configuring the DHCP client, and the resulting replies will be added to the configuration.

Second, when there is no DHCP client service, the network application must manually write values to the configuration for the *Item* values it views as important. A minimum configuration would include hostname, domain name, and a list of domain name servers. Note that multiple IP addresses should be stored as multiple instances of the same Item, not concatenated together with a longer byte length.

G.3.8 Extended System Information Tags

The following tag values are reserved for NDK and services configuration (see Appendix and Section E.3 for more information on PPP and HTTP realms):

CFGITEM_SYSINFO_REALM1
CFGITEM_SYSINFO_REALM2
CFGITEM_SYSINFO_REALM3
CFGITEM_SYSINFO_REALM4
CFGITEM_SYSINFO_REALMPPP
CFGITEM_SYSINFO_EVALCALLBACK

Realm Name 1 (maximum 31 chars) Realm Name 2 (maximum 31 chars)

Realm Name 3 (maximum 31 chars)
Realm Name 4 (maximum 31 chars)

Server Name for PPP (maximum 31 chars)

Callback function registered by application. It is used by the Evaluation version of the NDK to notify the application five minutes before the expiration of the 24-hour evaluation period.



G.3.9 OS / IP Stack Configuration Item Specification (CFGTAG OS, CFGTAG IP)

The OS and IP tags specify entries that alter various configuration options that can be adjusted in the operating system and low-level stack operation. When specifying an entry to the configuration, the *Tag* parameter is set to CFGTAG_OS or CFGTAG_IP, and the *Item* parameter is set to the configuration item to set (these are listed below).

Creating a configuration entry results in an alteration of the system's internal configuration structures, but because these entries are also part of the configuration object (hCfg), they can be stored off and recorded as part of the CfgSave() functionality. Thus, using the configuration API has a significant advantage over modifying the internal structures manually.

Removing an entry restores the default value to the internal stack configuration. Entries that are not present cannot be read, and an error return on read implies the entry is in its default state.

The following is the list of configuration items. All items are of type int or uint. They correspond exactly to the internal system configuration structures. For more information on these fields, see the internal configuration discussion in both the Section 2.1.1 section earlier in this document, and the Configuring the Stack section in the attached appendix Section A.13.

When creating a configuration entry for one of these tags, the entry should be specified as unique. For example, to enable routing in the IP stack that code would be as follows:

The following item values correspond directly to the OS and IP Stack configuration structures <code>_oscfg</code> and <code>_ipcfg</code>

For more information on these structures, see Section 2.1.1 and Section A.13.1.

When *Tag* is CFGTAG_OS, the value of *Item* can be one of the following:

CFGITEM_OS_DBGPRINTLEVEL	Debug message print threshold
CFGITEM_OS_DBGABORTLEVEL	Debug message abort threshold
CFGITEM_OS_TASKPRILOW	Lowest priority for stack task
CFGITEM_OS_TASKPRINORM	Normal priority for stack task
CFGITEM_OS_TASKPRIHIGH	Highest priority for stack task
CFGITEM_OS_TASKPRIKERN	Kernel-level priority (highest)
CFGITEM_OS_TASKSTKLOW	Minimum stack size
CFGITEM_OS_TASKSTKNORM	Normal stack size
CFGITEM_OS_TASKSTKHIGH	Stack size for high volume tasks

When *Tag* is CFGTAG_IP, the value of *Item* can be one of the following:

CFGITEM_IP_ICMPDOREDIRECT	Add route on ICMP redirect (1 = Yes)
CFGITEM_IP_ICMPTTL	TTL for ICMP messages (RFC1700 says 64)
CFGITEM_IP_ICMPTTLECHO	TTL for ICMP echo (RFC1700 says 64)
CFGITEM_IP_IPINDEXSTART	IP Protocol Start Index
CFGITEM_IP_IPFORWARDING	IP Forwarding Enable (1 = Yes)
CFGITEM_IP_IPNATENABLE	IP NAT Translation Enable (1 = Yes)
CFGITEM_IP_IPREASMMAXTIME	Maximum IP reassembly time in seconds
CFGITEM_IP_IPREASMMAXSIZE	Maximum IP reassembly packet size
CFGITEM_IP_DIRECTEDBCAST	Support directed BCast IP addresses (1 = Yes)
CFGITEM_IP_TCPREASMMAXPKT	Maximum out of order packets held by TCP socket
CFGITEM_IP_RTCENABLEDEBUG	Enable route control dbg messages (1 = Yes)
CFGITEM_IP_RTCADVTIME	Time in sec to send Router Adv. (0 = don't)



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CFGITEM_IP_RTCADVLIFE	Lifetime of route in RtAdv if active
CFGITEM_IP_RTCADVPREF	Preference of route in RtAdv if active
CFGITEM_IP_RTARPDOWNTIME	Time 5 failed ARPs keeps route down
CFGITEM_IP_RTKEEPALIVETIME	Timeout of validated route in seconds
CFGITEM_IP_RTARPINACTIVITY	Time in seconds beyond which an unused route is considered <i>inactive</i> and is cleaned up.
CFGITEM_IP_RTCLONETIMEOUT	Timeout of newly cloned route in seconds
CFGITEM_IP_RTDEFAULTMTU	MTU for internal routes
CFGITEM_IP_RTGARP	Set processing policy of received gratuitous ARP packets
CFGITEM_IP_SOCKTTLDEFAULT	Default IP TTL for Sockets
CFGITEM_IP_SOCKTOSDEFAULT	Default IP TOS for Sockets
CFGITEM_IP_SOCKMAXCONNECT	Maximum connections on listening socket
CFGITEM_IP_SOCKTIMECONNECT	Maximum time for connect socket
CFGITEM_IP_SOCKTIMEIO	Default Maximum time for socket send/rcv
CFGITEM_IP_SOCKTCPTXBUF	TCP Transmit allocated buffer size
CFGITEM_IP_SOCKTCPRXBUF	TCP Receive allocated buffer size (copy mode)
CFGITEM_IP_SOCKTCPRXLIMIT	TCP Receive limit (non-copy mode)
CFGITEM_IP_SOCKUDPRXLIMIT	UDP/RAW Receive limit
CFGITEM_IP_SOCKMINTX	Default min Tx space for able to write
CFGITEM_IP_SOCKMINRX	Default min Rx data for able to read
CFGITEM_IP_PIPETIMEIO	Maximum time for pipe send/rcv call
CFGITEM_IP_PIPEBUFMAX	Pipe internal buffer size
CFGITEM_IP_PIPEMINTX	Pipe min Tx space for able to write
CFGITEM_IP_PIPEMINRX	Pipe min Rx data for able to read
CFGITEM_IP_TCPKEEPIDLE	Idle time before 1st TCP keep probe
CFGITEM_IP_TCPKEEPINTVL	TCP keep probe interval
CFGITEM_IP_TCPKEEPMAXIDLE	Maximum TCP keep probing time before drop
CFGITEM_IP_ICMPDONTREPLYBC	Do not reply to ICMP Echo Request packets sent to broadcast/directed broadcast IP addresses (1 = Yes)
CFGITEM_IP_ICMPDONTREPLYMC	Do not reply to ICMP Echo Request packets sent to multicast IP addresses (1 = Yes)
CFGITEM_IP_ICMPDONTREPLYEC	Do not reply to any ICMP Echo Request packet (0=Reply)
CFGITEM_IP_UDPSENDICMPUNREACH	Reply with ICMP Unreachable packet to connection attempts to a not listened UDP port (1=Reply)
CFGITEM_IP_TCPSENDRST	Reply with RST packet to connection attempts to a not listened TCP port (1=Reply)
CFGITEM_IP_SOCKRAWETHRXLIMIT	Raw Ethernet socket receive limit
CFGITEM_IP_MAX	Maximum CFGTAG_STACK item



Initialization Procedure www.ti.com

G.4 Initialization Procedure

For applications that do not use XGCONF configuration, the basic process of stack initialization is as follows:

- 1. Initialize the operating system environment with the initialization function *NC_SystemOpen(Priority, OpMode)*. This function must always be called first before any other NDK related function. The calling parameters determine the priority and operating mode of the network event scheduler.
- 2. Create a new configuration via CfgNew().
- 3. Build the new configuration via configuration API calls, or load a previous configuration from non-volatile memory using *CfgLoad()*.
- 4. Boot the stack with the configuration by calling *NC_NetStart(hCfg, pfnStart, pfnStop, pfnNetIP)* with a handle to the configuration, plus pointers to three user supplied callback functions for start, stop, and IP address change operations. The *NC_NetStart()* function does not return until the stack session has terminated. The configuration handle *hCfg* becomes the default configuration for the system.
- 5. After some preliminary initialization, the NC_NetStart() function creates a new thread that calls the user supplied callback function for the start operation. At this point, the callback function creates task threads for its networking requirements. This start function does not need to return immediately, but should return at some point i.e., the callback function should not take permanent control of the calling thread. If system shutdown is initiated before the start function returns, some resources may not be freed.
- 6. Under normal operation, the network does not shut down until the NC_NetStop() function is called. At some point after a call to NC_NetStop(), the original NC_NetStart() thread calls the user supplied callback function for the stop operation. In this callback function, the application shuts down any operation it initiated in the start callback function and frees any allocated resources. After the stop callback function returns, NDK functionality is no longer available.
- 7. The original call to NC_NetStart() returns with the return value as set by the return parameter passed in the call to NC_NetStop(). The application can immediately reboot the NDK by calling NC_NetStart() again, with or without reloading a new configuration. This is useful for a reboot command.

When the system is ready for a final shutdown, the following actions are performed:

- 1. When NC_NetStart() returns and the session is over, call the CfgFree() function to free the configuration handle created with CfgNew().
- 2. After all resources have been freed, call the NC_SystemClose() function to complete the system shutdown.



Revision History

Table H-1 lists the changes made since the previous version of this document.

Table H-1. Document Revision History

Reference	Additions/Modifications/Deletions
	Change Summary for NDK 2.1
Section 4.1	New graphical configuration support for NDK modules has been added through the XGCONF configuration tool in CCS. Many settings that had to be made in C code can now be made with this tool.
Section 4.2.1	If you use XGCONF for configuration, the initialization process is automated and you can configure hook functions to be executed at various defined points.
Related Documentation From Texas Instruments	In addition to C6000 support, the NDK now supports the Cortex-A8 and ARM9 in ELF format.
Appendix G	The legacy configuration documentation has been moved to an appendix.
	DSP/BIOS 5.x is no longer supported; use the NDK with SYS/BIOS 6.30+.
	Changes in Earlier Versions
Title Page	Changed 1.94 to 2.00
How to Use This Manual	Added text
Related Documentation From Texas Instruments	Added reference
Section 1.1.1	Added text
Section 2.6.3	Added new sections
Section 3.4.2	Added new section "Raw Ethernet Sockets Programming Interface" - following sections renumbered accordingly
Section G.3.1	Added noter
Section G.3.9	Added/deleted text
Chapter 5	Add text
Section A.5	Added new section "Jumbo Packet Buffer Manager (Jumbo PBM) Object " - following sections renumbered accordingly
Section A.17	Added new section "Raw Ethernet Module"- following sections renumbered accordingly
Section A.7.1	Added new section "ARP Revalidation Logic"- following sections renumbered accordingly
Section A.7.3	Added new section "Information Structure"- following sections renumbered accordingly
Section A.7.5	Added new modules
Section A.13.1	Added/deleted text
Section A.18	Added text